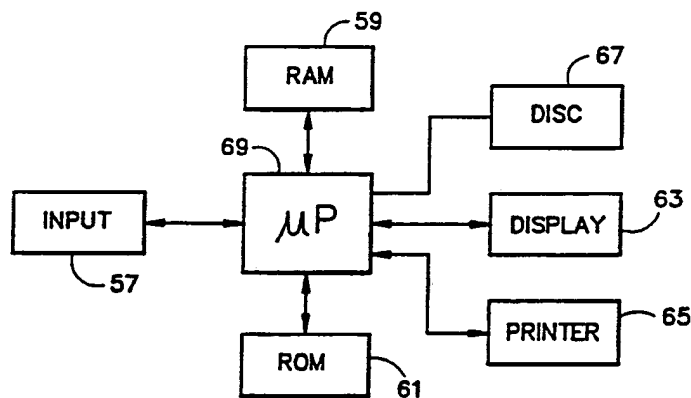




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(54) Title: SYSTEM AND METHOD FOR DETERMINING THREE-DIMENSIONAL STRUCTURES OF PROTEINS**(57) Abstract**

The system comprises an input means (57) such as a keyboard for specifying (entering) selected amino acid sequences and other data such as temperature and fold preferences, a RAM (random access memory) (59) for storing such data, a ROM (read-only memory) (61) with a stored program, a CRT (cathode ray tube) (63) display unit and/or printer (65) an optional auxiliary disc storage device (67) for storage of relevant data bases, and a microprocessor (69) for processing the entered data, for simulating, under control of the stored program, the folding of the protein from its unfolded state to its folded (tertiary) state, and for displaying via the display unit (or printer) tertiary conformations of the protein in three dimensions.

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SYSTEM AND METHOD FOR DETERMINING
THREE-DIMENSIONAL STRUCTURES OF PROTEINS

5 Background of the Invention

 This invention relates to modeling systems generally, and particularly to computer-based - simulation systems used in determining three-dimensional structures (tertiary native
10 conformations) of globular protein molecules.

 The value of determining structure or conformation of proteins is well known. For example, in 1961 a Nobel Prize was awarded to Max Perutz for his work in determining the structure of the
15 hemoglobin protein in blood. From this discovery, we now understand more about sickle cell hemoglobin and how drugs can be designed to treat patients with this disorder.

 The prediction of antigenic determinants
20 also is based on the prediction of protein tertiary structure. One such scientific work is reported, for example, by Hopp and Woods in "Prediction of protein antigenic determinants from amino acid sequences", *Proceedings of the National Academy of Science USA*
25 78, pp. 3824-3828 (1981), and in "A Computer Program for Predicting Protein Antigenic Determinants", *Molecular Immunology* Vol. 20, No. 4, pp. 483-489 (1983).

 The structure (native conformation) of the
30 protein, particularly the conformation of the outer sites or sidechains (which are linked to the backbone and inner structures of the protein) often determines the capacity of the protein to interact with other proteins. One factor which directly influences
35 conformation is protein folding. Deciphering the

rules through which the building blocks (amino acid sequences) of the protein affect folding promises significant improvements in the design of proteins, many with a host of new catalytic functions useful, for example, in the chemical, food processing, pharmaceutical, and other industries.

As a tool, computer systems are sometimes used to combine and display protein structures. One such system, used to convert two polypeptide chains to a single polypeptide chain, is described for example in U.S. Patent No. 4,704,692, entitled "Computer Based System and Method for Determining and Displaying Possible Chemical Structures for Converting Double- or Multiple-Chain Polypeptides to Single-Chain Polypeptides", issued November 3, 1987 to inventor Robert C. Ladner. Computer systems have also been used to investigate protein structures and predict protein folding. A few of such uses have been reported in *Protein Folding* by N. Go et al., pp. 167-81, ed. by N. Jaenicke, Amsterdam, Holland (1980); *Biopolymers* by S. Miyazawa et al., 21:1333-63, (1982); and *Journal of Molecular Biology*, by M. Levitt, 104:59-107 (1976).

These systems often (a) cannot process a full sequence of amino acid residues of a protein or protein segment (i.e., cannot process or otherwise represent the interactions of all the residues of the protein or protein segment; this task often becomes intractable, the system generally becomes unduly burdened by the many degrees of freedom of the residues), (b) cannot complete the folding process (because of inability of the system to recognize false, local energy - minima conditions), (c) cannot represent tertiary conformations in three dimensions, (d) cannot represent interactions between sidechains,

(e) do not display the pathway taken by a protein in folding, or (f) do not permit free (unconstrained) interactions between residues for more realistic simulation of real proteins.

5 What is needed and would be useful, therefore, is a computer-based system that would eliminate the above-mentioned deficiencies, and provide a faster way of determining protein structures, thereby increasing the productivity of
10 many scientists and encouraging the undertaking of many more needed investigations, including investigation of structures of protein sequences obtained from mapping of the human genome.

15 Summary of the Invention

 Accordingly, an improved computer-based system is provided that is capable of processing a full sequence of amino acid residues of a protein (e.g., plastocyanin), representing free
20 (unconstrained) interactions between residues and between sidechains, tracking an entire folding operation (pathway) from the protein's unfolded (denatured) state to its fully folded (native) state, and displaying tertiary conformations of the protein
25 in three dimensions.

 The system comprises an input means such as a keyboard for specifying (entering) selected amino acid sequences and other data such as temperature and fold preferences, a RAM (random access memory) for
30 storing such data, a ROM (read-only memory) with a stored program, a CRT (cathode ray tube) display unit and/or printer, an optional auxiliary disc storage device for storage of relevant data bases, and a microprocessor for processing the entered data, for
35 simulating, under control of the stored program, the

folding of the protein from its unfolded state to its folded (tertiary) state, and for displaying via the display unit (or printer) tertiary conformations of the protein in three dimensions.

5 A novel lattice is employed for representing (framing) the various conformations of the protein as it folds from an unfolded sequence of amino acid residues to a tertiary structure. The model comprises a cubic arrangement of 24-nearest-neighbor
10 lattice sites, with adjacent sites located a unit distance from each other, and adjacent α -carbons located a distance of $\sqrt{5}$ units from each other. The α -carbons represent a chain or backbone of the protein. Each α -carbon is shown to occupy a central
15 cubic lattice site plus six adjacent cubic lattice sites defining a surface of interaction (e.g., an area or volume having a surface of finite size). Each sidechain is represented as being embedded in the lattice and occupying a selected number (four) of
20 lattice sites located relative to the central site, the number of sites occupied by the sidechain being proportional to the number of sites defining the surface of interaction.

 In response to specification of temperature
25 and the amino acid sequence of the protein, the system determines the tertiary conformation of the protein using Monte Carlo dynamics with an asymmetric Metropolis sampling criterion. The system, (a) generates a three-dimensional representation of an
30 unfolded conformation consisting of an α -carbon backbone and sidechains, (b) produces (in accordance with local conformational preferences of the residues, and the lowest total energy of interactions between close sidechain pairs which satisfies the
35 criterion) successive likely conformations at the

temperature, according to the total energy of each conformation, (c) selects from the successive likely conformations the lowest total-free-energy tertiary conformation which satisfies said criterion, and (d) determines the coordinates of the selected tertiary conformation for display. In producing successive likely conformations, the system modifies each conformation by moving randomly selected residues (beads) and inter-residue bond vectors to different selected lattice sites by performing various type moves (single-bead jump-type moves, two-bead end-flip moves, chain-rotation type moves, and translation wave-type moves).

By the method employed by this system, simulation of protein folding and prediction of tertiary structure are not only performed with greater success and accomplished faster than by many existing methods, but the simulation itself becomes more manageable (tractable).

20

Brief Description of the Drawings

Fig. 1 is a diagrammatic illustration of a globular protein in its native folded conformation.

Fig. 2 is a diagrammatic illustration of a full sequence of amino acid residues of which the protein represented in Fig. 1 is comprised.

Fig. 3 is a block diagram of the system of the present invention.

Fig. 4 is a block diagram showing a perspective view of a cubic lattice model employed in the system of Fig. 3.

Fig. 5 is a block diagram showing a segment of a protein model comprising an α -carbon and sidechain in a cubic lattice of the type shown in Fig. 4.

Fig. 6 is a diagrammatic illustration of an α -carbon backbone of a protein segment.

Fig. 7 is a diagrammatic illustration of an α -carbon of the protein backbone segment shown in Fig. 6.

Figs. 8A-8C are diagrammatic illustrations of selected simple arrangements of an α -carbon backbone and associated sidechains.

Fig. 9 is a diagrammatic illustration of a jump-type move made by a randomly selected residue (bead) within the lattice of Fig. 4, effecting a change in conformation of the protein model.

Fig. 10 is a diagrammatic illustration of a rotation-type move made by a pair of randomly selected bond vectors within the lattice of Fig. 4, effecting a change in conformation of the protein model.

Fig. 11 is a diagrammatic illustration of a translation-type (wave-type) move made by a U-shaped segment within the lattice of Fig. 4, effecting a change in conformation of the protein model.

Figs. 12A-12D are diagrammatic illustrations of the folding of a selected segment of a protein to a β -barrel conformation.

Figs. 13A-13C are graphs showing an average number of native contact pairs between sidechains versus time.

Figs. 14A and 14B are graphical illustrations of a folding pathway defined by a sequence as it folds from an unfolded state to a folded (native) state.

Figs. 15A-15F are block diagrams (flow charts) showing a method employed by the system of Fig. 3 in simulating protein folding.

Fig. 16 is a block diagram showing an

alternate embodiment of the processor of Fig. 15.

Detailed Description of the Invention

5 A simplified representation of a globular protein (e.g., plastocyanin) in its native (natural, folded) form is shown in Figure 1. A simplified representation of a full sequence of amino acid residues of which the protein is comprised is shown in Figure 2. The protein becomes unfolded
10 (denatured) when it is heated to an elevated temperature, and it refolds to its native form when the temperature is lowered to a selected level. Temperature may be specified in any unit (whether fahrenheit, centigrade, or Kelvin) and at any level
15 or value (whether in or outside the transition range of the protein) as explained hereinafter. Generally, depending on the native biological conditions of the particular protein molecule being investigated, the temperatures that are specified are those in and
20 bordering the transition region of the protein (typically, in and above 35°C-45°C).

Given a sequence of amino acid residues of a known or unknown protein, it would be useful, for example in the designing of a drug, to know to what
25 protein form (structure, conformation) the sequence would fold if selected residues were changed (modified).

To determine the probable tertiary structure (three-dimensional conformation) to which a given
30 sequence or modified sequence would fold, a simulation of the folding operation could be performed on a computer system of the type shown in Fig. 3. The system uses a "210" lattice model, as shown in Fig. 4. The system is described in detail
35 hereinafter. Prior to description of the system,

however, to facilitate understanding of the invention, other aspects of the invention (such as lattice arrangement, types of movement of segments (residues) of protein within the lattice, orientational states of a segment, and inter-residue interaction) are described below.

Lattice Model, and Positioning of Protein Conformation

Referring now to Fig. 5, a section or segment 11 of a full sequence (e.g., a sequence of a protein much like that depicted in Fig. 2) is shown in stick form (without associated residues or atomic structure). The section 11 includes an α -carbon segment 13 and a sidechain (β -carbon) segment 15 representative of each amino acid residue of the protein.

The protein segments may be viewed as embodied within a cubic reference framework or lattice model (Fig. 4), constructed from vectors of the type (1,0,0), (0,1,0), (0,0,1), the distance between any two adjacent points being unity. The α -carbon atoms 13 when linked as shown in Fig. 6 form the backbone 14 of the protein. As shown in Figs. 4 and 7, each α -carbon 13 may be viewed as occupying a central cubic site 17 plus six adjacent cubic sites 18-23, defining a finite surface of interaction. Adjacent α -carbon centers may be viewed as linked by a 210-type lattice vector 25, as shown in Fig. 4.

The backbone 14 (Fig. 6) represents a structure of finite thickness about which a somewhat inflexible, hard core envelope of a chain of residues develop. The conformation of the backbone at the i^{th} α -carbon is specified in terms of r_{01}^2 , the square of the distance between adjacent α -carbons ($i-1$ and

α -carbons, and θ represents a bond angle that one of the α -carbons make with respect to the other, as shown in Fig. 6. In model units, the distance
5 between consecutive α -carbons equals $\sqrt{5}$ units. Selected values of r^2_θ are 6, 8, 10, 12, 14, 16, and 18, expressed in model units, indicating various accessible bond angle states. These values represent internal orientational states corresponding to actual
10 (known) physical conformations.

As shown in Figs. 5 and 8, each α -carbon has attached to it a sidechain 15, constructed for example in a helix conformation 27, or in a β -strand conformation 29. From the central vertex portion 31
15 of the α -carbon, the sidechain 15 is formed, comprising four lattice vector points (1,1,0), (1,1,0), (1,1,0), and (1,1,1) 33. Three points represent fcc-type (face center cubic) lattice vectors, i.e., vectors of the type $(\pm 1, \pm 1, 0)$. The
20 fourth point represents a diamond lattice vector of the type $(\pm 1, \pm 1, \pm 1)$. This latter vector serves as the center of hydrophobic or hydrophilic interactions (explained hereinafter). The orientation of the sidechain depends on the backbone conformation, i.e.,
25 depends on r^2_θ . At least two of the three fcc vectors comprising the sidechain are shown in an L-conformation (i.e., with left-handed chirality). The diamond lattice-type vector is always shown in the L-conformation. (For a more detailed description of
30 lattice rules which should be followed when constructing conformations, refer to Appendix A.) For the calculations described hereinafter, either the residues are glycine, in which case there is no sidechain, or the residues have a sidechain of
35 uniform size.

Interactions Between Residues

The following is a description of how the 210 lattice model (Fig. 4) is used to denote interactions between elements (residues) of a given backbone conformation, and to denote the energy of such interactions. To specify the conformation of the backbone of a chain, composed of n residues on an α -carbon representation, $n-2$ bond angles (θ) and $n-3$ torsional angles (ϕ) must be specified. To determine the conformation of the first and last residues, a virtual residue is appended to each end of the chain. These virtual residues are represented as inert. They occupy space but are devoid of sidechains. Thus, with the addition of the two fictitious (virtual) residues, n bond angles and $n-1$ torsional angles can now be used to specify the backbone conformation of the chain. (For convenience in denoting segments, the residues of the chain may be numbered from 1 to n .)

With respect to expressing (representing) a preference for a given conformation, any intrinsic preference of the protein model for a particular conformation may be represented by the individual preferences of the respective residues for the various bond angle states. In the description that follows, the term local conformational preferences shall mean the relative preferences which each local group of residues (i.e., a selected residue plus two flanking (adjacent) residues on either side of the selected residue) exhibit for the different conformational states. As indicated previously, these states are represented by the value r^2_{θ} of the lattice model. Since for every residue i there are seven distinct values of r^2_{θ} , corresponding to 18 distinct local conformational states, the local

energetic preference (denoted as parameter $\epsilon_\theta(r_{\theta i}^2)$) for each of the states (r_θ^2 values) must be specified. If it is desired to reduce the number of such adjustable parameters (that is, parameters requiring specification), the conformations (except conformations where $\epsilon_\theta(r_{\theta i}^2)=0$) may be made isoenergetic and assigned the value $\epsilon_\theta > 0$.

In addition to bond angle, the torsional (dihedral angle) potential of a residue (i.e., its tendency to undergo an angle of rotation or twist) must be specified. The torsional potential associated with the i^{th} residue is specified in terms of residues (i-1) through (i+2). Actually, a dihedral angle potential must be specified in the model for all residues from residue 2 (corresponding to real residue 1) to residue n-2 (corresponding to real residue n-1). Because the model is confined to a lattice, it is convenient to describe the torsional potential associated with the i^{th} residue in terms of: (a) r_θ^2 , $r_{\theta i+1}^2$, the bond angle states i and i+1, (b) r_ϕ^2 , the square of the distance between α -carbons i-1 and i+2, and (c) the handedness of the dihedral angle, $X = +1$ for right-handed chirality (R) or $X = -1$ for left-handed chirality (L). For example, a planar state having $\phi = 0$ is specified by (16, 16, 37, -1). That is, the square of the distance between α -carbons i-1 and i+1 is 16, between α -carbons i and i+2 is 16, and between α -carbons i-1 and i+2 is 37. (For definiteness in the calculation, a dihedral angle of 0 is taken to be left-handed. This conformation could also be specified by the vectors b_1 , b_{i+1} , b_{i+2} as shown in Figure 8). As many as 324 rotational states exist for each internal bond. These rotational states are all assigned a relative energy value $\epsilon_\phi(r_{\theta i}^2, r_{\theta i+1}^2, r_{\phi i}^2 X)$. Generally, all

such rotational states are statistically weighted. Where the majority of the conformations are taken to be isoenergetic (with a small bias toward a small subset of conformations that are native), the short and intermediate range energetic preferences may be represented as $\epsilon(r_{\theta,1}^2, r_{\theta,1+1}^2, r_{\theta,1}^2)$.

The seven lattice sites that define the α -carbon (Fig. 7) and the four lattice sites (Fig. 5) that define the surface 24 of the sidechain interact repulsively (i.e., with strong, hard core repulsion) with all the other α -carbons and their respective sidechains. In other words, no more than one sidechain or α -carbon can simultaneously occupy a given lattice site. (This is generally referred to as the excluded volume criterion.) Such a model may be viewed as having a backbone of finite thickness. In addition to the hard core repulsion, described above, there is a weak (soft core) repulsive interaction between non-bonded α -carbon backbone centers located within a distance of $\sqrt{5}$ model units of each other. If r_{kl} represents the distance between the k^{th} and l^{th} such centers, then the soft core repulsive energy ϵ_{rep} between the pair may be expressed as:

$$\epsilon_{\text{rep}} = \begin{bmatrix} \infty & ; & r_{kl}^2 = 0,1,2,4 \\ \epsilon_{\text{rep}} & ; & r_{kl}^2 = 3 \\ 3\epsilon_{\text{rep}} & ; & r_{kl}^2 = 5 \\ 0 & ; & \text{otherwise} \end{bmatrix}$$

(ϵ_{rep} typically takes on the value of 6 in the calculations that follow.)

Following description of the lattice, bond angle, bond angle states, and torsional angles, a description of tertiary interactions between the residues in a three-dimensional setting is presented

next. To represent the effect of hydrogen bonding and dipolar-type interactions, a cooperative interaction energy parameter E_c is introduced which allows for secondary structure stabilization when any part of the α -carbon hard core envelope of the 1th residue is at a distance of 3 units from the α -carbon center of the k^{th} residue.

If a pseudodot product between two vectors is defined as:

$$\text{dot}(b_k, b_l) = \begin{cases} 1 & ; \text{ if } b_k = \pm b_l \\ 0 & ; \text{ otherwise } \end{cases}$$

then, the cooperative interaction energy ϵ_{ckl} may be given by:

$$\epsilon_{ckl} = \epsilon_c \left(\begin{aligned} &\text{dot}(b_k, b_l) + \text{dot}(b_{k+1}, b_l) + \\ &\text{dot}(b_k, b_{l+1}) + \text{dot}(b_{k+1}, b_{l+1}) \end{aligned} \right)$$

where, ϵ_c represents an energetic preference parameter which is applied, uniformly, to all residue pairs independent of their conformation.

Sidechain Interactions

In the preceding section, the subject of interactions relating to backbone conformation was discussed. In the following section, the subject of interactions between sidechains is discussed. Sidechain interactions are treated as being independent of backbone conformation. Interactions between any pair of side chains is allowed if the interacting sidechain sites lie at a distance of $\sqrt{2}$ from each other. Sidechains may be hydrophobic, hydrophilic or inert. Pairs of hydrophobic sidechains interact with an attractive potential of mean force; hydrophobic/hydrophilic pairs interact with a repulsive potential of mean force; and hydrophilic pairs interact weakly (i.e., weakly

attractive or repulsive with no change in quality to behavior).

With respect to the calculation of sidechain-sidechain interaction energy, the following rules (scales) were employed in one calculation:

5 glycines were assumed to lack sidechains and were assigned a hydrophobicity index $h(i) = 0$. Hydrophobic residues were assigned a negative hydrophobicity index $h(i) < 0$, and hydrophilic

10 residues were assigned a positive hydrophobicity index $h(i) > 0$. For all sidechains that were greater than two residues apart down the chain, the sidechain-sidechain interaction matrix $am(i,j)$, representing the interaction energy between the i^{th}

15 and the j^{th} pair of sidechains, was given in the form:

$$am(i,j) = -h(i) \cdot h(j) \cdot \epsilon$$

where $\epsilon = \epsilon_{phobe-phobe} > 0$, if $h(i)$ and $h(j)$ were both negative (that is, if both were hydrophobic).

20 $\epsilon = \epsilon_{phobe-phil} > 0$ if one residue is hydrophobic and the other hydrophilic, and $\epsilon = -\epsilon_{phil-phil}$, (with $\epsilon_{phil-phil} > 0$), if both $h(i)$ and $h(j)$ are positive, that is, if both sidechains are hydrophilic. The subscripts

25 phobe-phobe mentioned above represent interaction between two hydrophobic residues, phobe-phil represents interaction between a hydrophobic residue and a hydrophilic residue, and phil-phil represents interaction between two hydrophilic residues. (As

30 indicated above and in the program listing shown in Appendix D, tertiary interactions between any spatially close pair of sidechains are implemented using a modified Miyazawa-Jernigan (MJ)

35 hydrophobicity scale. Based on the frequency of occurrence of contacts between sidechain pairs in protein crystal structures, the MJ scale is used to

determine effective inter-residue contact energies.)

As used below, short-range interactions shall mean interactions between adjacent residues in the chain and does not include effects of their neighbors (i.e., neighboring residues in the chain).
5 Medium-range interactions shall mean interactions between first, second, and third nearest-neighbor residue groups in the chain. Long-range interactions shall mean interactions between residues (not α -carbons) which are positioned greater than three
10 nearest neighbors apart down the chain but which are spatially close (i.e., within 3 Å of each other).

Both native and non-native interactions are allowed between non-bonded pairs of residues that are
15 specially close enough to interact. No criterion or constraint is imposed to drive the simulation towards any predetermined native conformation. Based on long or short interactions, a native conformation may comprise one of a number of isoenergetic states. It
20 is the juxtaposition of short-medium-and-long-range interactions, together with other factors described herein that produce the final result, namely a stable, folded conformation.

As described hereinafter, all of the
25 energetic parameters, ϵ_θ , ϵ_ϕ , ϵ_{rep} , $\epsilon_{phobe-phobe}$, $\epsilon_{phobe-phil}$, $\epsilon_{phil-phil}$ are uniformly scaled by a reduced temperature factor, T .

With respect to specifying other characteristics of the primary sequence of amino acid
30 residues, the following conventions are used. In a simplified model, the term $B_i(k)$ is used to represent the i^{th} stretch of k residues in the sequence. The k residues are represented as having identical ϵ_θ and ϵ_ϕ values and a marginal (short and intermediate
35 range) preference for β -state conformation.

range) preference for β -state conformation. Consistent with β -sheet formation, $B_i(k)$ also represents an alternating odd/even pattern of hydrophilic and hydrophobic residues. --

5 Where a sequence of k residues are locally indifferent to whether they are in an α -helix or in a β -sheet, the term $AB_i(k)$ may be used to denote the i^{th} -stretch in the amino acid sequence containing k residues in an alternating hydrophobic/hydrophilic pattern, such that $\epsilon_\theta(12) = \epsilon_\theta(16)$ for all k residues. Where a sequence of k residues has an alternating hydrophobic/hydrophilic pattern and locally prefers α -helical state conformation, such that $\epsilon_\theta(12) = 0$ and $\epsilon_\theta(16) > 0$, this is denoted by 10 the shorthand notation $A_i(k)$.

15 Putative band regions are denoted by $b_i(j)$, and consist of j residues located at the interface between putative β -stretches i and $i+1$.

20 Chain Dynamics. Modification of Conformations

The dynamics of the chain are simulated by a (pseudo) random sequence of conformational rearrangements (moves) (i) through (iv) described below. In all such moves, the bead (amino acid residue) on which the move is performed is chosen at random. 25

(i) Examples of single bead jumps (also referred to as flips, spike or kink moves) are shown in Figure 9. Also, a representative set of single-bead modifications is listed in Table I. These moves are constructed by conserving the vector $b_{i-1} + b_i$ (i.e., not changing the magnitude nor direction of imaginary vector $(b_{i-1}+b_i)$). The moves are made in a manner which maintains the bond angle associated with 30 the i^{th} residue but changes the bond angles of the i -

five distinct possible outcomes (associated with $r_{e1}^2 = 12$), each of the moves is coded with five outcomes, some of which are degenerate (i.e., their conformations, each has the same energy). A clock is used to sequentially choose the particular outcome. New conformations of jumps (kinks) are also generated at random. After a move has been selected, it is only accepted if the adjacent bond angles are allowed (i.e., r_{e1+1}^2 and r_{e-1}^2 must lie in the range 6-18). If the move satisfies these local geometric constraints, then the sites (seven backbone sites plus four sidechain sites) into which the bead will jump are checked to insure that they are unoccupied. Otherwise, the move is rejected (not made). A list of sample single-bead, modified vector values is presented in Table I.

TABLE 1

Sample Single Bead Modification Data

<u>CONFORMATION</u> <u>r^2_e</u>	<u>EXAMPLE SEQUENCE</u> <u>OF INITIAL VECTORS</u>	<u>POSSIBLE</u> <u>MODIFICATIONS</u>
2 (excluded)
4 (excluded)
6	(2,-1,0) (0,2,1)	a. (0,2,1), (210) b. (2,0,-1), (0,1,2) c. (0,1,2), (2,0,-1)
8	(1,2,0), (-1,0,2)	a. (-1,0,2), (1,2,0) b. (1,0,2), (-1,2,0) c. (-1,2,0), (1,0,2)
10	(1,2,0) (2,-1,0)	a. (2,-1,0), (1,2,0)
12	(1,2,0), (1,0,2)	a. (1,0,2), (1,2,0) b. (2,1,0), (0,1,2) c. (0,1,2), (2,1,0) d. (2,0,1), (0,2,1) e. (0,2,1), (2,0,1)
14	(2,-1,0), (0,-2,1)	a. (0,-2,1), (2,1,0)
16	(1,2,0), (-1,2,0)	a. (-1,2,0), (1,2,0) b. (0,2,1), (0,2,-1) c. (0,2,-1), (0,2,1)
18	(-1,2,0), (0,2,1) or (-2,1,0), (-1,2,0)	a. (0,2,1), (-1,2,0) a. (-1,2,0), (-2,1,0)
20 (excluded)

(ii) With respect to two-bead end flips (in which the two end bonds are transformed to a new set of vectors), the set of two vectors is chosen at random from the twenty-four possible orientations of the lattice vectors. In this case, the two new end bond vectors must satisfy the allowed local bond angle criteria. If they do not, the move is rejected. Further, the two end residues in their new conformation must not violate excluded volume constraints.

The above-mentioned moves (i) and (ii) satisfy the correct dynamics for the athermal random coil state in the absence of hydrodynamic interactions.

(iii) Turning now to chain rotations, an example of this type of move is shown in Fig. 10. The minimum size unit selected for rotation consists of three beads, and the maximum size unit is $2 + \text{wave}$. (The value of the parameter "wave" is generally 4, it is chosen so that the size of the unit undergoing the rotation is the size of a mean element of secondary structure.) The particular size of the unit ($\delta + 1$) undergoing the attempted rotation is chosen by the value of an external clock parameter, and sequentially varies from the minimum to maximum size. A particular bead I , at one end of the rotating unit, is chosen at random. For beads less than $n/2$, the unit undergoing the rotation is $I - \delta$. For beads greater than $n/2$, the unit undergoing rotation is $I + \delta$. If i_b represents the first residue at the beginning of the rotating unit, and i_{end} represents the residue at the end of the rotating unit, then if the bond angle state between the vectors b_{i_b} and $b_{i_{\text{end}}-1}$ is a 14-18 state, the rotation is attempted. (The range of values of $r_{\theta_1}^2$ is chosen so that the rotation

is physically possible.) The rotation is implemented by interchanging the two bond vectors (e.g., vectors 35, 37 joining randomly selected bead 39 shown in Fig. 10). The initial set of bond vectors joining residues i_b to i_{end} is $(b_{i_b}, b_{i_b+1}, \dots, b_{i_{end}-2}, b_{i_{end}-1})$.
 5 The final set of bond vectors is $(b_{i_{end}-1}, b_{i_b+1}, \dots, b_{i_{end}-2}, b_{i_b})$. The new conformation is checked to insure that it can join the remainder of the chain without violating bond angle restrictions and
 10 excluded volume restrictions.

(iv) Internal wave-like motions such as are shown in Figure 11 are also performed. These moves serve to propagate defects down the subchain by deleting a defect at one end of the subchain and
 15 creating the defect at the other end of the subchain. The defect propagation procedure is performed by the system as follows. I denotes a bead chosen at random. The system first determines if a U-shaped defect exists (i.e., does $b_I = -b_{I+3}$?). If not,
 20 attempt at wave-like motion is abandoned. If a defect exists, the system then picks a place where the defect should be inserted. The chosen point is at $JJ = I+2 \pm (5+\delta)$, with δ varying between 0 and wave-1. About half of the time, the defect insertion
 25 point lies to the left of I , and the other half the time it lies to the right of it. As mentioned before, typically, the value 4 is selected for wave. As shown in Fig. 11, the bond vectors b_I 41 and b_{I+3} 43 are then sliced out of the chain, thereby deleting
 30 two beads 43 and 47, provided that b_{I+1} 49 and b_{I+2} 51, which will form the new bond angle state or vertex $I+1$ 53, satisfy the local geometric constraints of the chain. Next, two bonds 49, 51 are inserted into the chain. If the original vectors associated with
 35 beads $JJ-1$ and JJ are b_{JJ-1} and b_{JJ} , the new set of

four vectors are $(v, b_{JJ-1}, b_{JJ}, -v)$, where the vector v is chosen at random. Note that the intervening bond factors between $I+4$ and $JJ-2$ are left unchanged. A new conformation is then generated by renumbering the residues so that their identity is conserved. As before, both excluded volume and local bond angle criteria must be satisfied in order for the conformation to be accepted.

After each of the elemental moves (i) - (iv), described above, the energy of the new conformation, E_{nev} , is calculated and compared to the energy of the old conformation E_{old} . E_{nev} represents the sum of the individual energies, and is expressed as:

$$E_{\text{nev}} = E_{\theta} + E_{\phi} + E_c + E_s$$

$$\text{where } E_{\theta} = \sum_N \epsilon_{\theta}$$

$$E_{\phi} = \sum_{\text{tor}} \epsilon_{\phi}$$

$$E_c = \sum_{i,j} \epsilon_{ckl}$$

$$\text{and } E_s \text{ (also referred to as } E_{s,\text{id}}) = 1/2 \sum_{i,j} \text{am}(i,j)$$

(The term E_{old} represents the initial total value, then successive previous total values with which E_{nev} is compared.)

With respect to free energy (as distinct from total energy), the system attempts to find a free energy minimum, given as:

$$\text{Free energy} = \text{Total energy} - TS$$

where T represents temperature, and S represents entropy.

If E_{nev} is less than E_{old} , then the conformation is accepted. Otherwise, a Metropolis

sampling criterion is applied (as described for example in *Monte Carlo Methods in Statistical Physics* 2nd ed. by K. Binder, Springer-Verlag, Berlin, New York, 1986). In which event, a random number—R
5 uniformly distributed between 0 and 1 is generated. If R is less than the probability P, where

$$P = \text{EXP} \frac{-(E_{\text{new}} - E_{\text{old}})}{K_b T}$$

10 then the conformation is accepted; otherwise, it is rejected. Here, k_b represents Boltzmann's constant and T represents the absolute temperature of the protein. Thus, a standard asymmetric Metropolis sampling scheme (criterion) is employed. As
15 described below, the sampling scheme or criterion is applied in conjunction with a dynamic Monte Carlo technique (as described for example in *Monte Carlo Methods in Statistical Physics* by K. Binder, cited above).

20 A single Monte Carlo dynamics time step consists of N attempts at move type (i) (jump-type move) mentioned above, two attempts at move type (ii) where each of the chain ends are subjected to move type (ii), one attempt at move type (iii), and one
25 attempt at move type (iv). In the simulation, the protein model is started out in a randomly generated high temperature (T) state. It is then cooled down, equilibrated, cooled further, until collapse to a folded conformation occurs. For each simulation run
30 in the transition region between unfolded and folded states, at least 1.25×10^6 Monte Carlo time steps are sampled. The set of elemental moves employed in the simulation satisfies the well known stochastic kinetics master equation describing the dynamics of
35 the system. (Refer, for example, to Appendix B.) In the limit (after a large number of steps), an

equilibrium distribution of states is generated.

With respect to the thermodynamics of folding, a detailed explanation is presented below. By restricting the protein to the lattice, it may be
 5 treated as a rotational isometric state model of the protein. First, the transition from the denatured to the native state is treated in the context of a two-state model. The free energies of the denatured state A_D , and the native state A_N are calculated as
 10 follows: A_D is calculated by neglecting all tertiary interactions in the denatured state (although pentane-like effects are included). In the calculation of A_D , long range excluded volume effects are neglected. For the calculation of A_N , small
 15 local fluctuations about the native state are neglected, and A_N is approximated by the energy of the native state E_N .

In the context of a two-state model for folding, the fraction of molecules in the native
 20 state, f_N , is given by

$$f_N = \frac{\exp\{-(E_N - A_D)\}}{[1 + \exp\{-(E_N - A_D)\}]} \quad (2)$$

25 where A_D is given as:

$$A_D = K_B T \ln(Z_D) \quad (3)$$

(The term Z_D may be expressed as $Z_D = J \prod_{i=1}^{N-1} V_{D,i} J$, as defined in Appendix C.)

30 In the context of the two-state model, the mean square radius of gyration $\langle S^2 \rangle$, defined as

$$\langle S^2 \rangle = \frac{\sum_{i=1}^N (r_i - r_{cm})^2}{N} \quad (4)$$

with $|r_i - r_{cm}|$ representing the distance of the i^{th} bead from the center mass r_{cm} , may be expressed as

$$\langle S^2 \rangle = f_N \langle S_N^2 \rangle + (1 - f_N) \langle S_D^2 \rangle \quad (5)$$

5 where $\langle S_N^2 \rangle$ and $\langle S_D^2 \rangle$ are the mean square radii of gyration in the native and denatured state, respectively.

The above explanation may be used to select appropriate temperature values for use in the
10 simulation. Substantial computer time can be saved by avoiding high temperatures associated with the denatured state. Also, temperatures that are too low can drastically quench the system.

15 Conformational Transitions

As shown below, conformational transitions can be approximated by a two-state model, or can be determined directly from folding trajectories.

In the following paragraphs, the
20 requirements for folding to a unique conformation (e.g., a four-member β -barrel state) are described. Figs. 12A-D show a segment with backbone α -carbons 101 and interacting sidechain sites 103. Also shown in the top view are hydrophobic core 105
25 with the interdigitating sidechains 107, 109. Also shown are the corresponding conformations 111, 113 with α -carbons alone.

The first of the three native turns is shown to involve the eight through eleventh residues with
30 backbone bond angle conformations 18, 8, 18, and 10, respectively. The central turn is shown to involve a crossover connection between the two anti-parallel β -strands, and involves the eighteenth through twentieth residues with backbone bond angle
35 conformations 14, 10, and 18. The remaining outer

turn is shown to involve residues the twenty-sixth through twenty-ninth residues in bond angle conformations 12, 14, 14 and 8. The remainder of the bond angle states are all 16-type states. Thus, a planar β -sheet is assumed. Within an anti-parallel β -hairpin, the α -carbons are shifted with respect to each other by one lattice unit. This allows for the interdigitation of the side chains mentioned above. In the fully native conformation, there are twenty contacts between neighboring sidechains (i.e., twenty pairs of sidechain interacting sites that are a distance of $\sqrt{2}$ from each other).

In the conformation considered here, the pattern of hydrophobic and hydrophilic residues is the same. The model chain consists of $N=37$ residues. In each of the strands, all of the even (odd) residues are hydrophobic (hydrophilic). The first strand consists of the first through eighth residue. The ninth through eleventh turn residues are all hydrophilic. The second strand runs from the twelfth to the eighteenth residue, with all the even (odd) residues hydrophobic (hydrophilic). The nineteenth and twentieth turn residues are, respectively, hydrophilic and hydrophobic. The third strand runs from the twenty-first to the twenty-sixth residue. The twenty-seventh through twenty-ninth are turn residues, all of which are hydrophilic. The fourth strand runs from the thirtieth to the thirty-seventh residue. The first and last residues (one and thirty-seven) are virtual residues (i.e., they are devoid of sidechains, but they do occupy excluded volume). They may be regarded as capping the two ends, and are included so that the bond angle state for the real residues (the second and thirty-sixth residue) may be defined.

Turning now to the subject of equilibrium folding, the requirements for equilibrium folding of a region of the chain to its unique, native structure (e.g., the four-member β -barrel structure) is described. The interplay of an intrinsic native turn propensity and a short- and medium-range preference for β -sheet formation is described.

In one simulation operation, for the sequence $B_1(7)b_1(4)B_2(6)b_2(3)B_3(5)b_3(4)B_4(8)$ the parameter $\epsilon_\theta(16)$ was found equal to zero for the B_1 state and $-0.25/T$ for all the other states. For the B_1 state the parameter $\epsilon_\phi(16,16,37) = .6/T$, and is zero for all other states. For the turns b_i : $\epsilon_\theta=0$ for the native conformation, and $\epsilon_\theta=.25/T$ for all other conformations. Similarly, $\epsilon_\phi = .6(1.75)/T = -1.05/T$. $\epsilon_{\text{phil-phil}} = .25/T$, $\epsilon_{\text{phil-phob}} = 1./T$, and $\epsilon_{\text{phob-phob}} = -.75/T$. The cooperativity parameter $\epsilon_c = -.15/T$. In the native conformation, the total short range free energy $E_\theta = 0$, the total torsional energy $E_{\text{tor}} = -25.8/T$, the total sidechain interaction free energy arising from hydrophobic interactions $E_{\text{side}} = -14.25/T$, and the cooperative interaction free energy $E_c = -11.25/T$. Thus, the total energy of the native state $E_N = -51.3/T$. A summary of the conformational properties of this sequence, as well as all the other types of primary sequences, is presented in Table II. The primary sequence is designated by a shorthand notation $\epsilon_\alpha > \epsilon_\beta, 1., 1.75$. This notation indicates that, based on bond angle preferences, β -conformations are locally preferred for the B_1 portions of the primary sequence, and that the torsional angle preference ϵ_ϕ (for native-like conformations in the B_1 region) is locally favored by a ratio of 1:1.75 over that in the turn region.

TABLE II
Compilation of Selected Folding Results

Sequence	No. of Folding Attempts	No. of Successful Folds	Intrinsic Turn Probability
$\epsilon_\alpha > \epsilon_\beta$; 1. 1.75	5	5	0.0046
$\epsilon_\alpha > \epsilon_\beta$; 1.; 1.5	6	4	0.0021
$\epsilon_\alpha = \epsilon_\beta$; 1.; 1.5	6	6	0.0025
$\epsilon_\alpha = \epsilon_\beta$; 0.5; 1.5	7	5	0.0093
$\epsilon_\alpha = \epsilon_\beta$; 0.; 1.5	11	5	0.063
$\epsilon_\alpha = \epsilon_\beta$; 0.; 1.75	10	10	0.14
$\epsilon_\alpha < \epsilon_\beta$; 1.6; 0.05.	11	11	0.036
$\epsilon_\alpha = \epsilon_\beta$; 1.; 0	14	0	5×10^{-5}

In the absence of long-range interactions, there is a negligible intrinsic preference for the native conformation. To address this point, reference is made to equations 2-5. Using equations 2-5, the transition midpoint (including tertiary interactions) is predicted to be near $T = 0.576$. Employing equation (3), it is found that at this temperature $A_D = -88.44$, and that E_N (without tertiary interactions) equals -44.79 . The fraction of molecules in the native conformation which would be present if all tertiary interactions are turned off (that is, the equilibrium population based on short and medium range interactions embodied in E_θ and E_{tor} alone) is given by

(6)

$$f_N^\circ = \exp(-E_{\text{tor}}) / \exp(-A_D).$$

Using equation 6, f_N° is found to have the value:

$$f_N^\circ = 1.11 \times 10^{-19}.$$

Thus, there appears to be a negligible

preference for the native state in the absence of long range interactions, suggesting that finding of the native conformation is by no means guaranteed by the above choice of short and medium range --
5 interaction parameters. Rather, this chain will thrash about until it finds the native state.

The next subject described below is the nature of the conformational transition itself. In Figs. 13A-C, the average number of native contact
10 pairs between sidechains (N_c) versus time, is plotted for a chain under denaturing conditions at $T = 0.6$, in the thermal transition region at $T = 0.58$, and under strongly renaturing conditions at $T = 0.545$. The times indicated in the figure are in units of 500
15 Monte Carlo steps, and the fully native molecule contains twenty contact pairs. Under denaturing conditions, N_c fluctuates around zero, characteristic of a relatively short, unfolded chain. In the transition region, the system starts out unfolded,
20 and then around $t/5000 = 118$, it undergoes a rapid transition in about 6,500 Monte Carlo time steps to the fully native molecule. For the remainder of the time, it stays in the native state. Other conformational properties (not shown), such as the
25 energy, the instantaneous value of the radius of gyration, the total number of contact pairs $N_{c, tot}$ also undergo sharp changes in value that is a characteristic of an all-or none transition (i.e., a transition where the intermediates between the
30 denatured and fully folded states are marginally populated). On further cooling to $T = 0.545$, the chain becomes fully native, with minor oscillations in N_c arising from the fluctuations of the ends residues of the chain.

35 Decreasing the turn propensity for native-

like states decreases the stability of the native conformation and decreases the transition temperature. In the transition region, however, not only are native in-register four member β -barrels observed, but so are out-of-register conformations in which one of the exterior strands is two residues out-of-register, shifting the native contact between sidechains two and thirty-six to a non-native contact of residues two through thirty-four in one case, and to a non-native sidechain contact of residues four through thirty-six in the other case. In the former case, the outer turn began at residue twenty-five instead of residue twenty-six, thus, pushing the outer strand beyond the end of the barrel; and in the latter case, the turn began at residue twenty-eight and involved five residues, producing a bulge. Out of a total of six conformational transitions to a folded state, four folded directly to the native conformation, and two produced the out-of-register states described above.

The out-of-register state associated with residues four through thirty six occurred at relatively high temperature and folded in about 65,000 Monte Carlo steps. It remained folded for 315,000 time units before unfolding in about 165,000 time units.

Many out-of-register conformations have the same number of contacts between hydrophobic sidechains as in the native state; they differ in the cooperative free energy between the strands and in the local conformational preferences. Dropping the turn preference, increases the population of these out-of-register states. It is seen, therefore, that in the absence of some intrinsic preference for secondary structure, many in-register and out-of-

register conformations can be generated, and it is the marginal intrinsic turn propensities which act to select from among them one conformation as the unique folded form. Based on tertiary interactions between hydrophobic sidechains alone, many otherwise degenerate conformations can be generated. Here, a marginal preference for β -strand secondary structure plus the presence of turn neutral regions are required for folding to occur to a unique native state. Here, turn propensities of 1% or lower (see below, and Table II) are sufficient to yield folding to the native barrel of Figure 12.

It has been found that as the local propensity for β -states decreases, there is an increasing population of non-native turns and out-of-register states, even though the native turn population increases as T decreases. To fold the system to the global free energy minimum that corresponds to the native conformation, therefore, the free energy of out-of-register conformations should be increased relative to in-register conformations. As the local preference for β -states decreases, it becomes easier to form non-native turns; this appears to be the origin of the out-of-register states. Therefore, since the number of contacts between sidechains is approximately the same for the in-register and out-of-register cases, what determines the native conformation is the number of cooperative-type interactions, ϵ_c , plus the differences in local conformational preferences. Where the local preference difference is decreased, a number of out-of-register states that are in deep local minima is observed.

For a primary sequence of the type $\epsilon_a = \epsilon_b$; 0, 1.5 (which is similar to the above cases, except

that the torsional potential in the putative β -strand is disregarded), the β - and α -states are locally isoenergetic. The particular sequence of the AB_i stretches are induced by tertiary interactions. In all cases, the folded conformations turn out to be β -barrels. Thus, tertiary interactions taken with local turn propensities provide for selection of β -collapsed states. Where the transition temperature is reduced, the native turn populations become greater. For example, the calculated turn population of native turn one is about 10% at $T = 0.40$. Based on tertiary interactions alone, the unique native state is not achieved. This is most likely due to the degeneracy in sidechain contacts between the in-register and the two residue out-of-register conformers. If native turn propensity is sufficiently augmented, it appears that tertiary interactions plus intrinsic turn propensities are sufficient to yield the unique native state. Further, if the short-range interactions favoring β -strand formation are decreased, turn formation at a non-native location becomes more likely and, thus, the intrinsic turn propensity must be augmented (see Table II) to insure the recovery of a unique conformational state.

Next examined were sequences of the type $A_1(7)b_1(4)A(6)b_2(3)A_3(5)b_3(4)A_4(8)$; that is, molecules having the sequence $\epsilon_\alpha < \epsilon_\beta$; 0, 1.6; 0.05, where the nature of the conformational transition for model proteins whose β -strands in the denatured state locally favor α -helix conformation, but whose amino acid pattern still consists of alternating hydrophobic and hydrophilic residues. For A_1 , it has been found that $\epsilon_\theta(12) = 0$, $\epsilon_\theta(16) = 0.05/T$, and for all the others $\epsilon_\theta = .25/T$. Furthermore, it was found

that $\epsilon_i = 0$ for all the residues in A_i . These systems (where the local preference is for an α -helix conformation but the global free energy minimum conformation is that of a β -strand) spend substantial time trapped in relatively deep local minima. As the local preference for helical conformations is increased in the putative β -strand forming regions, while the unique four-member β -barrel is sometimes obtained, the chain generally thrashes about for over many millions of time steps (e.g., over 50 million) without finding a unique folded form.

An important indication from these simulation results is that a marginal local turn preference plus tertiary interactions are sufficient to produce unique native conformations, even in the extreme situation where the local conformational preference is for helices rather than β -sheet. If the native conformation is in thermodynamic equilibrium, then it is deemed to be at the lowest free energy state (conformation), independent of how the free energy is divided. That is, while it is conceptually convenient to divide the free energy into short-, medium- and long-range interaction contributions, it is the sum of these contributions, i.e., the total free energy, that determines the equilibrium conformation. The approach taken by the simulations show that the local minima problem can be surmounted to recover the lowest free energy structure, which overrides local considerations if there is a marginal turn propensity for native-like turns. Thus, turns appear to play an extremely important role in determining the ability to recover a unique native conformation.

Folding Pathway (Trajectory)

Turning now to a discussion of the folding pathway, it is seen that the sequence defines an observable pathway (trajectory) as it folds and makes the transition from its denatured (unfolded) conformation state to its native (folded) conformation state. A trajectory of a sample having the primary sequence $\epsilon_a > \epsilon_\beta$, 1., 1.75, is shown in Figs. 14A-B. The conformations at different times, are shown at different orientations that aid in the visualization of the folding process. At $t = 585,800$ Monte Carlo time units, folding is seen to initiate from the central turn 115 between the β -hairpin composed of strands two 117 and three 119. (Folding is not unidirectional. β -strands may dissolve, as well as form, during the course of assembly.) If the conformation at $t = 585,900$ is compared with that at $t = 586,000$, it will be seen that a slight dissolution of the β -hairpin 121 has occurred. By $t = 586,300$, the first β -hairpin 121 is almost fully assembled. However, by $t = 586,550$, the majority of one of the two strands in the β -hairpin dissolves and, then, reforms at $t = 586,600$. Then, there is a pause as the random coil tail 123 thrashes about, until the next native-like turn 125 forms. By $t = 587,700$, three of the four β -strands 117, 119, 127 are essentially in place. Thus, assembly to the three-member β -barrel intermediates takes 1,900 time steps from the beginning of folding. Throughout this process, the excluded volume of the chain hinders assembly. Most of the configurations of the denatured tail are nonproductive; the tail thrashes about until $t = 591,800$ when it works its way into a position(s) that permits native state assembly. After which, the assembly becomes more rapid and, by

t = 592,250, the fully folded molecule forms. Thus, the three-member β -barrel is the long-lived intermediate, living for 4,550 time steps or 71% of the total elapsed time from the start of folding.
5 The mechanism of assembly is best described as punctuated, on-site construction.

With respect to unfolding of a tertiary structure, in all instances unfolding is the reverse of folding. Typically, unfolding starts with either
10 one of the external strands becoming denatured or an internal strand closest to the denatured tail becoming unfolded.

15 Computer System and Method

Referring now to Figs. 3 and 15, a system and method are shown and described for simulating protein folding and determining three-dimensional (tertiary) structures of proteins.

20 The system comprises an input means 57 such as a keyboard for specifying (entering) selected amino acid sequences and other data such as temperature and fold preferences, a RAM (random access memory) 59 for storing such data, a ROM (read-only memory) 61 with a stored program, a CRT (cathode ray tube) display unit 63 and/or printer 65, an
25 optional auxiliary disk storage device 67 for storage of relevant data bases, and a microprocessor 69 for performing, under control of the stored program, the
30 steps of processing the entered data, simulating the folding of the protein from its unfolded state to its folded (tertiary) state, and displaying via the display unit (or printer) tertiary conformations of the protein in three dimensions.

35 A user enters the amino acid sequence data

file from the auxiliary storage unit). In response to entry of the sequence data, the system inputs (specifies) the data for processing, stores the data in memory then processes it as shown in Figs. 15A-F.

5 Sample data of the type which may be input to the system is shown in Appendix E. In processing the data, the system generates a tertiary interaction matrix as shown in Appendix E and produces, in addition to a display of the protein's tertiary

10 structure, a sample output as shown in Appendix E for tracking the simulation. As indicated above, the system operates under the control of a stored program. A listing of the program is shown in Appendix D.

15 Turning now to Figs. 15A-F, in response to the specified data the system generates a random conformation of backbone and sidechain elements (residues). It does this by generating a set of random bond angles, then generating the coordinates

20 of the backbone and sidechains as a starting chain in a 210 lattice (Fig. 4). The system then checks to determine if the excluded volume criterion is met, after which, it constructs an interaction table, a sample of which is shown in Appendix E. It proceeds

25 to construct the interaction table by first establishing respective bond angle preferences, then establishing dihedral (rotational) angle preferences followed by establishing side-chain interaction criteria. The system then stores the temperature,

30 bond angle, lattice coordinates, preferences, and interaction data in a table or matrix like that shown in Appendix E. Thereafter, the system reads the data from the table and constructs, by means of Monte Carlo simulation, a random conformation; following

35 which, the system calculates the total energy of the

conformation represented as (E_{old}). Thereafter, the system selects (at random by Monte Carlo simulation) a pair of bond vectors for rotation. It then checks if the rotation would violate the excluded volume criterion. If it would, the rotation is not attempted, and the system proceeds to the next step. If it would not violate the excluded volume criterion, another check is made to determine if the bond angles subtended by the bond vectors are between 14 and 18; if they are, it attempts the rotation. Otherwise, it does not attempt the rotation and proceeds to the next step. In performing rotation, the system modifies the conformation by interchanging a randomly selected pair of bond vectors. In other words, it proceeds to change the rotation angle ϕ . Thereafter, the system proceeds to determine the coordinates of lowest energy conformation which satisfy the Metropolis criterion. It does this by first calculating the total energy (E_{new}) of the new modified conformation then comparing the total energy E_{new} with the total energy of the old conformation E_{old} . If E_{old} is greater than E_{new} , then the coordinates of the old conformation are replaced with the coordinates of the new conformation. The system then proceeds to the next step (step B) which is described below. If E_{old} is not greater than E_{new} then, in compliance with the Metropolis criterion, a random number R is generated and the probability

$$P = e^{\frac{-(E_{new} - E_{old})}{K_b T}}$$

is calculated. That probability is compared with the random number R . If R is less than P , the coordinates of the old conformation is replaced with the coordinates of the new conformation and the system proceeds to the next step (step B). If,

however, R is not less than P , the system directly proceeds to the next step (Step B). At the next step, the system proceeds to choose a bead at random to move within the lattice. Before moving the bead, 5 the system tests if the move (which is a jump-type move) would violate the excluded volume criterion. If no, it proceeds with the move. If yes, it does not proceed with the move, and proceeds instead to choose the next bead until all the beads in the chain 10 have been checked for modification (movement). If the move would not violate the excluded volume criterion, the conformation is modified by moving the bead to a new lattice site. In other words, the bead would make a jump move which would change its 15 coordinates and associated bond angle θ . After the move is made and the conformation is modified thereby, the system calculates the total energy of the new conformation, that is, the total energy E_{nev} in a similar manner as indicated earlier. E_{nev} is 20 then compared with E_{old} , the energy of the previous conformation before the move. If E_{old} is greater than E_{nev} , then the coordinates of the old conformation are replaced with the coordinates of the new, and the next bead move is checked. If E_{old} is greater than 25 E_{nev} , then the Metropolis criterion is applied (and the random number R is generated, and the probability P is calculated in the same manner as indicated earlier, as shown in Fig. 15A-F), and the random 30 number R is compared with the probability P . If R is less than P , the coordinates of the old conformation are replaced with the coordinates of the new and the next bead move is checked. If R is not less than P , the next bead move is checked and the loop is 35 repeated until all bead moves (i.e., the moves of all n beads) have been checked, at which time if all bead

moves have been checked the system proceeds to the next step (step C). At this next step, the system proceeds to process the two end beads. It identifies the first end bead then checks if an end flip-type move would violate the excluded volume criterion. If no, it proceeds with the move. Otherwise, it aborts the move and proceeds to check the second end bead. In the event the move of the first end bead would not violate the excluded volume criterion, the system proceeds to modify the conformation by performing an end-flip move that changes the coordinates of the end bead. It then proceeds to determine the coordinates of the lowest energy conformation which satisfies the Metropolis criterion in the same manner as it did for the rotational and jump-type moves. After determining the coordinates of the lowest energy conformation which satisfy the Metropolis criterion, the system checks if both end beads are processed. If the second end beads remain to be processed, the system identifies the second end bead and proceeds to check whether an end flip move of the second end bead would violate the excluded volume criterion. If it would violate the criterion and both end beads have been considered, it then proceeds to the next step (step D). If it does not violate the criterion, then the system proceeds to modify the conformation by performing an end-flip move of the second end bead changing the coordinates of the second end bead. It then proceeds to determine the coordinates of the lowest energy conformation which satisfy the Metropolis criterion, after which it proceeds to the next step (step D). At this next step, the system selects a bond at random then searches for a U-shaped segment. It then checks, after finding the U-shaped segment, whether a move of a translation (wave

motion) type move would violate the excluded volume criterion. If not, it proceeds with the modification. If it does violate the excluded volume criterion, it aborts the move and proceeds to check
5 if all the jump-type moves were made. If all were made, it proceeds to the next step (step E). However, if the move would not violate the excluded volume criterion, the system proceeds to modify the conformation by performing the translation/wave-
10 motion-type move changing the coordinates of the beads defining the U-shaped segment. The system then determines the coordinates of lowest energy conformation which satisfy the Metropolis criterion, after which it proceeds to check if all the jump-type
15 moves were made. If all the jump-type moves are not made (completed), it starts the loop again. One complete loop is represented by one rotational move, n jump-type moves, two end-flip moves, and one U-shaped move. After the loops have been completed and
20 all moves made and/or aborted, the system checks to determine if the chain is still positioned near the center of the lattice. If it isn't, it moves the chain to the center of the lattice and adjusts its coordinates accordingly. Thereafter, the system
25 displays a three-dimensional representation of the protein structure and repeats the process (processing) for a predetermined number of times. However, if upon checking whether the chain is still
30 positioned near the center of the lattice, it finds that it remained at the position near the center of the lattice, the system immediately proceeds to displaying the three-dimensional representation of the protein, then repeats the process. After the three-dimensional coordinates of the tertiary protein
35 structure are generated for display, a graphics

program such as SYBYL (which is commercially available from Tripost Associates Corporation of St. Louis, Missouri) is used by the system to display the tertiary structure corresponding to the coordinates.

5 Sample display output is presented in Fig. 1. Sample printed output is presented in Appendix E.

An alternative embodiment of the system is presented in Fig. 16 comprising a keyboard 151 for entering data representing temperature and amino acid sequences, a RAM 153 for storing the entered data, 10 and a unit 155 for generating a representation of a lattice, including unit 157 for positioning lattice sites, and unit 159 for positioning α -carbons relative to the lattice sites. The system includes a 15 unit 161 for combining the generated lattice representation and the sequence of residues, a unit 163 for producing representations of protein structures, and a unit 165 for comparing the protein structure representations to a predetermined 20 criterion and for selecting one of the protein structure representations for display.

25

30

APPENDIX A

The following is a description of various lattice model rules which must be followed for constructing conformations of various sidechains linked to various backbone configurations.

As shown in Figure 8, let the i^{th} bond vector b_i connect α -carbons $(i-1)$ and (i) . Then, for a given backbone conformation, r_e^2 may be defined as follows:

$$r_e^2 = (b_i + b_{i+1})^2$$

On the 210 lattice, the allowed values of r_e^2 are 6, 8, 10, 12, 14, 16 and 18. Any other value of r_e^2 is rejected as not realistic or not representable on the 210 lattice. For a given backbone conformation, four sidechain vectors are constructed. The center of sidechain interaction is located at the site defined by a diamond lattice vector d_{34} , of the type $(\pm 1, \pm 1, \pm 1)$, which points from the center of the α -carbon to the point $(\pm 1, \pm 1, \pm 1)$. The other three vectors f_1 , f_2 and $f_{3, 36, 38, 40}$ are of the fcc type, whose sum is twice that of the diamond lattice vector d_{34} . The vector d has left-handed chirality (L). With respect to the backbone, vector d points toward the N-terminus of the sequence. The orientation angle is generally not less than 60° .

Pseudovector p is defined as the cross-product of b_{i+1} and b_i .

$$p = b_{i+1} \otimes b_i$$

and w is defined as:

$$w = b_i - b_{i+1}$$

Appendix A (Cont'd)

The general procedure for the calculation d , f_1 , f_2 and f_3 is given as follows: If $d = (d_x, d_y, d_z)$, then

$$f_1 = (d_x, d_y, 0)$$

$$f_2 = (d_x, 0, d_z)$$

$$f_3 = (0, d_y, d_z).$$

In the following, use is made of the function $\text{isgn}(x)$, where:

$$\begin{aligned} \text{isgn}(x) &= 1 \quad x \geq 0 \\ &= -1 \quad x < 0 \end{aligned}$$

If $r_e^2 = 14$, then

$$d_x = \text{isgn}(p_x)$$

$$d_y = \text{isgn}(p_y)$$

$$d_z = \text{isgn}(p_z)$$

If $r_e^2 = 8, 12$ or 16 , then

$$d_x = \text{isgn}(p_x - 2b_{x,i+1})$$

$$d_y = \text{isgn}(p_y - 2b_{y,i+1})$$

$$d_z = \text{isgn}(p_z - 2b_{z,i+1})$$

where

$$b_{i+1} = (b_{x,i+1}, b_{y,i+1}, b_{z,i+1}).$$

If $r_e^2 = 6$ or 10 , then

$$d_x = \text{isgn}(p_x + w_x)$$

$$d_y = \text{isgn}(p_y + w_y)$$

$$d_z = \text{isgn}(p_z + w_z)$$

Appendix A (Cont'd)

And, if $r_{\theta}^2 = 18$, and if $p_x \cdot p_y \neq 0$, then

$$\begin{aligned}d_x &= \text{isgn}(p_x) \\d_y &= \text{isgn}(p_y) \\d_z &= \text{isgn}(p_z).\end{aligned}$$

Otherwise,

$$\begin{aligned}d_x &= \text{isgn}(p_x + w_x) \\d_y &= \text{isgn}(p_y + w_y) \\d_z &= \text{isgn}(p_z + w_z).\end{aligned}$$

APPENDIX B

A generalized master equation is shown below:

$$\frac{\partial p(\{i\}, t)}{\partial t} = \sum_{\{i'\}} \dots \sum k_f p(\{i\} | \{i'\}) q(\{r_{i'}\}) - k_b p(\{i'\} | \{i\}) q(\{r_i\}) \quad (1)$$

where

$\{i\}$ represents a first set of vectors;

$\{i'\}$ represents a second set of vectors;

$p(\{i\}, t)$ represents the probability of finding a set of vectors $\{i\}$ at a time t ;

k_f represents rate of increase of the set $\{i\}$ in size (membership) due to move of bead from set $\{i'\}$ to set $\{i\}$;

k_b represents rate of decrease of the set $\{i\}$ in size due to move of bead to set $\{i'\}$ from set $\{i\}$;

$\{r_i\}$ and $\{r_{i'}\}$ represent coordinates of the set of bond vectors $\{i\}$ and $\{i'\}$;

$q(\{r_{i'}\})$ represents an excluded volume function

= 1; if $\{r_{i'}\}$ are unoccupied

0; if $\{r_{i'}\}$ are occupied

$p(\{i\} | \{i'\})$ represents the probability of occupying set $\{i\}$ upon moving from set $\{i'\}$;

$p(\{i'\} | \{i\})$ represents the probability of occupying set $\{i'\}$ upon moving from set $\{i\}$;

and the relationship between k_f and k_b may be expressed as:

$$\frac{k_f}{k_b} = \exp\left(-\frac{(U(i) - U(i'))}{k_B T}\right)$$

Appendix B (Cont'd)

where $U(i)$ represents the total energy of the protein in the i^{th} conformation;

$U(i')$ represents the total energy of the protein in the i'^{th} conformation; —

k_B represents Boltzmann's constant; and

T represents temperature (in degree Kelvin) of the protein.

A bead represents an amino acid residue comprising a full sidechain (i.e., four lattice sites) and backbone segment (i.e., seven lattice sites). A bead is shown, for example, in Figures 5 and 9. In terms of the above equation, the probability of finding a set of vectors $(i, i+1)$ at a time t in a two-bond jump-type move of a bead from one coordinate position (r_i) to another coordinate $(r_{i'})$ may be expressed as:

$$\frac{P(\{i, i+1\}, t)}{t} = \sum_{\substack{i', i'+1 \\ \theta_{i', i'+1} = \theta_{i, i+1}}} k_B P(i; i+1 | i'; i'+1; \theta) q(r_i) - k_B P(i'; i'+1 | i; i+1; \theta) q(r_{i'})$$

where,

i and $i+1$ represents a first pair of vectors;

i' and $i'+1$ represents a second pair of vectors; and

θ represents the bond angle between vectors (bonds) i and $i+1$ and between i' and $i'+1$.

In addition to the single-bead jump-type move described above, a conformation may be modified by rotational and/or translational motion of one or more beads, as shown for example in Figures 10 and 11.

Appendix C

Calculation of the Denatured State Free Energy

In this appendix, an expression for the free energy of the unfolded state of a model protein confined to a 210 lattice is calculated. Two cases are examined. The first corresponds to the situation when the torsional potential ϵ_ϕ equals zero, and the second corresponds to the more general case when ϵ_ϕ is non-zero.

With respect to the lattice, each of the twenty-four possible vectors connecting the lattice sites may be given a number one through twenty-four, as follows:

1=(2,1,0)	13=(0,-1,-2)	(C-1)
2=(2,0,1)	14=(0,-2,-1)	
3=(2,-1,0)	15=(0,1,-2)	
4=(2,0,-1)	16=(0,-2,1)	
5=(1,2,0)	17=(-1,2,0)	
6=(1,0,2)	18=(-1,0,2)	
7=(1,-2,0)	19=(-1,-2,0)	
8=(1,0,-2)	20=(-1,0,-2)	
9=(0,1,2)	21=(-2,1,0)	
10=(0,2,1)	22=(-2,0,1)	
11=(0,-1,2)	23=(-2,-1,0)	
12=(0,2,-1)	24=(-2,0,-1).	

To specify the conformation of the chain, given the location of the first bead, a sequence of $N-1$ numbers, ranging from 1 to 24, is specified with the first bond vector (vector 1) chosen arbitrarily as vector (2,1,0), the second vector must satisfy the constraint $6 \leq r_e^2 \leq 18$. There are 18 such possibilities, and there are four states such that $r_e^2 = 6$. The second vector can be (0,-2, ± 1) and (-1,0, ± 2). There are two such possibilities when $r_e^2 = 8$, namely (0,-1, ± 2). When $r_e^2 = 10$, there are two possibilities as well, (-1,2,0) and (1,-2,0). If $r_e^2 = 12$, again, there are two possibilities with the allowed second vectors being (0,1, ± 2). Turning to the $r_e^2 = 14$ case, there are a total of four possibilities (0,2, ± 1) and (1,0, ± 2). If $r_e^2 = 16$, there is one

possibility, (2,-1,0). Finally, for $r_e^2 = 18$, there are three possibilities (2,0, ± 1) and (1,2,0). In general, for a given vector number i , there are eighteen allowed vectors; subsequent allowed vectors vary depending on the particular vector that precedes them.

A pseudo inner product may be defined (by analogy to orthonormal basis sets) as follows:

$$\langle i, j \rangle = 1, \quad (C-2)$$

if the two vectors i and j are allowed, and

$$\langle i, j \rangle = 0, \quad (C-3)$$

if the two vectors i and j are not allowed.

Denatured state partition function $\epsilon_e = 0$

In the absence of a torsional potential that serves to couple adjacent bond angle states (and which, therefore, introduces cooperativity into the model), the internal partition function of the denatured state, Z_D^0 , may be obtained from

$$Z_D^0 = J \prod_{i=2}^{N-1} U_{D,i} J, \quad (C-4)$$

where J is a row vector of dimension 24, consisting of a 1 followed by twenty-three zeros, J is a column vector consisting of twenty-four ones, and $U_{D,i}$ is a 24 x 24 matrix associated with the i th residue, each row of which contains 18 non-zero elements and 6 zero elements. $U_{D,i}$ may be expressed as:

$$U_{D,i}(k,l) = \langle k,l \rangle \exp(-\epsilon_{e,i}(k,l) / k_B T). \quad (C-5)$$

As shown below, the configurational partition function can be written as the product of the internal bond angle partition functions associated with each bond angle state $^2_{e,i}$:

$$Z_D^0 = \prod_{i=2}^{N-1} Z_{\theta,i} \quad (C-6)$$

The matrix product in equation C-4 is of the form:

$$Z_D^0 = \sum_{k=1}^{24} \sum_{l=1}^{24} \cdots \sum_{r=1}^{24} \sum_{s=1}^{24} U_{D,2}(1,k) U_{D,3}(k,l) \cdots U_{D,N-2}(v,r) U_{D,N-1}(r,s) \quad (C-7)$$

Given that the sum of all the elements in the columns is independent of the row index (i.e., each row has the same set of bond angle states that must be summed over), the sum of the products can be expressed as the product of the sums, as follows:

$$Z_D^0 = \prod_{i=2}^{N-1} \sum_{k=1}^{24} U_{\theta,i}(1,k) \quad (C-8)$$

which is identical to equation C-6 because $Z_{\theta,i}$ is the same as

$$Z_{\theta,i} = \sum_{k=1}^{24} U_{\theta,i}(1,k) \quad (C-9)$$

Thus, the separability of the partition function is established. The free energy of the denatured state is simply

$$\epsilon_0 \neq 0 \quad R_D^0 = -k_B T \ln(Z_D^0) \quad (C-10)$$

To include the effect of non-zero ϵ_0 into the calculation of the partition function, the chain is divided into statistical weight matrices associated with pairs of bonds. That is, the partition function is calculated as

$$Z_D = J_{576} \prod_{i=2, \text{even}}^L U_i^{\theta} J_{576} \quad (C-11)$$

where J_{576} is a row vector of dimensionality 576 whose first term is unity and remaining terms are zero. J_{576} is a column vector of dimensionality 576, all of whose elements are unity. $l_0 = N$ if N is even, and $l_0 = N-1$ if N is odd. U_i^{θ} is a 576 by 576 matrix. For convenience in setting up U_i^{θ} , the torsional angles are labeled from 3 to $N-1$, rather than from 2 to $N-2$ as in the main text. For $i=2$, one merely has to account for the bond angle

associated with the second residue. Choosing the first bond as vector 1, the only non-zero elements of U_2^0 are

$$U_2^0(1,j) = \langle 1,j \rangle \exp(-\epsilon_{\theta,2}(1,j)/k_B T). \quad (C-12)$$

We next consider the case where $2 < i < l_0$. Let the bond vectors associated with residues $i-3$, $i-2$, $i-1$ and i be labelled by j, k, l, m , respectively. The j th bond vector connects residues $i-3$ to $i-2$. The rows of U_i^0 (row, column) are obtained from j and k by

$$\text{row} = (j-1)24 + k \quad (C-13)$$

$$\text{col} = (l-1)24 + m \quad (C-14)$$

In defining the statistical weight matrix $U_i(j, k, l, i)$ associated with the torsional potential due to the particular sequence of the three bonds j, k, l (where k goes from vertex $i-1$ to i), the distance $r_{i-2, i+1}$ between residues $i-2$ to $i+1$ is considered. If the square of this distance is less than 3, then due to the hard core steric repulsion,

$$U_i(j, k, l, i) = 0 \quad (C-15)$$

If $r_{i-2, i+1}^2 = 3$, then

$$U_i(j, k, l, i) = \langle j, k \rangle \langle k, l \rangle \exp[-(\epsilon_i(j, k, l) + 3\epsilon_{rep})/k_B T] \quad (C-16)$$

If $r_{i-2, i+1}^2 = 5$, then

$$U_i(j, k, l, i) = \langle j, k \rangle \langle k, l \rangle \exp[-(\epsilon_i(j, k, l) + \epsilon_{rep})/k_B T]. \quad (C-17)$$

For all other $r_{i-2, i+1}^2$,

$$U_i(j, k, l, i) = \langle j, k \rangle \langle k, l \rangle \exp[-(\epsilon_i(j, k, l))/k_B T] \quad (C-18)$$

Thus, local short range repulsions are accounted for in the treatment as well.

For $2 < i < l_u$, if l_u is even, and for $2 < i \leq l_u$ is odd, then

$$U_i^e(j,k,l,m) = \langle j,k \rangle \langle k,l \rangle \langle l,m \rangle \exp\left(-\frac{(\varepsilon_{\theta,i-1}(k,l) + \varepsilon_{\theta,i}(l,m))}{k_B T}\right) U_e(j,k,l,i-1) U_e(k,l,m,i) \quad (C-19)$$

If $i=l_u$, and l_u is even then, since vertex i is at the end of the chain, it is necessary to only account for the last bond angle and torsional angle associated with vertex $N-1$. To make this last matrix conformable with the previous matrices (e.g., vector type 1), an extra bond is appended at the end of the chain, giving:

$$U_{i=N}^e(j,k,l,N) = \langle j,k \rangle \langle k,l \rangle \langle l,l \rangle \exp\left(-\frac{\varepsilon_{\theta,N-1}(k,l)}{k_B T}\right) U_e(j,k,l,N-1) \quad (C-20)$$

From the above definitions of U , J and Z , it is seen where the free energy A_0 of the denatured state can be determined from the equation:

$$A_0 = -k_B T \ln(Z_0).$$

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APPENDIX D

```

C      only left handed diamond lattice  vectors can interact
C      revised to include a finer trajectory
C
C      generalized to include other  favoring of torsional potentials
C      uses full hydrophobic hydrophobic interaction matrix
C      based on Miyazawa Jernigan interaction scale
C
C      8/19/89
C      **FIXES THE PROBLEM OF GLYCINES AT POSITIONS 3 AND LENF-2
C      **PRESENT IN ALL PREVIOUS VERSIONS
C
C      ncglyshort.f is a version of nothermshort.f but which introduces
C      thermalization into the wave displacements
C
C      generates short trajectories
C      like jstherm but it also
C      calculates the number of native contacts
C
C      *****
C      SIDENCHAINS ONLY A DISTANCE OF THE SQUARE ROOT OF TWO CAN INTERACT
C      all other faces of the sidechain are hard core
C      produces equivalent interaction for 12 and 16' states
C      should produce shifted sq(10) for beta barrel like states
C      with hydrophobic core
C      program uses setind.f and ergd.f
C      *****
C
C      *
C      *          P R O T E I N    201
C      *          THE NEXT GENERATION
C      *
C      *****
C
C      WITH GLYCINE (NO SIDE GROUP) CODED AS := 0 (zero) HYDROPHOBICITY
C      NO GLYCINE ASSUMED ON THE THREE ENDS SEGMENTS.  ALLOWS FOR 6 STATE
C
C      PROGRAM SIMULATES SIMPLIFIED MODELS OF GLOBULAR PROTEINS BASED ON
C      THE " 2 1 0 " LATTICE ALPHA-CARBON REPRESENTATION.  INCLUDES SOME
C      DETAILS OF A SEQUENCE DESCRIPTION.  HAS BUILD-IN CHIRALITY OF THE
C      AMINOACIDS.  ASYMETRIC METROPOLIS SCHEME WITH A VARIETY OF LOCAL
C      REARRANGEMENTS OF MAIN (AND SIDE GROUPS) CHAIN BACKBONE.  EDITED BY
C      AK - FEB. 1989 ST. LOUIS.
C
C      REPULSIVE INTERACTIONS SORT(5)
C      WITH 'WAVE' MOTIONS, HYDROGEN BONDS, COOPERATIVITY, SIDE GROUPS..
C      THREE (+1) SITE SIDE GROUPS
C      NOTE THAT THIS PROGRAM USES EREP5,EHB,setini,REMOVES,LOOKG,ERGS
C      setind.f allows for interactions between left handed chirality
C      diamond lattice vector
C      vaxran version
C      *****
C      this version of program was created on 5/12/89
C      *****
C      4/18/89

```

c constructs the torsional potential in the program

c PHISEQ used
 c ah is the 1./temp in the thermalization step of the waves and
 c rotations
 c at the head of the INPUT file
 c *****

THE LATERAL TRANSLATION OF A STRING ADDED

WITH SPECIFICATION OF THE TORSIONAL POTENTIAL FOR SEQUENCE
 THIS IS GIVEN IN APH(24,24,24,'LENGTH') ARRAY WHICH HAS TO BE
 PREPARED AS AN INPUT FILE FILENAME='PHIPAT' USE AKPHIMAKE

LIST OF BACKBONE VECTORS - USE FOR ANALYSE OF LOCAL GEOMETRY

VECTOR NR	1	2	1	0	0	-1	1
	2	2	0	1	0	1	-1
	3	2	-1	0	0	-1	-1
(CODES ALSO	4	2	0	-1	0	1	1
FOR DIAMOND							
LATTICE TL)	5	1	2	0	-1	1	0
	6	1	0	2	-1	-1	0
	7	1	-2	0	-1	0	1
	8	1	0	-2	1	0	-1
	9	0	1	2	-1	0	-1
	10	0	2	1	-1	0	1
	11	0	-1	2	-1	-1	0
	12	0	2	-1	1	1	0
	13	0	-1	-2			
	14	0	-2	-1			
	15	0	1	-2			
	16	0	-2	1			
	17	-1	2	0			
	18	-1	0	2			
	19	-1	-2	0			
	20	-1	0	-2			
VECTOR NR	21	-2	1	0			
IS	22	-2	0	1			
THE	23	-2	-1	0			
CODE	24	-2	0	-1			

.....
 IMPLICIT INTEGER (I-2)

```

REAL vaxran
double precision etot,etot2,cv,anct,ant
real asumr2,asums2,as2
LOGICAL GOODC,LOOK
parameter(ndim=150)
DIMENSION ASTR(ndim),IDIS(ndim),STATN(ndim)
DIMENSION astrr(ndim),RIDIS(ndim),RSTATN(ndim),RIHAND(ndim)

```

```

DIMENSION XYZ(ndim,ndim,ndim), X(ndim),Y(ndim),Z(ndim),ihand(ndim)
DIMENSION VECTOR(-2:2,-2:2,-2:2), VX(24),VY(24),VZ(24)
DIMENSION ICONF(24,24),GOODC(24,24)
DIMENSION VECT1(24,24,5),VECT2(24,24,5)
DIMENSION SIDGR1(24,24),SIDGR2(24,24),SIDGR3(24,24)
DIMENSION ICA(0:ndim), STLX(13),STLY(13),STLZ(13)
DIMENSION AC(ndim,20),AM(ndim,ndim),IHYD(ndim),IC6(ndim)
DIMENSION IC8(ndim),IC10(ndim),IC12(ndim),IC14(ndim),IC16(ndim),IC18(ndim)
DIMENSION PRODV(24,24),ICAO(ndim), APH(24,24,24,ndim)
DIMENSION XNEW(ndim),YNEW(ndim),ZNEW(ndim),INDGL(ndim)
dimension iflip(20,5),inc(ndim,ndim)
dimension SLX(24,24)
dimension SLY(24,24)
dimension SLZ(24,24)
dimension xt(ndim),yt(ndim),zt(ndim)
DIMENSION AM(ndim,ndim),IHYD(ndim),IC6(ndim),ahyd(ndim,ndim)
      XYZ - OCCUPANCY LIST WITH SIDE GROUPS {0,-1,INDEX!!!}
      X, Y, Z - EXPLICIT COORDINATES OF I-LEAF BEADS
      ICONF - R2(VECTOR CODE, VECTOR CODE)
      ICA - EXPLICIT VECTORS DOWN THE CHAIN
      APH - ENERGY OF A GIVEN SEQUENCE OF THREE BONDS, DEPENDS
            ON CONFORMATION AND THE NUMBER OF THE RESIDUE

```

```

DATA VX /4*2,4*1,8*0,4*-1,4*-2/
DATA VY /1,0,-1,0,2,0,-2,0,1,2,-1,2,-1,-2,1,-2,2,0,-2,0,1,0,-1,0/
DATA VZ /0,1,0,-1,0,2,0,-2,2,1,2,-1,-2,-1,-2,1,0,2,0,-2,0,1,0,-1/

```

```

FCC LATTICE VECTORS (AND 000)
DATA STLX /4*0,-1,1,-1,1,-1,1,-1,1,0/
DATA STLY /-1,1,-1,1,1,-1,4*0,-1,1,0/
DATA STLZ /1,-1,-1,1,2*0,1,-1,-1,1,3*0/

```

TETRAHEDRAL LATTICE VECTORS

```

DATA TLX /1,-1,1,-1,1,-1,1,-1/
DATA TLY /-1,1,-1,1,1,-1,1,-1/
DATA TLZ /-1,1,1,-1,-1,1,1,-1/

```

CODING THE VECTORS TO THE ARRAY

```

DO XX=-2,2
DO YY=-2,2
DO ZZ=-2,2

```

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```

VECTOR(XX,YY,ZZ)=0
ENDDO
ENDDO
ENDDO

```

```

        VECTOR(2,1,0)=1
        VECTOR(2,0,1)=2
        VECTOR(2,-1,0)=3
        VECTOR(2,0,-1)=4
    VECTOR(1,2,0)=5
    VECTOR(1,0,2)=6
    VECTOR(1,-2,0)=7
    VECTOR(1,0,-2)=8
        VECTOR(0,1,2)=9

```

```

        VECTOR(0,2,1)=10
        VECTOR(0,-1,2)=11
        VECTOR(0,2,-1)=12
    VECTOR(0,-1,-2)=13
    VECTOR(0,-2,-1)=14
    VECTOR(0,1,-2)=15
    VECTOR(0,-2,1)=16
        VECTOR(-1,2,0)=17
        VECTOR(-1,0,2)=18
        VECTOR(-1,-2,0)=19
        VECTOR(-1,0,-2)=20
    VECTOR(-2,1,0)=21
    VECTOR(-2,0,1)=22
    VECTOR(-2,-1,0)=23
    VECTOR(-2,0,-1)=24

```

```

.....
LIST OF CONFORMATIONS - THE SUM OF TWO VECTORS
.....

```

```

DO I=1,24
DO J=1,24
ICONF(I,J)=(VX(I)+VX(J))**2+(VY(I)+VY(J))**2+(VZ(I)+VZ(J))**2
IDOTP=IABS(VX(I)*VX(J)+VY(I)*VY(J)+VZ(I)*VZ(J))
IF(IDOTP.EQ.5) PRODV(I,J)=1
ENDDO
ENDDO

```

```

THE CODE OF A VECTOR READS AS CODE=VECTOR(X,Y,Z) (1 TO 24)
AND VICE VERSA COORDINATES READ AS X=VX(CODE).....

```

```

.....
LIST OF ACCEPTABLE CONFORMATIONS 6-18 (LOGICAL TABLE)
.....

```



```

DO I=1,24
LO J=1,24
IF(ICONF(I,J).LT.6.OR.ICONF(I,J).GT.18) THEN
C      6,8,10,12,14,16, AND R2=18 ALLOWED
      GOODC(I,J)=.FALSE.
      ELSE
      GOODC(I,J)=.TRUE.
      END IF
ENDDO
ENDDO

C .....
C
C FLIP-TWIST ARRAY GIVES A DIRECT PREDICTION OF THE NEW CONF. STATE
C VECT1(I,J,K) GIVES A FIRST VECTOR AFTER JUMP FROM SEQUENCE OF I-J
C TO NEW STATES (SOMETIMES DEGENERATED) K=1,...5 < READS AS A CODE >
C .....
C
DO I=1,24

DO J=1,24
IF(GOODC(I,J)) THEN
  WX=VX(I)
  WY=VY(I)
  WZ=VZ(I)
  NX=VX(J)
  NY=VY(J)
  NZ=VZ(J)
  VECT1(I,J,1)=J
  VECT1(I,J,4)=J
  VECT1(I,J,5)=J
  VECT2(I,J,1)=I
  VECT2(I,J,4)=I
  VECT2(I,J,5)=I
  ICONA=(ICONF(I,J)-4)/2
  GO TO (6,1,2,3,2,5,2) ICONA
C
C      CONFORMATION R2-6
C      FOUR POSSIBLE ARRANGEMENTS
  SX=WX+NX
  SY=WY+NY
  SZ=WZ+NZ
  IF(ABS(SX).EQ.2) THEN
    IF(SY.NE.SZ) THEN
      WY=-WY
      WZ=-WZ
      NZ=-NZ
      NY=-NY
      ENDIF
    WX1=WX
    WX2=NX
    WY1=WZ

```

56

```

      WZ1=WX
      WY2=NZ
      WZ2=NY
      GO TO 15
    ENDIF
  IF(IABS(SY).EQ.2) THEN
    IF(SX.NE.SZ) THEN
      WX=-WX
      WZ=-WZ
      NX=-NX
      NZ=-NZ
    ENDIF

    WY1=WY
    WY2=NY
    WX1=WZ
    WZ1=WX
      WX2=NZ
      WZ2=NX
      GO TO 15
    ENDIF
  IF(IABS(SZ).EQ.2) THEN
    IF(SX.NE.SY) THEN
      WX=-WX
      WY=-WY
      NX=-NX

```

```

      NY=-NY
    ENDIF

```

```

      WZ1=WZ
      WZ2=NZ
      WX1=WY
      WY1=WX
      WX2=NY
      WY2=NX

```

```

    ENDIF

```

15

```

      N1=VECTOR(WX1,WY1,WZ1)
      N2=VECTOR(WX2,WY2,WZ2)
      VECT1(I,J,2)=N1
      VECT2(I,J,2)=N2
      VECT1(I,J,3)=N2
      VECT2(I,J,3)=N1
      GO TO 7

```

C
1

```

      MX=1
      MY=1
      MZ=1
      IF(IABS(WX).EQ.1) MX=-1
      IF(IABS(WY).EQ.1) MY=-1
      IF(IABS(WZ).EQ.1) MZ=-1
      PX=WX*MX
      PY=WY*MY

```

CONFORMATION R2=5

```

PZ=WZ*MZ
I2=VECTOR(PX,PY,PZ)
LX=NX*MX
LY=NY*MY
LZ=NZ*MZ
J2=VECTOR(LX,LY,LZ)
VECT1(I,J,2)=I2
VECT2(I,J,2)=J2
      VECT1(I,J,4)=I2
      VECT2(I,J,4)=J2
      VECT1(I,J,5)=J2
      VECT2(I,J,5)=I2
VECT1(I,J,3)=J2
VECT2(I,J,3)=I2
GO TO 7

```

C
C
C
C
2

CONFORMATION R2-10
CONFORMATION R2-14
CONFORMATION R2-18

```

VECT1(I,J,2)=J
VECT2(I,J,2)=I
VECT1(I,J,3)=J
VECT2(I,J,3)=I
GO TO 7

```

C
3

CONFORMATION R2-12

```

TEMPCO=3*WX*NX+2*WY*NY+WZ*NZ
SX=WX+NX
SY=WY+NY
SZ=WZ+NZ
TEMPCO=3
      -2

```

X AXIS DIRECTION IN THE ORIGINAL STATE
Y

C

```

      -1      Z      DIRECTION
GO TO (13,12,11) TEMPCO

```

11

```

WX1=SX
WX2=0
WZ1=0
WZ2=SZ
WY1=SY/2
WY2=SY/2
KX1=SX
KX2=0
KY1=0
KY2=SY
KZ1=SZ/2
KZ2=SZ/2
GO TO 14

```

12

```

WY1=SY
WY2=0
WZ1=0
WZ2=SZ

```

```

      WX1-SX/2
      WX2-SX/2
      KY1-SY
      KY2=0
      KX1=0
      KX2-SX
      KZ1-SZ/2
      KZ2-SZ/2
      GO TO 14
13  WZ1-SZ
      WZ2=0
      WX1=0
      WX2-SX
      WY1-SY/2
      WY2-SY/2
      KZ1-SZ
      KZ2=0
      KY1=0
      KY2-SY
      KX1-SX/2
      KX2-SX/2
14  N1=VECTOR(WX1,WY1,KZ1)
      N2=VECTOR(WX2,WY2,KZ2)
      VECT1(I,J,2)=N1
      VECT2(I,J,2)=N2
      M1=VECTOR(KX1,KY1,KZ1)
      M2=VECTOR(KX2,KY2,KZ2)
      VECT1(I,J,3)=M1
      VECT2(I,J,3)=M2
      VECT1(I,J,4)=N2
      VECT2(I,J,4)=N1
      VECT1(I,J,5)=M2
      VECT2(I,J,5)=M1
      GO TO 7
      SX=WX+NX
      SY=WY+NY

```

CONFORMATION R2=16

```

      SZ=WZ+NZ
      TEMPCO=(3*IABS(SX)+2*IABS(SY)+IABS(SZ))/4
      GO TO (23,22,21) TEMPCO
21  WX1=WX
      WX2=NX
      WY1=WZ
      WY2=NZ
      WZ1=WY
      WZ2=NY
      KX1=WX
      KX2=NX
      KY1=NZ
      KY2=WZ

```

```

      KZ1=NY
      KZ2=WY
      GO TO 24
22    WY1=WY
      WY2=NY
      WX1=WZ
      WX2=NZ
      WZ1=WX
      WZ2=NX
      KY1=WY
      KY2=NY
      KX1=NZ
      KX2=WZ
      KZ1=NX
      KZ2=WX
      GO TO 24
23    WZ1=WZ
      WZ2=NZ
      WX1=WY
      WX2=NY
      WY1=WX
      WY2=NX
      KZ1=WZ
      KZ2=NZ
      KX1=NY
      KX2=WY
      KY1=NX
      KY2=WX
24    N1=VECTOR(WX1,WY1,WZ1)
      N2=VECTOR(WX2,WY2,WZ2)
      VECT1(I,J,2)=N1
      VECT2(I,J,2)=N2
      VECT1(I,J,4)=N2
      VECT2(I,J,4)=N1
      M1=VECTOR(KX1,KY1,KZ1)
      M2=VECTOR(KX2,KY2,KZ2)
      VECT1(I,J,3)=M1
      VECT2(I,J,3)=M2
      VECT1(I,J,5)=M2
      VECT2(I,J,5)=M1
      CONTINUE
      CONFORMATION IS NOT ACCECTABLE
      ELSE

```

```

      ENDDO
      ENDDO

```

```

      DO K=1,5
      VECT1(I,J,K)=0
      VECT2(I,J,K)=0
      ENDDO
      END IF

```

```
C
C
C .....
C SIDE GROUPS - EXPLICITE DEFINITION BASED ON CONFORMATION R2
C .....
C                                     -
C          SIDGR1(24,24) - CONTAINS CODES OF 110 VECTORS
C          SIDGR2(24,24) - CONTAINS CODES OF 110 VECTORS
C          SIDGR3(24,24) - CONTAINS CODES OF 110 VECTORS
C
C DO I=1,24
C DO J=1,24
C     IF(.NOT.GOODC(I,J)) GO TO 40
C       X1=VX(I)
C       Y1=VY(I)
C       Z1=VZ(I)
C       X2=VX(J)
C       Y2=VY(J)
C       Z2=VZ(J)
C       ICONA=(ICONF(I,J)-4)/2
C       PX=Y1*Z2-Y2*Z1
C       PY=X2*Z1-Z2*X1
C       PZ=X1*Y2-Y1*X2
C
C           PX=-PX
C           PY=-PY
C           PZ=-PZ
C
C           WX=X1-X2
C           WY=Y1-Y2
C           WZ=Z1-Z2
C       GO TO (33,32,33,32,31,32,36) ICONA
C
C           SUMAX=PX
C           SUMAY=PY
C           SUMAZ=PZ
C
C               GO TO 39
C
C           SUMAX=PX-2*X2
C           SUMAY=PY-2*Y2
C           SUMAZ=PZ-2*Z2
C       GO TO 39
C
C           SUMAX=PX+WX
C           SUMAY=PY+WY
C
C SUMAZ=PZ+WZ
```

```

C      GO TO 39
C
C      CONFORMATION R2-18
C
C      36      IF(PX*PY.NE.0) THEN
C
C      SUMAX=PX
C      SUMAY=PY
C      SUMAZ=PZ
C
C      GO TO 39
C      ENDIF
C
C      THE CASE OF DOWN THE AXIS CONFORMATION
C
C
C      SUMAX=PX+WX
C      SUMAY=PY+WY
C      SUMAZ=PZ+WZ
C
C
C      39      SUX=ISIGN(1,SUMAX)
C      SUY=ISIGN(1,SUMAY)
C      SUZ=ISIGN(1,SUMAZ)
C
C      X1=SUX
C      X2=SUX
C      X3=0
C
C      Y1=SUY
C      Y2=0
C      Y3=SUY
C
C      Z1=0
C      Z2=SUZ
C      Z3=SUZ
C
C      GIVES THE CODE OF (STLX,STLY,STLZ)V, VALUE 1,2,..12
C
C      ICODT=9*X1+3*Y1+Z1
C      IF(ICODT.LT.0) ICODT=-1-ICODT
C      SIDGR1(I,J)=ICODT
C      ICODT=9*X2+3*Y2+Z2
C      IF(ICODT.LT.0) ICODT=-1-ICODT
C      SIDGR2(I,J)=ICODT
C      ICODT=9*X3+3*Y3+Z3
C      IF(ICODT.LT.0) ICODT=-1-ICODT
C      SIDGR3(I,J)=ICODT
C
C      insert of check for handedness
C      x4=(x1+x2+x3)/2
C      y4=(y1+y2+y3)/2
C      z4=(z1+z2+z3)/2
C      SLX(i,j)=x4
C      SLY(i,j)=y4
C      SLZ(i,j)=z4
C
C      40      CONTINUE
C      ENDDO
C      ENDDO
C
C      INPUT      INPUT      INPUT      INPUT      INPUT      INPUT      INPUT      INPUT      INPUT

```

SET UP OF THE VECTOR REPRESENTATION OF THE CHAIN

```

OPEN(UNIT=5,FILE='INPUT',STATUS='OLD')
OPEN(UNIT=10,FILE='FILEDAT',STATUS='OLD')
OPEN(UNIT=6,FILE='OUTPUT',STATUS='OLD')
OPEN(UNIT=1,FILE='SEQUENCE',STATUS='OLD')
OPEN(UNIT=11,FILE='contact',STATUS='OLD')
OPEN(UNIT=12,FILE='PHISEQH',STATUS='OLD')
OPEN(UNIT=14,FILE='PHISEQHR',STATUS='OLD')
OPEN(UNIT=13,FILE='TRACE',STATUS='OLD')
open(unit=15,file='hydmap',status='old')
open(unit=16,file='output',status='old')

```

```

READ(10,*) LENF
LENF1=LENF-1
LENF2=LENF-2
AL2=LENF2
LENF3=LENF-3
AL3=LENF3
LENF4=LENF-4
AL4=LENF4
AL6=LENF-6
AL9=LENF-9
MIX=1
LENHA=LENF/2

```

```

do i=1,100
  STATN(i)=0.d0
  IDIS(i)=0.d0
  ASTR(i)=0.d0
  IHAND(i)=0.d0
  RSTATN(i)=0.d0
  RIDIS(i)=0.d0
  astrr(i)=0.d0
  RIHAND(i)=0.d0
do j=1,100
do k=1,100

  xyz(k,j,i)=0.d0
end do
end do
end do

```

*****SEQUENCE READING*****

*****READING OF TORSIONAL POTENTIALS*****

EXPLICIT CONSTRUCTION OF APH
DO LJ=2,LENF1


```
READ(12,*)K,STATN(LJ),IDIS(LJ),ASTR(LJ),IHAND(LJ)
```

```

      END DO
c      generalized to include other conformational preferences
      read(14,*)other
      if(other .eq. 0) go to 542
      do lj=1,other
      READ(14,*)K,RSTATN(k),RIDIS(k),ASTRR(k),RIHAND(k)
      END DO
542      continue
      *****SEQUENCE READING*****
c
c      CAUTION::: THE REVERSE PATTERN IS NOT ALLOWED +K HAS TO BE
c                  ASSUMED AS A PREFERENCE FOR A GIVEN STATE
c
c
c      STATN - R2(I-1,I+1)
c      IDIS - R2(I-1,I+2)
c      ASTR- STRENGTH OF PREFERENCE FOR THE DIHEDRAL ANGLE
c
c      ah plays the role of the thermalization factor
      read(5,*)ah
      WRITE(6,8120)
8120  FORMAT(1X,' ** THE THREE SIDE GROUP PROGRAM
      * AND GLI glypredict.f full hydrophobic interaction matrix',/,
      *       'uses not necessarily native conf in torsions',/)

      NBGL=0
      INDGL(1)=0
      INDGL(LENF)=0
      DO I=2,LENF1
      INDGL(I)=1
      READ(1,*) K,IC6(I),
      * IC8(I),IC10(I),IC12(I),IC14(I),IC16(I),IC18(I),IHYD(I)
      IF(IHYD(I).EQ.0) THEN
          INDGL(I)=0
          NBGL=NBGL+1
      ENDIF
      ENDDO
c
c      *****INPUT FILE*****
c
      READ(5,*) RANDOM,NCYCLE, PHOT
      READ(5,*) AC6,AC8,AC10,AC12,AC14,AC16,AC18
      READ(5,*) APLPB,BPLPL,CPBPB,AREP,ANB,APHI
      READ(5,*) ATEMP,WAVEL
c
      WRITE(6,8020) RANDOM,NCYCLE,PHOT,WAVEL

```

```

8020  FORMAT(1X,' ** THE THREE SIDE GROUP PROGRAM AND GLI.**',/,
*      'DIAMOND LATTICE SITES INTERACT ',/,
*      '** glypredict with .5 *jernigan **',
*      1X,' RANDOM SEED =',I6,' NUMBER OF CYCLES',2I5,/,
*      1X,' MAXIMUM WAVE LENGTH =',I4,/)
      write(6,8999)ah
8999  format(1x,' temp/tempthermal =',1f8.4)

```

```

      WRITE(6,8021) AC6,AC8,AC10,AC12,AC14,AC16,AC18
8021  FORMAT(5X,/,3X,' ENERGY OF STATE 6 =',F6.2,/,
*      3X,' ENERGY OF STATE 8 =',F6.2,/,
*      3X,' ENERGY OF STATE 10=',F6.2,/,
*      3X,' ENERGY OF STATE 12=',F6.2,/,
*      3X,' ENERGY OF STATE 14=',F6.2,/,
*      3X,' ENERGY OF STATE 16=',F6.2,/,
*      3X,' ENERGY OF STATE 18=',F6.2,/)
      WRITE(6,8022) APLPB,BPLPL,CPPPB
8022  FORMAT(3X,' PHIL-PHOB, PHIL-PHIL, PHOB-PHOB ',4F8.3,/)
      WRITE(6,8024) AREP,AHB,APHI
8024  FORMAT(3X,' REPULSIVE INT. AND COOPER.+H-BOND',2F8.3,/,
*      ,3X,' SCALING FACTOR FOR DIHEDRAL ANGLE POTENTIAL',F8.3,/)
      WRITE(6,8023) ATEMP
8023  FORMAT(1X,/,3X,' TEMPERATURE OF THE SYSTEM =',F8.3,/)
C
C      construction of native contact map
      do i=1,lenf2
      do j=1,lenf1
      inc(i,j)=0.d0
      inc(j,i)=0.d0
      end do
      end do

      read(11,*)ntot
      write(6,2039)ntot
2039  format(1x,'not=',i3,/, 'the native contact pairs are' :
      do i=1,ntot
      read(11,*)j,k
      inc(j,k)=1
      write(6,*)j,k
      end do

C
C      ***** SET THE CURRENT FORCE OF INTERACTIONS *****
C
      APHI=APHI/ATEMP
      AHB=AHB/ATEMP
      AC6=AC6/ATEMP
      AC8=AC8/ATEMP
      AC10=AC10/ATEMP
      AC12=AC12/ATEMP
      AC14=AC14/ATEMP
      AC16=AC16/ATEMP

```

```

AC18=AC18/ATEMP
APLPB=APLPB/ATEMP
BPLPL=BPLPL/ATEMP
CPBFB=CPBFB/ATEMP
AREP=AREP/ATEMP

```

```

c do i=1,lenf2
  read(15,*)(ahyd(i,j),j=i,lenf2)
  write(6,*)(ahyd(i,j),j=i,lenf2)
  do j=i,lenf2
    ahyd(j,i)=ahyd(i,j)
  end do
end do

```

```

DO I=2,LENF1
  iml=i-1
  DO J=2,LENF1
    jml=j-1
    IF(IABS(I-J).GT.2) THEN
      am(i,j)=ahyd(iml,jml)/atemp
    ELSE
      AM(I,J)=0.
    A PRIORI NO INTERACTIONS OF SIDE GROUPS WHEN/I-J/<3
  ENDDIF
  ENDDO
ENDDO

```

```

DO I=2,LENF1
  AC(I,6)=IC6(I)*AC6
  AC(I,8)=IC8(I)*AC8
  AC(I,10)=IC10(I)*AC10
  AC(I,12)=IC12(I)*AC12
  AC(I,14)=IC14(I)*AC14
  AC(I,16)=IC16(I)*AC16
  AC(I,18)=IC18(I)*AC18
ENDDO

```

```

*****READING OF TORSIONAL POTENTIALS*****

```

```

DO 100 I=1,24
  X1=VX(I)
  Y1=VY(I)
  Z1=VZ(I)
DO 1200 J=1,24
  IF(GOODC(I,J)) THEN
    X2=VX(J)
    Y2=VY(J)
    Z2=VZ(J)

```

CROSS PRODUCT OF THE TWO FIRST VECTORS

.....

```
B=0.
aph(i,j,k,index)=0.
```

```

IF (STATN(INDEX).EQ.ST1.AND.STATN(INDEX+1).EQ.ST2) THEN
      KX=X1+X2+X3
      KY=Y1+Y2+Y3
      KZ=Z1+Z2+Z3
      R2=KX*KX+KY*KY+KZ*KZ
IF (R2.EQ.IDIS(INDEX).and. ihan .eq. ihand(index))B=ASTR(INDEX)
      ENDIF
APH(I,J,K,INDEX)=(B)*APHI
IF (RSTATN(INDEX).EQ.ST1.AND.RSTATN(INDEX-1).EQ.ST2) THEN
      KX=X1+X2+X3
      KY=Y1+Y2+Y3
      KZ=Z1+Z2+Z3
      R2=KX*KX+KY*KY+KZ*KZ
IF (R2.EQ.RIDIS(INDEX).and. ihan .eq. Rihand(index))B=astrR(INDEX)
      ENDIF
APH(I,J,K,INDEX)=(B)*APHI
CONTINUE

```

```

C.....
C
300    CONTINUE
      END IF
1200    CONTINUE
100     CONTINUE

```

```

ICA(0)=1
C  this is because the simplicity of APH reading, value irrelevant
ICA(LENF)=1

```

*****INITIAL CONFORMATION*****

C

caution (zero initialization assumed)

```

MAX=100
MID=MAX/2
SX=0
SY=0
SZ=0
DO I=1,LENF
  READ(10,*) X(I),Y(I),Z(I)
  SX=SX+X(I)
  SY=SY+Y(I)
  SZ=SZ+Z(I)
ENDDO

```

```

  SX=SX/LENF
  SY=SY/LENF
  SZ=SZ/LENF
  XSHIFT=MID-SX
  YSHIFT=MID-SY
  ZSHIFT=MID-SZ

```

```

DO I=1,LENF
  X(I)=X(I)+XSHIFT
  Y(I)=Y(I)+YSHIFT
  Z(I)=Z(I)+ZSHIFT
ENDDO

```

```

  DO I=1,LENF1
    J=I+1

```

```

    WX=X(J)-X(I)
    WY=Y(J)-Y(I)
    WZ=Z(J)-Z(I)
    ICA(I)=VECTOR(WX,WY,WZ)
  ENDDO

```

```

CALL setin(XYZ,INDGL(1),X(1),Y(1),Z(1),13,13,13,1)
CALL setin(XYZ,INDGL(LENF),X(LENF),Y(LENF),Z(LENF),13,13,13,1)
DO J=2,LENF1

```

```

  I=J-1

```

```

  II=ICA(I)

```

```

  JJ=ICA(J)

```

```

  IF(GOODE(II,JJ)) THEN

```

```

    S1=SIDGR1(II,JJ)

```

```

    S2=SIDGR2(II,JJ)

```

```

    S3=SIDGR3(II,JJ)

```

```

    CALL setin(XYZ,INDGL(J),X(J),Y(J),Z(J),S1,S2,S3,J)

```

```

  ELSE

```

```

    WRITE(6,8001) I,J

```

8001

```

    FORMAT(5X,'WRONG INPUT CHAIN - VECTORS ',2I4)

```

```

    GO TO 9000

```

```

  END IF

```

```

ENDDO

```

C

C.....CALCULATION OF THE ENERGY OF INITIAL STATE

```

C      E=0.
      ENERG=0.
      DO J=2,LENF1
      I=J-1
      II=ICA(I)
      JJ=ICA(J)
C
C      JCONF=ICONF(II,JJ)
      ENERG=ENERG+AC(J,JCONF)
C
C      ROTATIONAL CONTRIBUTION
C      INTERACTIONS OF SIDE GROUPS
C
C      IX=X(J)+S1X(ii,jj)
C      IY=Y(J)+S1Y(ii,jj)
C      IZ=Z(J)+S1Z(ii,jj)
C      E=E+ERG(XYZ,INDGL(J),AM,IX,IY,IZ,J)
4501  continue
      ENDDO
      ENERG=ENERG+E/2.
C
C      COOPERATIVE AND HYDROGEN BOND
C      E=0.
      DO I=2,LENF1
      E=E+EHB(XYZ,ICA,PRODV,X(I),Y(I),Z(I),I,AHB)
      ENDDO
      ENERG=ENERG+E/2
C
C      REPULSIVE INTERACTIONS
C      E=0.
      DO I=2,LENF1
      E=E+EREPU(LXYZ,X(I),Y(I),Z(I),1.)
C
C      ENDDO
C      this is because the implicate symmetry of repulsive interactions
C      which is taken into account in the remainder of the program.
C
C      E=(E-AL3*2.)/2.
      ENERG=ENERG+E*AREP
C
C      DIHEDRAL POTENTIAL
C
C      DO J=2,LENF2
      II=ICA(J-1)
      JJ=ICA(J)
      KK=ICA(J+1)
      ENERG=ENERG+APH(II,JJ,KK,J)
      ENDDO
C
C      //////////////////////////////////////
      RN1=RANDOM*2+7531
      RN2=RANDOM*2+8883
      RN3=RANDOM*6+7907

```

```

C *****
C *
C *          DYNAMICS OF THE CHAIN          *
C *
C *****
C
C MAIN CLOCK OF THE ALGORITHM
C
C ICLOCK=1
C
C QROT=0
C QWAVE=0
C QKINK=0
C QEND=0
C
C asumr2=0.
C asums2=0.
C etot=0.d0
C etot2=0.d0
C sxd=0.d0
C syd=0.d0
C szd=0.d0
C
C anct=0.d0
C ant=0.d0
C write(6,931)
931 format(1x,'iterm= R2= AS2= ENERGY= native any contacts')
C
C DO 7777 ITERM=1,NCYCLE
C                                iclock=iclock+1
C
C DO 7700 IDUMI=1,100
C                                iclock=iclock+1
C
C
C
C DO 7770 IPHCO=1,PHOT
C
C IF(ICLOCK.GT.2000) ICLOCK=ICLOCK-vaxran(rn2)*1000
C
C .....LATERAL WAVE DISPLACEMENT.....
C
C set up of the thermalization move
C if(vaxran(rn2) .gt. .01) then
C     af=1.d0
C else
C     af=ah
C end if
C IVA=MOD(ICLOCK,WAVEL)+3

```

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```

I=INT(vaxran(rnl)*AL6)+3
IF(I.GT.LENHA) THEN
    IFIRST=I-IVA
    ILAST=I
    ELSE
    IFIRST=I
    ILAST=I+IVA
    ENDIF
WI=ICA(IFIRST)
JL=ILAST-1
WJ=ICA(JL)
JCONF=ICONF(WI,WJ)
IF(JCONF.LT.14.OR.JCONF.GT.18) GO TO 7001
IF(.NOT.GOODC(ICA(IFIRST-1),WJ)) GO TO 7001
IF(.NOT.GOODC(WJ,ICA(IFIRST+1))) GO TO 7001
IF(.NOT.GOODC(ICA(ILAST-2),WI)) GO TO 7001
IF(.NOT.GOODC(WI,ICA(ILAST))) GO TO 7001

```

C

REMOVE THE STRING

```

DO K=IFIRST,ILAST
    II=ICA(K-1)
    KK=ICA(K)
    IKS1=SIDGR1(II,KK)
    IKS2=SIDGR2(II,KK)
    IKS3=SIDGR3(II,KK)
    XJ=X(K)
    YJ=Y(K)
    ZJ=Z(K)
    CALL REMOVE(XYZ,INDGL(K),XJ,YJ,ZJ,IKS1,IKS2,IKS3)
ENDDO

```

C
C
CSETIN AND EXCLUDED
VOLUME TEST

THE NEW VECTORS
ICA(IFIRST)=WJ
ICA(JL)=WI

```

    IFA=IFIRST-1
    XJ=X(IFA)
    YJ=Y(IFA)
    ZJ=Z(IFA)
DO J=IFIRST,ILAST

```

II=ICA(J-1)

```

JJJ=ICA(J)
    XJ=XJ+VX(II)
    YJ=YJ+VY(II)
    ZJ=ZJ+VZ(II)
    XNEW(J)=XJ

```


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```

YNEW(J)=YJ
ZNEW(J)=ZJ
S1=SIDGR1(II,JJJ)
S2=SIDGR2(II,JJJ)
S3=SIDGR3(II,JJJ)
IF(LOOK(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3)) THEN
C                                     THEN REMOVE AND TERMINATE
    IF(J.EQ.IFIRST) GO TO 2004
    DO K=IFIRST,J-1
    KK=ICA(K-1)
    KKK=ICA(K)
    S1=SIDGR1(KK,KKK)
    S2=SIDGR2(KK,KKK)
    S3=SIDGR3(KK,KKK)
    CALL REMOVE(XYZ,INDGL(K),XNEW(K),YNEW(K),ZNEW(K),S1,S2,S3)
    ENDDO
2004                                ICA(IFIRST)=WI
                                    ICA(JL)=WJ

    DO I=IFIRST,ILAST
    II=ICA(I-1)
    JJJ=ICA(I)

    S1=SIDGR1(II,JJJ)
    S2=SIDGR2(II,JJJ)
    S3=SIDGR3(II,JJJ)

    CALL setin(XYZ,INDGL(I),X(I),Y(I),Z(I),S1,S2,S3,I)
    ENDDO
    GO TO 7001
    ELSE
C                                     SET NEW BEAD
    CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
    ENDDO
    ENDDIF

    ENDDO
C                                     THE NEW STRING KEEPS EXCLUDED VOLUME

C                                     COMPUTATION OF ENERGY OF THE NEW CONFORMATION AND REMOVE STRING

    ENEW=0.
    ER=0.
    E=0.
    DO J=IFIRST,ILAST
    I=J-1
    II=ICA(I)
    JJ=ICA(J)
    XJ=XNEW(J)

```

YJ=YNEW(J)

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```

      ZJ=ZNEW(J)
      S1=SIDGR1(II,JJ)
      S2=SIDGR2(II,JJ)
      S3=SIDGR3(II,JJ)
      JCONF=ICONF(II,JJ)
      ENEW=ENEW+AC(J,JCONF)+APH(II,JJ,ICA(J+1),J)
C                                     INTERACTIONS OF SIDE GROUPS

      IX=XJ+S1X(ii,jj)
      IY=YJ+S1Y(ii,jj)
      IZ=ZJ+S1Z(ii,jj)
      E=E+ERG(XYZ,INDGL(J),AM,IX,IY,IZ,J)

C                                     COOPERATIVE AND HYDROGEN BOND
      E=E+EHB(XYZ,ICA,PRODV,XJ,YJ,ZJ,J,AHB)
C                                     REPULSIVE INTERACTIONS
      ER=ER+EREPU(L(XYZ,XJ,YJ,ZJ,AREP)
      CALL REMOVE(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3)
      ENDDO
      ENEW=ENEW+APH(ICA(IFIRST-2),ICA(IFA),ICA(IFIRST),IFA)
      ENEW=ENEW+E+ER
C
C
C
C
C                                     COMPUTATION OF THE OLD ENERGY AND SETIN OF THE CHAIN PIECE
C
      THE OLD VECTORS
      ICA(IFIRST)=WI
      ICA(JL)=WJ
      EOLD=0.
      ER=0.
      E=0.
      DO J=IFIRST,ILAST
      XJ=X(J)
      YJ=Y(J)
      ZJ=Z(J)
      II=ICA(J-1)
      JJJ=ICA(J)
      S1=SIDGR1(II,JJJ)
      S2=SIDGR2(II,JJJ)
      S3=SIDGR3(II,JJJ)
      S4=SIDGR4(ii,jjj)
C
C      tx=tlx(s4)
C      ty=tly(s4)
C      tz=tlz(s4)
C      CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
C
      JCONF=ICONF(II,JJJ)
      EOLD=EOLD+AC(J,JCONF)+APH(II,JJJ,ICA(J+1),J)
C                                     INTERACTIONS OF SIDE GROUPS

      IX=XJ+S1X(ii,jjj)
      IY=YJ+S1Y(ii,jjj)
      IZ=ZJ+S1Z(ii,jjj)

```

```

E=E+ERG(XYZ,INDGL(J),AM,IX,IY,IZ,J)

C                                     COOPERATIVE AND HYDROGEN BOND
E=E+EHB(XYZ,ICA,PRODV,XJ,YJ,ZJ,J,AHB)
C                                     REPULSIVE INTERACTIONS
ER=ER+EREPUL(XYZ,XJ,YJ,ZJ,AREP)
ENDDO
EOLD=EOLD+APH(ICA(IFIRST-2),ICA(IFA),ICA(IFIRST),IFA)
EOLD=EOLD+E+ER

C
C METROPOLIS CRITERION
C
DE=ENEW-EOLD
IF(EXP(-DE*af).GT.vaxran(rn3)) THEN
C                                     ACCEPTED
    QROT=QROT+1
    ENERG=ENERG+DE
    DO J=IFIRST, ILAST
        II=ICA(J-1)
        JJ=ICA(J)
        S1=SIDGR1(II,JJ)
        S2=SIDGR2(II,JJ)
        S3=SIDGR3(II,JJ)

        CALL REMOVE(XYZ,INDGL(J),X(J),Y(J),Z(J),S1,S2,S3)
    ENDDO

C                                     THE NEW VECTORS
    ICA(IFIRST)=WJ
    ICA(JL)=WI
    DO J=IFIRST, ILAST
        XJ=XNEW(J)
        YJ=YNEW(J)
        ZJ=ZNEW(J)
        X(J)=XJ
        Y(J)=YJ
        Z(J)=ZJ
        II=ICA(J-1)
        JJ=ICA(J)
        S1=SIDGR1(II,JJ)
        S2=SIDGR2(II,JJ)
        S3=SIDGR3(II,JJ)
        CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
    ENDDO
ENDIF

7001 DO 7000 IDUMA=1,LENF4
      ICLOCK=ICLOCK+1
C
C I=INT(vaxran(rn1)*AL4)+2
C      RUNS FROM 2 TO LENF-3 (VECTOR INDEX RUNS FROM 1 TO LENF-1)
J=I+1
KINK=MOD(ICLOCK,5)+1
C      DEFINES KIND OF KINK OF THE VECTORS I-J

```

IV=ICA(I)

JV=ICA(J)
IIV=VECT1(IV,JV,KINK)
IP=I-1
IPV=ICA(IP)
IF(.NOT.GOODC(IPV,IIV)) GO TO 7000
JN=J+1
JNV=ICA(JN)
JJV=VECT2(IV,JV,KINK)
IF(.NOT.GOODC(JJV,JNV)) GO TO 7000

C
C

CONFORMATION IS OK - CHECK THE EXCLUDE VOLUME

C

REMOVE THE STRING

JL=J
ifirst=i
ilast=jn
DO K=IFIRST,ILAST
II=ICA(K-1)
KK=ICA(K)
IKS1=SIDGR1(II,KK)
IKS2=SIDGR2(II,KK)
IKS3=SIDGR3(II,KK)
XJ=X(K)
YJ=Y(K)
ZJ=Z(K)
CALL REMOVE(XYZ,INDGL(K),XJ,YJ,ZJ,IKS1,IKS2,IKS3)
ENDDO

C
C
- C

SETIN AND EXCLUDED
VOLUME TEST

THE NEW VECTORS
ICA(IFIRST)=iiv
ICA(JL)=jjv

IFA=IFIRST-1
XJ=X(IFA)
YJ=Y(IFA)
ZJ=Z(IFA)
DO J=IFIRST,ILAST
II=ICA(J-1)
JJJ=ICA(J)
XJ=XJ+VX(II)
YJ=YJ+VY(II)
ZJ=ZJ+VZ(II)
XNEW(J)=XJ
YNEW(J)=YJ
ZNEW(J)=ZJ
S1=SIDGR1(II,JJJ)
S2=SIDGR2(II,JJJ)

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C

```

S3=SIDGR3(II,JJJ)
IF(LOOK(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3)) THEN
    THEN REMOVE AND TERMINATE
    IF(J.EQ.IFIRST) GO TO 2204
    DO K=IFIRST,J-1
    KK=ICA(K-1)
    KKK=ICA(K)

```

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```

S1=SIDGR1(KK,KKK)
S2=SIDGR2(KK,KKK)
S3=SIDGR3(KK,KKK)
CALL REMOVE(XYZ,INDGL(K),XNEW(K),YNEW(K),ZNEW(K),S1,S2,S3)
ENDDO
ICA(IFIRST)=IV
ICA(JL)=JV

```

```

DO I=IFIRST,ILAST
II=ICA(I-1)
JJJ=ICA(I)

```

```

S1=SIDGR1(II,JJJ)
S2=SIDGR2(II,JJJ)
S3=SIDGR3(II,JJJ)

```

```

CALL setin(XYZ,INDGL(I),X(I),Y(I),Z(I),S1,S2,S3,I)
ENDDO

```

```

GO TO 7000
ELSE

```

C

```

CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
ENDIF

```

ENDDO

THE NEW STRING KEEPS EXCLUDED VOLUME

C

C

C

C

C

COMPUTATION OF ENERGY OF THE NEW CONFORMATION AND REMOVE STRING

```

ENEW=0.
ER=0.
E=0.
DO J=IFIRST,ILAST
I=J-1
II=ICA(I)
JJ=ICA(J)

```

```

XJ=XNEW(J)
YJ=YNEW(J)
ZJ=ZNEW(J)
S1=SIDGR1(II,JJ)
S2=SIDGR2(II,JJ)
S3=SIDGR3(II,JJ)

```

```

C                                     ROTATIONAL CONTRIBUTION
JCONF=ICONF(II,JJ)
C ENEW=ENEW+AC(J,JCONF)+APH(II,JJ,ICA(J+1),J)
                                     INTERACTIONS OF SIDE GROUPS
IX=XJ+S1X(ii,jj)
IY=YJ+S1Y(ii,jj)
IZ=ZJ+S1Z(ii,jj)
E=E+ERG(XYZ,INDGL(J),AM,IX,IY,IZ,J)

C                                     COOPERATIVE AND HYDROGEN BOND
E=E+EHB(XYZ,ICA,PRODV,XJ,YJ,ZJ,J,AHB)
C                                     REPULSIVE INTERACTIONS

ER=ER+EREPUL(XYZ,XJ,YJ,ZJ,AREP)
CALL REMOVE(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3)
ENDDO
ENEW=ENEW+APH(ICA(IFIRST-2),ICA(IPA),ICA(IFIRST),IPA)
ENEW=ENEW+E+ER

C
C
C
C
C COMPUTATION OF THE OLD ENERGY AND SETIN OF THE CHAIN PIECE
C
C THE OLD VECTORS
ICA(IFIRST)=IV
ICA(JL)=JV
EOLD=0.
ER=0.
E=0.
DO J=IFIRST,ILAST
XJ=X(J)
YJ=Y(J)
ZJ=Z(J)
II=ICA(J-1)
JJJ=ICA(J)
S1=SIDGR1(II,JJJ)
S2=SIDGR2(II,JJJ)
S3=SIDGR3(II,JJJ)
S4=SIDGR4(II,JJJ)
C tx=tlx(s4)
C ty=tly(s4)
C tz=tlz(s4)
CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
C
C JCONF=ICONF(II,JJJ)
EOLD=EOLD+AC(J,JCONF)+APH(II,JJJ,ICA(J+1),J)
C                                     INTERACTIONS OF SIDE GROUPS
IX=XJ+S1X(ii,jjj)

```

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```

      IY=YJ+S1Y(ii,jjj)
      IZ=ZJ+S1Z(ii,jjj)
      E=E+ERG(XYZ,INDGL(J),AM,IX,IY,IZ,J)

C      COOPERATIVE AND HYDROGEN BOND
      E=E+EHF(XYZ,ICA,PRODV,XI,IJ,ZI,J,AHB)
C      REPULSIVE INTERACTIONS
      ER=ER+EREPUL(XYZ,XJ,YJ,ZJ,AREP)
      ENDDO
      EOLD=EOLD+APH(ICA(IFIRST-2),ICA(IFA),ICA(IFIRST),IFA)
      EOLD=EOLD+E+ER

C      METROPOLIS CRITERION
C
C      DE=ENEW-EOLD
      IF(EXP(-DE).GT.vaxran(rn3)) THEN
C
C          ACCEPTED
          iflip(iconf(iv,jv),kink)=iflip(iconf(iv,jv),kink)+1

      OKINK=OKINK+1
      ENERG=ENERG+DE
      DO J=IFIRST, ILAST
        II=ICA(J-1)
        JJ=ICA(J)
        S1=SIDGR1(II,JJ)
        S2=SIDGR2(II,JJ)
        S3=SIDGR3(II,JJ)

        CALL REMOVE(XYZ,INDGL(J),X(J),Y(J),Z(J),S1,S2,S3)
      ENDDO
C      THE NEW VECTORS
      ICA(IFIRST)=IIV
      ICA(JL)=JJV
      DO J=IFIRST, ILAST
        XJ=XNEW(J)
        YJ=YNEW(J)
        ZJ=ZNEW(J)
        X(J)=XJ
        Y(J)=YJ
        Z(J)=ZJ
        II=ICA(J-1)
        JJ=ICA(J)
        S1=SIDGR1(II,JJ)
        S2=SIDGR2(II,JJ)
        S3=SIDGR3(II,JJ)
        CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,S1,S2,S3,J)
      ENDDO
      ENDIF
C

```

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```

7000  CONTINUE
C      idummy=1
C      if(idummy .eq. 1) go to 7770
C
C      END FLIPS (TWO BONDS REARRANGEMENTS)
C
C      N-TERMINUS (TAIL)
C
C      JV3=ICA(3)
60     NV2=INT(vaxran(rn1)*24.)+1
      IF(.NOT.GOODC(NV2,JV3)) GO TO 60
61     NV1=INT(vaxran(rn3)*24.)+1
      IF(.NOT.GOODC(NV1,NV2)) GO TO 61
C      CONFORMATION IS OK. CHECK THE EXCLUDED VOLUME
      CALL REMOVE(XYZ,INDGL(1),X(1),Y(1),Z(1),13,13,13)
      ICA1=ICA(1)
      ICA2=ICA(2)
      PK21=SIDGR1(ICA1,ICA2)
      PK22=SIDGR2(ICA1,ICA2)
      PK23=SIDGR3(ICA1,ICA2)

C      *****
C      CALL REMOVE(XYZ,INDGL(2),X(2),Y(2),Z(2),PK21,PK22,PK23)
C      CHECK THE ROTATION OF SIDE GROUP ON THIRD BEAD

C
C      8/19/89
C      oninvoke if no glycines are here
C
C      if(indgl(3) .eq.0) go to 3040
      PK31=SIDGR1(ICA2,JV3)
      PK32=SIDGR2(ICA2,JV3)
      PK33=SIDGR3(ICA2,JV3)
C      *****
C      *****

      SX1=X(3)+STLX(PK31)
      SX2=X(3)+STLX(PK32)
      SX3=X(3)+STLX(PK33)
      SY1=Y(3)+STLY(PK31)
      SY2=Y(3)+STLY(PK32)
      SY3=Y(3)+STLY(PK33)
      SZ1=Z(3)+STLZ(PK31)
      SZ2=Z(3)+STLZ(PK32)
      SZ3=Z(3)+STLZ(PK33)
      XYZ(SX1,SY1,SZ1)=0
      XYZ(SX2,SY2,SZ2)=0
      XYZ(SX3,SY3,SZ3)=0
      xone=(sx1+sx2+sx3-x(3))/2
      yone=(sy1+sy2+sy3-y(3))/2
      zone=(sz1+sz2+sz3-z(3))/2

```



```
xyz(xone,yone,zone)=0
```

```

NK31=SIDGR1(NV2,JV3)
NK32=SIDGR2(NV2,JV3)
NK33=SIDGR3(NV2,JV3)
c  s4=sidgr4(nv2,jv3)
c  tx=tlx(s4)
c  ty=tly(s4)
c  tz=tlz(s4)
c  *****
MX1=X(3)+STLX(NK31)
MX2=X(3)+STLX(NK32)
MX3=X(3)+STLX(NK33)
MY1=Y(3)+STLY(NK31)
MY2=Y(3)+STLY(NK32)
MY3=Y(3)+STLY(NK33)
MZ1=Z(3)+STLZ(NK31)
MZ2=Z(3)+STLZ(NK32)
MZ3=Z(3)+STLZ(NK33)
IF(XYZ(MX1,MY1,MZ1).NE.0) GO TO 64
IF(XYZ(MX2,MY2,MZ2).NE.0) GO TO 64
IF(XYZ(MX3,MY3,MZ3).NE.0) GO TO 64
    mxone=(mx1+mx2+mx3-x(3))/2
    myone=(my1+my2+my3-y(3))/2
    mzone=(mz1+mz2+mz3-z(3))/2
    if(xyz(mxone,myone,mzone).ne.0) go to 64

XYZ(MX1,MY1,MZ1)--1
XYZ(MX2,MY2,MZ2)--1
XYZ(MX3,MY3,MZ3)--1
xyz(mxone,myone,mzone)=3

```

```

- c...
c  end of check of sidechain conformation if sidechain there is not
c  a glycine.
3040 continue
c  NK21=SIDGR1(NV1,NV2)
c  NK22=SIDGR2(NV1,NV2)
c  NK23=SIDGR3(NV1,NV2)
c  *****
    WX2=VX(NV2)
    WY2=VY(NV2)
    WZ2=VZ(NV2)
X2=X(3)-WX2
Y2=Y(3)-WY2
Z2=Z(3)-WZ2
    IF(LOOK(XYZ,INDGL(2),X2,Y2,Z2,NK21,NK22,NK23)) GO TO 63
WX1=VX(NV1)
WY1=VY(NV1)
WZ1=VZ(NV1)
    X1=X2-WX1

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```

      Y1=Y2-WY1
      Z1=Z2-WZ1
      IF(LOOK(XYZ,INDGL(1),X1,Y1,Z1,13,13,13)) GO TO 63
C
C.....OLD CONFORMATIONAL ENERGY (LOCAL)
C
      IC3=ICONF(ICA2,JV3)
      IC2=ICONF(ICA1,ICA2)
      COLD=AC(2,IC2)+AC(3,IC3)
C      s4=sidgr4(ical,ica2)
C      tx=tlx(s4)
C      ty=tly(s4)
C      tz=tlz(s4)
C      PK23=SIDGR3(ICA1,ICA2)
C      ipk21=ihan1(ical,ica2)
      QX1=X(2)+slx(ical,ica2)
      QY1=Y(2)+sly(ical,ica2)
      QZ1=Z(2)+slz(ical,ica2)

      SuX1=X(3)+SlX(ica2,jv3)
      SuY1=Y(3)+SlY(ica2,jv3)
      SuZ1=Z(3)+SlZ(ica2,jv3)

      EOLD=COLD
      *      +ERG(XYZ,INDGL(3),AM,SuX1,SuY1,SuZ1,3)
C      *      +ERG(XYZ,INDGL(3),AM,SuX3,SuY3,SuZ3,3)
      *      +ERG(XYZ,INDGL(2),AM,QX1,QY1,QZ1,2)

      *      +APH(ICA1,ICA2,JV3,2)+APH(ICA2,JV3,ICA(4),3)
      *      +EREPUL(XYZ,X(2),Y(2),Z(2),AREP)
      *      +EHB(XYZ,ICA,PRODV,X(3),Y(3),Z(3),3,AHB)
      *      +EHB(XYZ,ICA,PRODV,X(2),Y(2),Z(2),2,AHB)

C
C.....NEW CONFORMATIONAL ENERGY (LOCAL)
C
      ICA(1)=NV1
      ICA(2)=NV2

      IC3=ICONF(NV2,JV3)
      IC2=ICONF(NV1,NV2)
      CNEW=AC(2,IC2)+AC(3,IC3)
C      *****
C      s4=sidgr4(nv1,nv2)
C      tx=tlx(s4)
C      ty=tly(s4)

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```

c      tz=tlz(s4)

      LX1=X2+S1x(nv1,nv2)
      LY1=Y2+S1y(nv1,nv2)
      LZ1=Z2+S1z(nv1,nv2)

      MuX1=X(3)+S1X(nv2,jv3)
      MuY1=Y(3)+S1y(nv2,jv3)
      MuZ1=Z(3)+S1z(nv2,jv3)

      ENEW=CNEW
      *      +ERG(XYZ,INDGL(3),AM,muX1,muY1,MuZ1,3)
      *
      *      +ERG(XYZ,INDGL(2),AM,LX1,LY1,LZ1,2)
      *
      *      -APH(NV1,NV2,JV3,2)+APH(NV2,JV3,ICA(4),3)
      *      -EREPUL(XYZ,X2,Y2,Z2,AREP)
      *      -EHB(XYZ,ICA,PRODV,X(3),Y(3),Z(3),3,AHB)
      *      +EHB(XYZ,ICA,PRODV,X2,Y2,Z2,2,AHB)
c.....METROPOLIS CRITERION
c
      DE=ENEW-EOLD
      IF(EXP(-DE).LT.vaxran(rn3)) GO TO 63
      ENERG=ENERG-DE

c
c      SET-IN THE NEW CONFORMATION OF THE TAIL
      X(1)=X1
      Y(1)=Y1
      Z(1)=Z1
      X(2)=X2
      Y(2)=Y2
      Z(2)=Z2
      CALL setin(XYZ,INDGL(1),X1,Y1,Z1,13,13,13,2)
      CALL SETIN(XYZ,INDGL(2),X2,Y2,Z2,NK21,NK22,NK23,2)
      QEND=QEND-1
      GO TO 79

c
c      SET-IN THE OLD CONFORMATION OF THE TAIL
63  if(indgl(3).eq.0) go to 641
      XYZ(MX1,MY1,MZ1)=0
      XYZ(MX2,MY2,MZ2)=0
      XYZ(MX3,MY3,MZ3)=0

      xyz(mxone,myone,mzone)=0

64  XYZ(SX1,SY1,SZ1)--1
      XYZ(SX2,SY2,SZ2)--1
      XYZ(SX3,SY3,SZ3)--1

```

82

```

xyz(xone,yone,zone)=3
641 continue
      ICA(1)=ICA1
      ICA(2)=ICA2
      CALL setin(XYZ,INDGL(1),X(1),Y(1),Z(1),13,13,13,1)
      CALL SETIN(XYZ,INDGL(2),X(2),Y(2),Z(2),PK21,PK22,PK23,2;
C
C      C-TERMINUS (HEAD)
C
79 JV3=ICA(LENF3)
80 NV2=INT(vaxran(rn1)*24.)+1
   IF(.NOT.GOODC(JV3,NV2)) GO TO 80
81 NV1=INT(vaxran(rn2)*24.)+1
   IF(.NOT.GOODC(NV2,NV1)) GO TO 81
C      CONFORMATION IS OK. CHECK THE EXCLUDED VOLUME
      CALL REMOVE(XYZ,INDGL(LENF),X(LENF),Y(LENF),Z(LENF),13,13,13;
      ICA2=ICA(LENF2)
      ICA1=ICA(LENF1)
      PK21=SIDGR1(ICA2,ICA1)
      PK22=SIDGR2(ICA2,ICA1)
      PK23=SIDGR3(ICA2,ICA1)
C
      IIII=INDGL(LENF1)
      CALL REMOVE(XYZ,IIII,X(LENF1),Y(LENF1),Z(LENF1),PK21,PK22,PK23;
C      CHECK THE ROTATION OF SIDE GROUP ON THIRD BEAD
      if(indgl(lenf2).eq. 0) go to 6045
      PK31=SIDGR1(JV3,ICA2)
      PK32=SIDGR2(JV3,ICA2)
      PK33=SIDGR3(JV3,ICA2)

      SX1=X(LENF2)+STLX(PK31)
      SY1=Y(LENF2)+STLY(PK31)
      SZ1=Z(LENF2)+STLZ(PK31)
      SX2=X(LENF2)+STLX(PK32)
      SY2=Y(LENF2)+STLY(PK32)
      SZ2=Z(LENF2)+STLZ(PK32)
      SX3=X(LENF2)+STLX(PK33)
      SY3=Y(LENF2)+STLY(PK33)
      SZ3=Z(LENF2)+STLZ(PK33)
      XYZ(SX1,SY1,SZ1)=C
      XYZ(SX2,SY2,SZ2)=0
      XYZ(SX3,SY3,SZ3)=0
      xone=(sx1+sx2+sx3-x(lenf2))/2
      yone=(sy1+sy2+sy3-y(lenf2))/2
      zone=(sz1+sz2+sz3-z(lenf2))/2
      xyz(xone,yone,zone)=0

      NK31=SIDGR1(JV3,NV2)
      NK32=SIDGR2(JV3,NV2)

      NK33=SIDGR3(JV3,NV2);

```

```

MX1=X(LENF2)+STLX(NK31)
MY1=Y(LENF2)+STLY(NK31)
MZ1=Z(LENF2)+STLZ(NK31)
MX2=X(LENF2)+STLX(NK32)
MY2=Y(LENF2)+STLY(NK32)
MZ2=Z(LENF2)+STLZ(NK32)
MX3=X(LENF2)+STLX(NK33)
MY3=Y(LENF2)+STLY(NK33)
MZ3=Z(LENF2)+STLZ(NK33)

IF(XYZ(MX1,MY1,MZ1).NE.0) GO TO 84
IF(XYZ(MX2,MY2,MZ2).NE.0) GO TO 84
IF(XYZ(MX3,MY3,MZ3).NE.0) GO TO 84
    mxone=(mx1+mx2+mx3-x(lenf2))/2
    myone=(my1+my2+my3-y(lenf2))/2
    mzone=(mz1+mz2+mz3-z(lenf2))/2
    if(xyz(mxone,myone,mzone).ne.0) go to 84
XYZ(MX1,MY1,MZ1)--1
XYZ(MX2,MY2,MZ2)--1
XYZ(MX3,MY3,MZ3)--1
xyz(mxone,myone,mzone)=lenf2
C....
6045 continue
NK21=SIDGR1(NV2,NV1)
NK22=SIDGR2(NV2,NV1)
NK23=SIDGR3(NV2,NV1)
    WX2=VX(NV2)
    WY2=VY(NV2)
    WZ2=VZ(NV2)
X2=X(LENF2)+WX2
Y2=Y(LENF2)+WY2
Z2=Z(LENF2)+WZ2
    IF(LOOK(XYZ,I111,X2,Y2,Z2,NK21,NK22,NK23)) GO TO 83
WX1=VX(NV1)
WY1=VY(NV1)
WZ1=VZ(NV1)
    X1=X2+WX1
    Y1=Y2+WY1
    Z1=Z2+WZ1
    IF(LOOK(XYZ,INDGL(LENF),X1,Y1,Z1,I3,I3,I3)) GO TO 83

C.....OLD CONFORMATIONAL ENERGY (LOCAL)
C
IC3=ICONF(JV3,ICA2)
IC2=ICONF(ICA2,ICA1)
COLD=AC(LENF1,IC2)+AC(LENF2,IC3)
C
s4=sidgr4(ica2,ical)
C
tx=tlx(s4)
C
ty=tly(s4)
C
tz=tlz(s4)
C
QX1=X(lenf1)+Slx(ica2,ical)
QY1=Y(lenf1)+Sly(ica2,ical)
QZ1=Z(lenf1)+Slz(ica2,ical)

```

```

      SuX1=X(LENF2)+SlX(jv3,ica2)
      Suy1=y(LENF2)+Sly(jv3,ica2)
      Suz1=z(LENF2)+Slz(jv3,ica2)

C      QX1=X(LENF1)+STLX(PK21)*
C      QY1=Y(LENF1)+STLY(PK21)
C      QZ1=Z(LENF1)+STLZ(PK21)
C      QX2=X(LENF1)+STLX(PK22)
C      QY2=Y(LENF1)+STLY(PK22)
C      QZ2=Z(LENF1)+STLZ(PK22)
C      QX3=X(LENF1)+STLX(PK23)
C      QY3=Y(LENF1)+STLY(PK23)
C      QZ3=Z(LENF1)+STLZ(PK23)
C      ECLD=COLD
      *      -ERG(XYZ,INDGL(LENF2),AX,SuX1,Suy1,Suz1,LENF2)

      *      -APH(ICA(LENF4),JV3,ICA2,LENF3)
      *      -APH(JV3,ICA2,ICA1,LENF2)
      *      -ERG(XYZ,IIIE,AX,QX1,QY1,QZ1,LENF1)

      *      +EREPUL(XYZ,X(LENF1),Y(LENF1),Z(LENF1),AREP)
      *      +EHB(XYZ,ICA,PRODV,X(LENF2),Y(LENF2),Z(LENF2),LENF2,AHB)
      *      +EHB(XYZ,ICA,PRODV,X(LENF1),Y(LENF1),Z(LENF1),LENF1,AHB)

C.....NEW CONFORMATIONAL ENERGY (LOCAL)
C
      ICA(LENF1)=NV1
      ICA(LENF2)=NV2

      IC3=ICONF(JV3,NV2)
      IC2=ICONF(NV2,NV1)
      CNEW=AC(LENF1,IC2)+AC(LENF2,IC3)

      LX1=X2+slx(nv2,nv1)
      LY1=Y2+sly(nv2,nv1)
      LZ1=Z2-slz(nv2,nv1)

      MuX1=X(lenf2)+Slx(jv3,nv2)
      Muy1=y(lenf2)+Sly(jv3,nv2)
      Muz1=z(lenf2)+Slz(jv3,nv2)

C      LX1=X2+STLX(NK21)
C      LY1=Y2+STLY(NK21)
C      LZ1=Z2+STLZ(NK21)
C      LX2=X2+STLX(NK22)
C      LY2=Y2+STLY(NK22)
C      LZ2=Z2+STLZ(NK22)

```

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C LX3=X2-STLX(NK23)

C LY3=Y2-STLY(NK23)

C LZ3=Z2-STLZ(NK23)

ENEW=CNEW

* +ERG(XYZ,INDGL(LENF2),AM,muX1,muY1,muZ1,LENF2)

* -APH(ICA(LENF4),JV3,NV2,LENF3)

* -APH(JV3,NV2,NV1,LENF2)

* -ERG(XYZ,IIII,AX,LX1,LX1,LX1,LENF1)

* -EREPUL(XYZ,X2,Y2,Z2,AREP)

* -EHB(XYZ,ICA,PRODV,X(LENF2),Y(LENF2),Z(LENF2),LENF2,AHB)

* -EHB(XYZ,ICA,PRODV,X2,Y2,Z2,LENF1,AHB)

C
C.....METROPOLIS CRITERION

C

DE=ENEW-EOLD

IF(EXP(-DE).LT.vaxran(rn3)) GO TO 83

ENERG=ENERG+DE

C

C

SET-IN THE NEW CONFORMATION OF THE HEAD

X(LENF)=X1

Y(LENF)=Y1

Z(LENF)=Z1

X(LENF1)=X2

Y(LENF1)=Y2

Z(LENF1)=Z2

CALL setin(XYZ,INDGL(LENF),X1,Y1,Z1,13,13,13,1)

CALL SETIN(XYZ,IIII,X2,Y2,Z2,NK21,NK22,NK23,LENF1)

QEND=QEND+1

GO TO 7007

C

C

83

SET-IN THE OLD CONFORMATION OF THE TAIL

if(indgl(lenf2).eq. 0) go to 675

XYZ(MX1,MY1,MZ1)=0

XYZ(MX2,MY2,MZ2)=0

XYZ(MX3,MY3,MZ3)=0

xyz(mxone,myone,mzone)=0

84

XYZ(SX1,SY1,SZ1)--1

XYZ(SX2,SY2,SZ2)--1

XYZ(SX3,SY3,SZ3)--1

xyz(xone,yone,zone)=lenf2

675

continue

```

      ICA(LENF1)=ICA1
      ICA(LENF2)=ICA2
      CALL setin(XYZ,INDGL(LENF),X(LENF),Y(LENF),Z(LENF),13,13,13,1)
      CALL SETIN(XYZ,IIII,X(LENF1),Y(LENF1),Z(LENF1),PK21,PK22,PK23,LENF1) .

```

C
C

WAVE LINE MOTION OF THE CHAIN FRAGMENT, VARIOUS CONFORMATIONS

C
7007

```

      I=INT(AL9*vaxran(rn2))-3
      if( vaxran(rn3) .gt. .01) then
        af=1.d0
      else
        af =ah
      end if

```

C
C
C
C
C

I+2 IS THE CENTRAL BEAD OF THE PIECE TO BE CUT-OFF
 JJ - IS THE CENTRAL ONE OF THE PIECE TO BE CONSTRUCTED
 SEARCH FOR U-SHAPED (OF VARIOUS WIDTH) CONFORMATIONS

```

      IV2=ICA(I)
      IV5=ICA(I+3)
      VX2=VX(IV2)
      VX5=VX(IV5)
      IF(VX2.NE.-VX5) GO TO 7770
      VY2=VY(IV2)
      VY5=VY(IV5)
      IF(VY2.NE.-VY5) GO TO 7770
      VZ2=VZ(IV2)
      VZ5=VZ(IV5)
      IF(VZ2.NE.-VZ5) GO TO 7770

```

C

```

      IVA=MOD(ICLOCK,WAVEL;
      MIX=-MIX

```

LOOK FOR THE SECOND END

```

      JJ=I+2-MIX*(5+IVA)

```

```

      IF(JJ.LT.4.OR.JJ.GT.LENF3) GO TO 7770

```

C
C

ACCEPTED DOWN THE CHAIN CHOICE
 I-END CONSTRUCTION (CUT-OFF)

```

      IV3=ICA(I+2)
      IV4=ICA(I+1)

```

C

KINK PERFORMEED (KINK=-1)

```

      IV1=ICA(I-1)
      I4=I+4
      IV6=ICA(I4)

```

C

```

      IF(GOODC(IV1,IV3).AND.GOODC(IV4,IV6)) GO TO 200

```

ELSE TRY KINK FLIP OF THE TOP

```

      INV3=VECT1(IV3,IV4,KINK)
      IV4=VECT2(IV3,IV4,KINK)
      IV3=INV3
      IF(.NOT.GOODC(IV1,IV3)) GO TO 7770

```


87

IF(.NOT.GOODC(IV4,IV6)) GO TO 7770

C CONSTRUCT THE NEW JJ- END

```

200 J1=JJ-1
    JV1=ICA(J1)
    JV2=ICA(JJ)
    JVL=ICA(JJ-2)
    J3=JJ+1
    JVP=ICA(J3)
201 V=INT(vaxran(rn1)*24.)+1
    IF(.NOT.GOODC(JVL,V)) GO TO 201
    WVX=VX(V)
    WVY=VY(V)

```

```

WVZ=VZ(V)
VM=VECTOR(-WVX,-WVY,-WVZ)
IF(.NOT.GOODC(VM,JVP)) GO TO 201

```

TOP OF THE JJ-END CONSTRUCTED

```

    DO KINK=1,5
    JN1=VECT1(JV1,JV2,KINK)
    IF(GOODC(V,JN1)) THEN
        JN2=VECT2(JV1,JV2,KINK)
        IF(GOODC(JN2,VM)) GO TO 202
    END IF

```

ENDDO

GO TO 7770

MODIFICATION OF THE BOND STRING ARRAY ICA. STORE THE OLD ONE

```

202 IF(MIX.GT.0) THEN
    IFIRST=1
    ILAST=J3
    ELSE
    IFIRST=J1
    ILAST=I4
    ENDIF

```

```

DO J=IFIRST-1,ILAST
    ICAO(J)=ICA(J)
ENDDO

```

```

C IF(MIX.GT.0) THEN
    ICA(I)=IV3
    ICA(I+1)=IV4
    DO J=I4,JJ-2
    ICA(J-2)=ICAO(J)
    ENDDO
    ICA(JJ)=VM
    ICA(J1)=JN2
    ICA(J1-1)=JN1
    ICA(J1-2)=V

```

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```

ELSE
    ICA(I4-1)=IV4
    ICA(I4-2)=IV3
    DO J=J3,I-1
        ICA(J-2)=ICAO(J)
    ENDDO
    ICA(J1)=V
    ICA(JJ)=JN1
    ICA(J3)=JN2
    ICA(J3+1)=VM

```

END IF

C

REMOVE THE STRING

```

DO K=IFIRST,ILAST
    II=ICAO(K-1)
    KK=ICAO(K)
    IKS1=SIDGR1(II,KK)
    IKS2=SIDGR2(II,KK)
    IKS3=SIDGR3(II,KK)
    XJ=X(K)

```

```

YJ=Y(K)
ZJ=Z(K)
CALL REMOVE(XYZ,INDGL(K),XJ,YJ,ZJ,IKS1,IKS2,IKS3)
ENDDO

```

C
CSETIN AND EXCLUDED
VOLUME TEST

IFA=IFIRST-1

```

XJ=X(IFA)
YJ=Y(IFA)
ZJ=Z(IFA)
DO J=IFIRST,ILAST
    II=ICA(J-1)
    JJJ=ICA(J)
    XJ=XJ+VX(II)
    YJ=YJ+VY(II)
    ZJ=ZJ+VZ(II)
    XNEW(J)=XJ
    YNEW(J)=YJ
    ZNEW(J)=ZJ
    IKS1=SIDGR1(II,JJJ)
    IKS2=SIDGR2(II,JJJ)
    IKS3=SIDGR3(II,JJJ)

```

C

```

IF(LOCK(XYZ,INDGL(J),XJ,YJ,ZJ,IKS1,IKS2,IKS3)) THEN
    THEN REMOVE AND TERMINATE
IF(J.EQ.IFIRST) GO TO 204
DO K=IFIRST,J-1
    KK=ICA(K-1)
    KKK=ICA(K)
    IKS1=SIDGR1(KK,KKK)

```

```

                IKS2=SIDGR2(KK,KKK)
                IKS3=SIDGR3(KK,KKK)
CALL REMOVE(XYZ,INDGL(K),XNEW(K),YNEW(K),ZNEW(K),IKS1,IKS2,IKS3)
                ENDDO
204                DO I=IFIRST,ILAST
                    ICA(I)=ICAO(I)
                    II=ICA(I-1)

                    JJJ=ICA(I)
                    IKS1=SIDGR1(II,JJJ)
                    IKS2=SIDGR2(II,JJJ)
                    IKS3=SIDGR3(II,JJJ)
CALL setin(XYZ,INDGL(I),X(I),Y(I),Z(I),IKS1,IKS2,IKS3,I)
                    ENDDO
                    GO TO 7770
                    ELSE
                                SET NEW BEAD
CALL SETIN(XYZ,INDGL(J),XJ,YJ,ZJ,IKS1,IKS2,IKS3,J)
                    ENDEF
ENDDO
                THE NEW STRING KEEPS EXCLUDED VOLUME

```

```

C
C
C
COMPUTATION OF ENERGY OF THE NEW CONFORMATION AND REMOVE STRING

```

```

ENew=0.
ER=0.
E=0.
DO J=IFIRST,ILAST
I=J-1
II=ICA(I)
JJ=ICA(J)
        XJ=XNEW(J)
        YJ=YNEW(J)
        ZJ=ZNEW(J)
IKS1=SIDGR1(II,JJ)
IKS2=SIDGR2(II,JJ)
IKS3=SIDGR3(II,JJ)

```

```

C
C
C
JCONF=ICONF(II,JJ)
ENew=ENew+AC(J,JCONF)+APH(II,JJ,ICA(J+1),J)
                                ROTATIONAL CONTRIBUTION
                                INTERACTIONS OF SIDE GROUPS
        IX1=XJ+S1X(II,JJ)
        IY1=YJ+S1Y(II,JJ)
        IZ1=ZJ+S1Z(II,JJ)

```

```

E=E+ERG(XYZ,INDGL(J),AX,IX1,IY1,IZ1,J)

C                                     COOPERATIVE AND HYDROGEN BOND
E=E+EHB(XYZ,ICA,PRODV,XJ,YJ,ZJ,J,AHB)
C                                     REPULSIVE INTERACTIONS
ER=ER+EREPUL(XYZ,XJ,YJ,ZJ,AREP)
CALL REMOVE(XYZ,INDGL(J),XJ,YJ,ZJ,IKS1,IKS2,IKS3)
ENDDO
ENEW=ENEW+APH(ICA(IFIRST-2),ICA(IFA),ICA(IFIRST),IFA)
ENEW=ENEW+E+ER

C
C
C
C
COMPUTATION OF THE OLD ENERGY AND SETIN OF THE CHAIN PIECE

DO J=IFIRST,ILAST
I=ICA(J)
ICA(J)=ICAO(J)
ICAO(J)=I
ENDDO
NEW ICA STORED IN ICAO AT THIS POINT

EOLD=0.
ER=0.
E=0.
DO J=IFIRST,ILAST
XJ=X(J)
YJ=Y(J)
ZJ=Z(J)
II=ICA(J-1)
JJJ=ICA(J)

IKS1=SIDGR1(II,JJJ)
IKS2=SIDGR2(II,JJJ)
IKS3=SIDGR3(II,JJJ)
s4=sidgr4(ii,jjj)
tx=tlx(s4)
ty=tly(s4)
tz=tlz(s4)
CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,IKS1,IKS2,IKS3,J)

JCONF=ICONF(II,JJJ)
EOLD=EOLD+AC(J,JCONF)+APH(II,JJJ,ICA(J+1),J)
INTERACTIONS OF SIDE GROUPS
IX1=XJ+Slx(ii,jjj)
IY1=YJ+Sly(ii,jjj)
IZ1=ZJ+Slz(ii,jjj)
E=E+ERG(XYZ,INDGL(J),AX,IX1,IY1,IZ1,J)

C
COOPERATIVE AND HYDROGEN BOND

```

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```

      E=E-EHB(XYZ,ICA,PRODV,XJ,YJ,ZJ,J,AHB)
C      REPULSIVE INTERACTIONS
      ER=ER+EREPUL(XYZ,XJ,YJ,ZJ,AREP)
      ENDDO
      EOLD=EOLD+APH(ICA(IFIRST-2),ICA(IFA),ICA(IFIRST),IFA)
      EOLD=EOLD+E+ER

C
C      METROPOLIS CRITERION
C
      DE=ENEW-EOLD
      IF(EXP(-DE*af).GT.vaxran(rn3)) THEN
C      ACCEPTED
          QWAVE=QWAVE+1
          ENERG=ENERG+DE
          DO J=IFIRST, ILAST
              II=ICA(J-1)
              JJ=ICA(J)
              IKS1=SIDGR1(II,JJ)
              IKS2=SIDGR2(II,JJ)
              IKS3=SIDGR3(II,JJ)
              CALL REMOVE(XYZ,INDGL(J),X(J),Y(J),Z(J),IKS1,IKS2,IKS3)
              ENDDO
              DO J=IFIRST, ILAST
                  XJ=XNEW(J)
                  YJ=YNEW(J)
                  ZJ=ZNEW(J)
                  X(J)=XJ
                  Y(J)=YJ
                  Z(J)=ZJ
                  II=ICAO(J-1)
                  JJ=ICAO(J)
                  IKS1=SIDGR1(II,JJ)
                  IKS2=SIDGR2(II,JJ)
                  IKS3=SIDGR3(II,JJ)
                  CALL setin(XYZ,INDGL(J),XJ,YJ,ZJ,IKS1,IKS2,IKS3,J)
                  ICA(J)=ICAO(J)

          ENDDO
      ENDIF
C
C      7770 CONTINUE
C
C      OPTIONAL NORMALISATION OF THE COORDINATES
      SX=0
      SY=0
      SZ=0
      DO I=1,LENF
          SX=SX+X(I)
          SY=SY+Y(I)
          SZ=SZ+Z(I)

```

```

      zt(i)=z(i)-szc
    end do
    write(13,*)(xt(i),yt(i),zt(i),i=1,lenf)

    R2=(X(LENF)-X(1))**2+(Y(LENF)-Y(1))**2+(Z(LENF)-Z(1))**2
    asumr2=asumr2+r2
    etot2=etot2+energ*energ
    etot=etot+energ
    AS2=0.
    SX=0
    SY=0
    SZ=0
    DO I=1,LENF
      SX=SX+X(I)
      SY=SY+Y(I)
      SZ=SZ+Z(I)
    ENDDO

    C
      ASX=FLOAT(SX)/LENF
      ASY=FLOAT(SY)/LENF
      ASZ=FLOAT(SZ)/LENF

      DO I=1,LENF
        BX=(ASX-X(I))**2
        BY=(ASY-Y(I))**2
        BZ=(ASZ-Z(I))**2
        AS2=AS2+BX+BY+BZ
      ENDDO
      AS2=AS2/LENF
      asums2=asums2+as2
    C
      insertion of the native contact pairs

      nt=0.d0
      nct=0.
      do 1400 i=2,lenf2
        k=i+1
        ii=ica(i-1)
        iii=ica(i)
        SX1=slx(ii,iii)-x(i)
        SY1=slx(ii,iii)-y(i)
        SZ1=slz(ii,iii)-z(i)
        DO 1400 J=K,LENF1
          C it is not counting the nearest1 down-the-chain neighbours, which may be
          C usefull for some purposes .....
          if(iabs(i-j).eq.1) go to 1400
          iR2=(X(J)-X(I))**2+(Y(J)-Y(I))**2+(Z(J)-Z(I))**2
          IF(iR2.GT.18) GO TO 1400
          II=ICA(J-1)

```

```

      III=ICA(J)

```

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```

      Kx1=s1X(II,III)+X(J)
      KY1=S1Y(II,III)+Y(J)
      KZ1=S1Z(II,III)+Z(J)
      R11=(SX1-KX1)**2+(SY1-KY1)**2+(SZ1-KZ1)**2
      IF(R11.EQ.2) then
        nct=nct+inc(i,j)
        nt=nt+1
      end if
1400  CONTINUE
      ant=ant+nt
      anct=anct+nct
      WRITE(6,8009) ITERM, R2, AS2, ENERG,nct,nt
8009  FORMAT(2X,2I5,F8.2,F10.4,3X,i3,2X,i3)

C
7777  CONTINUE
C
9000  CONTINUE

      REWIND(UNIT=10)
      WRITE(10,8000) LENF
      DO I=1,LENF
        WRITE(10,8000) X(I),Y(I),Z(I)
      ENDDO

C      DO I=2,LENF1
C      WRITE(6,8000) I,X(I),Y(I),Z(I),ICA(I),ICNF(ICA(I-1),ICA(I))
C      ENDDO

C      ACCEPTANCE RATIOS FOR VARIOUS MOVES
      FKINK=FLOAT(QKINK)/FLOAT(NCYCLE*PHOT)/AL4/100.
      FWAVE=FLOAT(QWAVE)/FLOAT(NCYCLE*PHOT)/100.
      FROT=FLOAT(QROT)/FLOAT(NCYCLE*PHOT)/100.
      FEND=FLOAT(QEND)/FLOAT(NCYCLE*PHOT)/200.
      etot=etot/ncycle
      etot2=etot2/ncycle
      cv=etot2-etot*etot
      asumr2=asumr2/ncycle
      asums2=asums2/ncycle

      anct=anct/ncycle
      ant=ant/ncycle
      write(6,9942)etot,etot2,cv,asumr2,asums2,anct,ant
9942  format(1x,'<E>=',1F10.4,5X,'<E2>=',1Pd15.8,5X,'CV=',1pd15.8,/,
      'mean-square-end to end vector=',1pd15.8,/,
      '<S2>=',1pd15.8,/, 'native contacts=',1pd15.8,/,
      ' number of contacts=',1pd15.8,/)

      write(6,8012)
8012  format(1x,'      fkink=      fend =      fwave=      frot=')
      WRITE(6,8002) FKINK,FEND,FWAVE,FROT

C
C      DETAILED ANALYSIS OF THE CHAIN STRUCTURE
C

```

```

181      write(16,181) atemp,etot,cv,asumr2,asums2,anct,ant
      format(1x,1f8.3,2x,6(1f8.3,2x))

8004      WRITE(6,8004)
      FORMAT(1X,/,/,8X,'VECTOR1  VECTOR2',8x,'SIDE 1/2/3',6x,'HANDENES',/)

      DO I=2,LENF1
      II=ICA(I-1)
      JJ=ICA(I)
      KK=ICA(I+1)

      Icj=ICONF(II,JJ)
      SID1=SIDGR1(II,JJ)
      SID2=SIDGR2(II,JJ)
      SID3=SIDGR3(II,JJ)

      WX1=VX(II)
      WY1=VY(II)
      WZ1=VZ(II)
      WX2=VX(JJ)
      WY2=VY(JJ)
      WZ2=VZ(JJ)
      WX3=VX(KK)
      WY3=VY(KK)
      WZ3=VZ(KK)
      R3=(WX1+WX2+WX3)**2+(WY1+WY2+WY3)**2+(WZ1+WZ2+WZ3)**2
      W1X=(S1X(ii,jj))*INDGL(I)
      W1Y=(S1Y(ii,jj))*INDGL(I)
      W1Z=(S1Z(ii,jj))*INDGL(I)
c      specification of the non interactions for sites

      W2X=stlx(sid1)*INDGL(I)
      W2Y=stly(sid1)*INDGL(I)
      W2Z=stlz(sid1)*INDGL(I)

      W3X=stlx(sid2)*INDGL(I)
      W3Y=stly(sid2)*INDGL(I)
      W3Z=stlz(sid2)*INDGL(I)

      W4X=stlx(sid3)*INDGL(I)
      W4Y=stly(sid3)*INDGL(I)
      W4Z=stlz(sid3)*INDGL(I)

      IHX=(WY1*WZ2-WY2*WZ1)*INDGL(I)
      IHY=(WX2*WZ1-WZ2*WX1)*INDGL(I)
      IHZ=(WX1*WY2-WY1*WX2)*INDGL(I)
      IH1=ISIGN(1,(IHX*W1X+IHY*W1Y-IHZ*W1Z))

      WRITE(6,8003) I,WX1,WY1,WZ1,WX2,WY2,WZ2,
      * W1X,W1Y,W1Z,W2X,W2Y,W2Z,W3X,W3Y,W3Z,IH1,Icj,r3

```


ENDDO

CENTRE OF GRAVITY COORDINATES

C

```

ASX=FLOAT(SX)/LENF
ASY=FLOAT(SY)/LENF
ASZ=FLOAT(SZ)/LENF
XSHIFT=MID-ASX
YSHIFT=MID-ASY
ZSHIFT=MID-ASZ

```

IF((XSHIFT**2+YSHIFT**2+ZSHIFT**2).GT.30) THEN

NORMALISATION

C

```

CALL REMOVE(XYZ,INDGL(1),X(1),Y(1),Z(1),13,13,13)
CALL REMOVE(XYZ,INDGL(LENF),X(LENF),Y(LENF),Z(LENF),13,13,13)
DO I=2,LENF1
  II=ICA(I-1)
  JJ=ICA(I)
  SID1=SIDGR1(II,JJ)
  SID2=SIDGR2(II,JJ)
  SID3=SIDGR3(II,JJ)
  CALL REMOVE(XYZ,INDGL(I),X(I),Y(I),Z(I),SID1,SID2,SID3)
ENDDO
DO I=1,LENF
  X(I)=X(I)+XSHIFT
  Y(I)=Y(I)+YSHIFT
  Z(I)=Z(I)+ZSHIFT
ENDDO
sxd=sxd-xshift
syd=syd-yshift
szd=szd-zshift

```

```

CALL setin(XYZ,INDGL(1),X(1),Y(1),Z(1),13,13,13,1)
CALL setin(XYZ,INDGL(LENF),X(LENF),Y(LENF),Z(LENF),13,13,13,1)
DO I=2,LENF1
  II=ICA(I-1)
  JJ=ICA(I)
  SID1=SIDGR1(II,JJ)
  SID2=SIDGR2(II,JJ)
  SID3=SIDGR3(II,JJ)

  CALL setin(XYZ,INDGL(I),X(I),Y(I),Z(I),SID1,SID2,SID3,I)
ENDDO
END IF

```

- C
7700

CONTINUE

C

```

write(13,*)iterm,energ,sxd,syd,szd
do i=1,lenf
  xt(i)=x(i)+sxd
  yt(i)=y(i)+syd

```

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ENDDO

```

8003  FORMAT(1X,I4,X,3I3,X,3I3,2X,3I2,X,3I2,X,3I2,2X,I2,x,i3,x,i3)
8002  FORMAT(1X,/,5X,5F10.6)
      write(6,8010)
8010  format(1x,/,5x,50(1h-),/)
8000  FORMAT(3X,5I4,I6)
      do i=6,18,2
      write(6,8005) i,iflip(i,1),iflip(i,2),iflip(i,3),iflip(i,4),
      * iflip(i,5)
      enddo
8005  format(1x,i5,5i8)
c
c      test1 of occupancy - a direct one
      lenfo7=lenf*7
      lenf23=lenf2-NBGL
8006  write(6,8006) lenf, lenfo7, lenf23,nbgl
      format(1x,/,5x,'lenf 7*lenf lenf-2 -nbgl ngbl',4i6,/)
      isi=0
      ione=0
      ioc=0
      do xx=1,max
      do yy=1,max
      do zz=1,max
      point=xyz(xx,yy,zz)
      if(point.ne.0) then

          if(point.gt.0) then
              isi=isi-1
          else
              if(point.eq.-1) ione=ione-1
              ioc=ioc-1
          endif
      endif

      enddo
      enddo
      enddo
c writing of the backbone and side groups coordinates - without the
c central (inert) bead
c
c      do i=2,lenf2
c      ii=ica(i-1)
c      iii=ica(i)
c      SX1=stlLX(SIDGR1(II,III))+X(I)
c      SY1=stlLY(SIDGR1(II,III))+Y(I)
c      SZ1=stlLZ(SIDGR1(II,III))+Z(I)
c      SX2=stlLX(SIDGR2(II,III))+X(I)
c      SY2=stlLY(SIDGR2(II,III))+Y(I)
c      SZ2=stlLZ(SIDGR2(II,III))+Z(I)
c      SX3=stlLX(SIDGR3(II,III))+X(I)
c      SY3=stlLY(SIDGR3(II,III))+Y(I)

```

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```

c      SZ3=stlL2(SIDGR3(II,III))+Z(I)
c      write(6,420) x(i),y(i),z(i),sx1,syl,sz1,sx2,sy2,sz2,
c      * sx3,sy3,sz3
c 420  format(5x,4(2x,3i4))
c      enddo
c      ioc=ioc-3*(lenf2-nbgl)

c      ione=(ione-14)/3 -2
c      there are 3 -1 per side chain that is not a glycine
c      let us count the number of excess minus ones

c      write(6,8007) ione, ioc,isi
8007  format(1x,/,1x,'L-GLY, occupancy and side groups ',3i6,/,
c      * 5x,'***** contact map *****',/)

c      do 400 i=2,lenf2
c      k=i+1
c      ii=ica(i-1)
c      iii=ica(i)
c      s4=sidgr4(ii,iii)
c      tx=tlx(s4)
c      ty=tly(s4)
c      tz=tlz(s4)
c      ih1=ihan1(ii,iii)
c      ih2=ihan2(ii,iii)
c      ih3=ihan3(ii,iii)

c      SX1=slx(ii,iii)+x(i)
c      SY1=sly(ii,iii)+y(i)
c      SZ1=slz(ii,iii)+z(i)

c      DO 400 J=K,LENF1
c  it is not counting the nearest down-the-chain neighbours, which may be
c  usefull for some purposes .....
c      if(iabs(i-j).eq.1) go to 400
c      R2=(X(J)-X(I))**2+(Y(J)-Y(I))**2+(Z(J)-Z(I))**2
c      IF(R2.GT.18) GO TO 400
c      II=ICA(J-1)
c      III=ICA(J)
c      KX1=slx(II,III)+X(J)
c      KY1=sly(II,III)+Y(J)
c      KZ1=slz(II,III)+Z(J)

c      R11=(SX1-KX1)**2+(SY1-KY1)**2+(SZ1-KZ1)**2
c      mult=0

c      IF(R11.EQ.2) MULT=MULT+1
c      IF(MULT.EQ.0) GO TO 400
c      IF(am(i,j).gt. 0) THEN

```

```
      WRITE(6,410) I,J,am(i,j)
      elseif(am(i,j).lt.0) THEN
        WRITE(6,411) I,J,am(i,j)
      else
        WRITE(6,412) I,J,am(i,j)
      endif
400  CONTINUE
410  FORMAT(5X,I3,' and',I3,' residues are repulsive ',1f10.4)
411  FORMAT(3X,'**',I3,' and',I3,' are attractive ',1f10.4)
412  format(5x,i3,'and',i3,'are inert ',1f10.4)
```

```
CLOSE(UNIT=1)
CLOSE(UNIT=2)
```

```
CLOSE(UNIT=5)
CLOSE(UNIT=6)
CLOSE(UNIT=10)
```

```
stop
```

```
END
```

```
function vaxran(iseed)
equivalence (iyfl,yfl2)
data mask,mask2/x'3f000000',x'3f800000'/
iseed=iseed*69069 + 1
nseed=rshift(iseed,8)
if(iseed.lt.0) then
  iyfl= mask2+nseed
  vaxran=yfl2
else
  iyfl=mask+nseed
  vaxran=yfl2-.5
endif
return
end
```

```

C
C .....SIDE *3 ...GLYCINE.....
C REMOVES THE CLUSTER (RESIDUE + SIDE GROUP)
C SUBROUTINE REMOVE (XYZ,INDGL,JX,JY,JZ,ID1,ID2,ID3)
C INTEGER XYZ(150,150,150),STLX(13),STLY(13),STLZ(13)
C FCC LATTICE VECTORS (AND 000)
C DATA STLX /4*0,-1,1,-1,1,-1,1,-1,1,0/
C DATA STLY /-1,1,-1,1,1,-1,4*0,-1,1,0/
C DATA STLZ /1,-1,-1,1,2*0,1,-1,-1,1,3*0/
C
      IF(INDGL.EQ.0) GO TO 88
      IX=JX+STLX(ID1)
      IY=JY+STLY(ID1)
      IZ=JZ+STLZ(ID1)
      XYZ(IX,IY,IZ)=0
      IIX=JX+STLX(ID2)
      IIY=JY+STLY(ID2)
      IIZ=JZ+STLZ(ID2)
      XYZ(IIX,IIY,IIZ)=0
      IIIX=JX+STLX(ID3)
      IIIV=JY+STLY(ID3)
      IIIZ=JZ+STLZ(ID3)
      XYZ(IIIX,IIIV,IIIZ)=0
      LX=(IX+IIIX+IIIX-JX)/2
      LY=(IY+IIY+IIIV-JY)/2
      LZ=(IZ+IIZ+IIIZ-JZ)/2
      XYZ(LX,LY,LZ)=0
88  XYZ(JX,JY,JZ)=0
      IXL=JX-1
      XYZ(IXL,JY,JZ)=0
      IXP=JX+1
      XYZ(IXP,JY,JZ)=0
      IYL=JY-1
      XYZ(JX,IYL,JZ)=0
      IYP=JY+1
      XYZ(JX,IYP,JZ)=0
      IZL=JZ-1
      XYZ(JX,JY,IZL)=0
      IZP=JZ+1
      XYZ(JX,JY,IZP)=0
      RETURN
      END

```

101

```

C .....SIDE *3 ..glycine.....
C THIS SUBROUTINE SETS -INDEX TO THE EXCLUDED VOLUME ENVELOPE
C AND INDEX-2,.... LENF1 AT THE SIDE GROUP POSITION. BOTH THE
C TERMINUSES ARE CODED -1 (IT IS USED IN ENERGY CALCULATIONS)
C .....
C ONLY THE FCC LATTICE VECTORS ARE ALLOWED TO INTERACT
C subroutine setind.f
C includes check for handedness so that all interacting points
C are left handed
C SUBROUTINE SETIN (XYZ,INDGL,JX,JY,JZ,ID1,ID2,ID3,IND)
C INTEGER XYZ(150,150,150),STLX(13),STLY(13),STLZ(13),INDGL
C FCC LATTICE VECTORS (AND 000)
C DATA STLX /4*0,-1,1,-1,1,-1,1,-1,1,0/
C DATA STLY /-1,1,-1,1,1,-1,4*0,-1,1,0/
C DATA STLZ /1,-1,-1,1,2*0,1,-1,-1,2,3*0/
C if(indgl.eq.0) go to 88
C IX=JX+STLX(ID1)
C IY=JY+STLY(ID1)
C IZ=JZ+STLZ(ID1)
C XYZ(IX,IY,IZ)--1
C IIX=JX+STLX(ID2)
C IIY=JY+STLY(ID2)
C IIZ=JZ+STLZ(ID2)
C XYZ(IIX,IIY,IIZ)--1
C IIIX=JX+STLX(ID3)
C IIY=JY+STLY(ID3)
C IIIZ=JZ+STLZ(ID3)
C XYZ(IIIX,IIY,IIIZ)--1
C LX=(IX+IIX+IIIX-JX)/2
C LY=(IY+IIY+IIIY-JY)/2
C LZ=(IZ+IIZ+IIIIZ-JZ)/2
C XYZ(LX,LY,LZ)=ind
88 XYZ(JX,JY,JZ)--IND
C IXL=JX-1
C XYZ(IXL,JY,JZ)--IND
C IXP=JX+1
C XYZ(IXP,JY,JZ)--IND
C IYL=JY-1
C XYZ(JX,IYL,JZ)--IND
C IYP=JY+1
C XYZ(JX,IYP,JZ)--IND
C IZL=JZ-1
C XYZ(JX,JY,IZL)--IND
C IZP=JZ+1
C XYZ(JX,JY,IZP)--IND
C RETURN
C END

```

102

```

C .....SIDE *3 ...glycine.....
C CHECK OF OCCUPANCY - ENTIRE CLUSTER (RESIDUE+SIDE GROUP)
C FUNCTION LOOK(XYZ,INDGL,JX,JY,JZ,ID1,ID2,ID3)
  LOGICAL LOOK
  INTEGER XYZ(150,150,150),STLX(13),STLY(13),STLZ(13)
C FCC LATTICE VECTORS (AND 000)
  DATA STLX /4*0,-1,1,-1,1,-1,1,-1,1,0/
  DATA STLY /-1,1,-1,1,1,-1,4*0,-1,1,0/
  DATA STLZ /1,-1,-1,1,2*0,1,-1,-1,1,3*0/
    LOOK=.FALSE.
C
    IF(INDGL.EQ.0) GO TO 88
    IX=JX+STLX(ID1)
    IY=JY+STLY(ID1)
    IZ=JZ+STLZ(ID1)
    IF(XYZ(IX,IY,IZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
    IIX=JX+STLX(ID2)
    IIY=JY+STLY(ID2)
    IIZ=JZ+STLZ(ID2)
    IF(XYZ(IIX,IIY,IIZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
    IIIX=JX+STLX(ID3)
    IIIV=JY+STLY(ID3)
    IIIZ=JZ+STLZ(ID3)
    IF(XYZ(IIIX,IIIV,IIIZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
    LX=(IX+IIX+IIIX-JX)/2
    LY=(IY+IIY+IIIV-JY)/2
    LZ=(IZ+IIZ+IIIZ-JZ)/2
    IF(XYZ(LX,LY,LZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
C
C 88 IF(XYZ(JX,JY,JZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
    IXL=JX-1
    IF(XYZ(IXL,JY,JZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN
    ENDIF
    IXP=JX+1
    IF(XYZ(IXP,JY,JZ).NE.0) THEN
      LOOK=.TRUE.
      RETURN

```


ENDIF

```

IYL=JY-1
IF(XYZ(JX,IYL,JZ).NE.0) THEN
    LOOK=.TRUE.
    RETURN
ENDIF
IYP=JY+1
IF(XYZ(JX,IYP,JZ).NE.0) THEN
    LOOK=.TRUE.
    RETURN
ENDIF
IZL=JZ-1
IF(XYZ(JX,JY,IZL).NE.0) THEN
    LOOK=.TRUE.
    RETURN
ENDIF
IZP=JZ+1
IF(XYZ(JX,JY,IZP).NE.0) LOOK=.TRUE.
RETURN
END
```

104

```

C .....side 3 .....glycine.....
C THIS FUNCTION COMPUTES THE STRENGTH OF INTERACTIONS BETWEEN THE
C SIDE GROUPS - only the nearest neighbours r=1, for ak102gly.f
C all interactions are at a distance 2
C
C program setind.f 5/12/89
C FUNCTION ERG(XYZ,INDGL,AM,KSX,KSX,KSZ,J)
C DIMENSION AM(150,150)
C INTEGER XYZ(150,150,150),P1,P2,P3,P4,P5,P6,p7,p8,p9
C integer p10,p11,p12
C
C ERG=0.
C IF(INDGL.EQ.0) RETURN
C
C IX=KSX-1
C JX=KSX+1
C IY=KSY-1
C JY=KSY+1
C IZ=KSZ-1
C JZ=KSZ+1
C
C vectors in the z plane
C P1=XYZ(JX,jy,KSZ)
C IF(P1.GT.0) ERG=ERG+AM(P1,J)
C P2=XYZ(jX,iY,KSZ)
C IF(P2.GT.0) ERG=ERG+AM(P2,J)
C P3=XYZ(iX,jy,KSZ)
C IF(P3.GT.0) ERG=ERG+AM(P3,J)
C p4=XYZ(iX,iY,KSZ)
C IF(p4.GT.0) ERG=ERG+AM(p4,J)
C
C vectors in the x plane
C p5=XYZ(KSX,JY,jZ)
C IF(p5.GT.0) ERG=ERG+AM(p5,J)
C p6=XYZ(KSX,IY,jZ)
C IF(p6.GT.0) ERG=ERG+AM(p6,J)
C p7=XYZ(KSX,JY,iZ)
C IF(p7.GT.0) ERG=ERG+AM(p7,J)
C p8=XYZ(KSX,IY,iZ)
C IF(p8.GT.0) ERG=ERG+AM(p8,J)
C
C VECTORS IN THE Y PLANE
C P9=XYZ(IX,KSX,JZ)
C IF(P9.GT.0) ERG=ERG+AM(P9,J)
C P10=XYZ(IX,KSY,iZ)
C IF(P10.GT.0) ERG=ERG+AM(P10,J)
C P11=XYZ(JX,KSY,JZ)
C IF(P11.GT.0) ERG=ERG+AM(P11,J)
C P12=XYZ(JX,KSY,iZ)
C IF(P12.GT.0) ERG=ERG+AM(P12,J)
C RETURN
C END

```

105

```

C      repulsion only to r2=5
C
C      THIS FUNCTION COMPUTES THE STRENGTH OF REPULSIVE INTERACTIONS
C
      FUNCTION EREPUL(XYZ,X,Y,Z,AREP)
      INTEGER XYZ(150,150,150),X,Y,Z
      DATA LO /-1/
      I=0
      IX=X-1
      JX=X+1
      IY=Y-1
      JY=Y+1
      IZ=Z-1
      JZ=Z+1
      c      fcc lattice
      IF(XYZ(IX,IY,Z).LT.LO) I=I+1
      IF(XYZ(IX,JY,Z).LT.LO) I=I+1
      IF(XYZ(JX,IY,Z).LT.LO) I=I+1
      IF(XYZ(JX,JY,Z).LT.LO) I=I+1
      IF(XYZ(X,IY,IZ).LT.LO) I=I+1
      IF(XYZ(X,IY,JZ).LT.LO) I=I+1
      IF(XYZ(X,JY,IZ).LT.LO) I=I+1
      IF(XYZ(X,JY,JZ).LT.LO) I=I+1
      IF(XYZ(IX,Y,IZ).LT.LO) I=I+1
      IF(XYZ(IX,Y,JZ).LT.LO) I=I+1
      IF(XYZ(JX,Y,IZ).LT.LO) I=I+1
      IF(XYZ(JX,Y,JZ).LT.LO) I=I+1
      EREPUL=I*AREP
      RETURN
      END

```

106

```

C
C
HYDROGEN BONDING AND "COOPERATIVITY" (BETA AND ALPHA MOTIFFS)
FUNCTION EHB(XYZ,ICA,PRODV,IX,IY,IZ,ID,AHB)
INTEGER XYZ(150,150,150),ICA(0:150),PRODV(24,24)
DATA LO /-1/
I=0
IXL=IX-3
IXP=IX+3
IYL=IY-3
IYP=IY+3
IZL=IZ-3
IZP=IZ+3
IC1=ICA(ID-1)
IC2=ICA(ID)
IF(XYZ(IXL,IY,IZ).LT.LO) THEN
  IDD=-XYZ(IXL,IY,IZ)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF
IF(XYZ(IXP,IY,IZ).LT.LO) THEN
  IDD=-XYZ(IXP,IY,IZ)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF
C
IF(XYZ(IX,IYL,IZ).LT.LO) THEN
  IDD=-XYZ(IX,IYL,IZ)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF
C
IF(XYZ(IX,IYP,IZ).LT.LO) THEN
  IDD=-XYZ(IX,IYP,IZ)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF
C
IF(XYZ(IX,IY,IZL).LT.LO) THEN
  IDD=-XYZ(IX,IY,IZL)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF
C
IF(XYZ(IX,IY,IZP).LT.LO) THEN
  IDD=-XYZ(IX,IY,IZP)
  IN1=ICA(IDD-1)
  IN2=ICA(IDD)
  I=I+PRODV(IC1,IN1)+PRODV(IC1,IN2)+PRODV(IC2,IN1)+PRODV(IC2,IN2)
ENDIF

```

APPENDIX E

SAMPLE INPUT

.25 0.25 0.25 0.34 0.25 0.34 0.25 ← Weights for states 6,8,10,12,14,16,18

1. 0.25 0.75 6.0 -0.15 -0.6

Repulsive potential weight.

Dihedral (torsional/rotational) angle weight.

Hydrogen bond (bond angle) parameter.

0.35 4 Size of kink jump

<u>States</u>								
<u>Residue</u>	<u>6</u>	<u>8</u>	<u>10</u>	<u>12</u>	<u>14</u>	<u>16</u>	<u>18</u>	<u>Hydrophobicity</u>
2	1	1	1	0	1	1	1	-1
3	1	1	1	0	1	1	1	-1
4	1	1	1	0	1	1	1	-1
.								
.								
10	1	1	0	1	1	1	-1	
11	1	1	1	1	0	1	1	
.								
.								
31	1	1	1	1	0	1	1	0 ← Glycine
.								
.								
43	1	1	1	1	0	1	1	1
.								
.								
n								

2 16 37 1 1

3 16 37 1 1

.

.

.

Dihedral
(torsional/
rotational)
angles for
sequence.

<u>Residue</u>	<u>6</u>	<u>8</u>	<u>10</u>	<u>12</u>	<u>14</u>	<u>16</u>	<u>18</u>	<u>Hydrophobicity</u>
10	10	21	1.5	1				
.								
.								
.								
31	14	11	1.5	-1				
.								
.								
.								
43	14	29	1.5	-1				
.								
.								
.								
n								

PHIL-PHOB, PHIL-PHIL, PHOB-PHOB	1.000	0.250	-0.750
REPULSIVE INT. AND COOPER. +H-BOND	6.000	-0.150	
SCALING FACTOR FOR DIHEDRAL ANGLE POTENTIAL	-0.600		

APPENDIX E

SAMPLE TERTIARY INTERACTION TABLE

APPENDIX E

SAMPLE TERTIARY INTERACTION TABLE

1 = cys	6 = val	11 = thr	16 = asp
2 = met	7 = tryp	12 = ser	17 = his
3 = phe	8 = tyr	13 = gln (glutamine)	18 = arg
4 = ile	9 = ala	14 = asn	19 = lys
5 = leu	10 = gly	15 = glu (glutonic acid)	20 = pro

cys interactions

```

ahyd(1,1)--5.44
ahyd(1,2)--5.05
ahyd(1,3)--5.63
ahyd(1,4)--5.03
ahyd(1,5)--5.03
ahyd(1,6)--4.46
ahyd(1,7)--4.76
ahyd(1,8)--3.89
ahyd(1,9)--3.38
ahyd(1,10)--3.16
ahyd(1,11)--2.88
ahyd(1,12)--2.86
ahyd(1,13)--2.73
ahyd(1,14)--2.59
ahyd(1,15)--2.08
ahyd(1,16)--2.66
ahyd(1,17)--3.63
ahyd(1,18)--2.70
ahyd(1,19)--1.54
ahyd(1,20)--2.92

```

phe interactions

```

ahyd(3,3)--6.85
ahyd(3,4)--6.39
ahyd(3,5)--6.26
ahyd(3,6)--5.75
ahyd(3,7)--6.02
ahyd(3,8)--4.95
ahyd(3,9)--4.36
ahyd(3,10)--3.72
ahyd(3,11)--3.76
ahyd(3,12)--3.56
ahyd(3,13)--3.30
ahyd(3,14)--3.55
ahyd(3,15)--3.51
ahyd(3,16)--3.31
ahyd(3,17)--4.61
ahyd(3,18)--3.54
ahyd(3,19)--2.83
ahyd(3,20)--3.73

```

leu

```

ahyd(5,5)--5.79
ahyd(5,6)--5.38
ahyd(5,7)--5.50
ahyd(5,8)--4.26
ahyd(5,9)--3.96
ahyd(5,10)--3.43
ahyd(5,11)--3.43
ahyd(5,12)--3.16
ahyd(5,13)--3.09
ahyd(5,14)--2.99
ahyd(5,15)--2.91
ahyd(5,16)--2.59
ahyd(5,17)--3.84
ahyd(5,18)--3.15
ahyd(5,19)--2.63
ahyd(5,20)--3.06

```

valine

```

ahyd(6,6)--4.94
ahyd(6,7)--5.05
ahyd(6,8)--4.05
ahyd(6,9)--3.62
ahyd(6,10)--3.06
ahyd(6,11)--2.95
ahyd(6,12)--2.79
ahyd(6,13)--2.67
ahyd(6,14)--2.36
ahyd(6,15)--2.56
ahyd(6,16)--2.25
ahyd(6,17)--3.38
ahyd(6,18)--2.78
ahyd(6,19)--1.95
ahyd(6,20)--2.96

```

met interactions

```

ahyd(2,2)--6.06
ahyd(2,3)--6.68
ahyd(2,4)--6.33
ahyd(2,5)--6.01
ahyd(2,6)--5.52
ahyd(2,7)--6.37
ahyd(2,8)--4.92
ahyd(2,9)--3.99
ahyd(2,10)--3.75
ahyd(2,11)--3.73
ahyd(2,12)--3.55
ahyd(2,13)--3.17
ahyd(2,14)--3.50
ahyd(2,15)--3.19
ahyd(2,16)--2.90
ahyd(2,17)--3.31
ahyd(2,18)--3.49
ahyd(2,19)--3.11
ahyd(2,20)--4.11

```

ile interactions

```

ahyd(4,4)--6.22
ahyd(4,5)--6.17
ahyd(4,6)--5.58
ahyd(4,7)--5.64
ahyd(4,8)--4.63
ahyd(4,9)--4.41
ahyd(4,10)--3.65
ahyd(4,11)--3.74
ahyd(4,12)--3.43
ahyd(4,13)--3.22
ahyd(4,14)--2.99
ahyd(4,15)--3.23
ahyd(4,16)--2.91
ahyd(4,17)--3.76
ahyd(4,18)--3.33
ahyd(4,19)--2.70
ahyd(4,20)--3.47

```

tryp

```

ahyd(7,7)--5.42
ahyd(7,8)--4.44
ahyd(7,9)--3.93
ahyd(7,10)--3.37
ahyd(7,11)--3.31
ahyd(7,12)--2.95
ahyd(7,13)--3.16
ahyd(7,14)--3.11
ahyd(7,15)--2.94
ahyd(7,16)--2.91
ahyd(7,17)--4.02
ahyd(7,18)--3.56
ahyd(7,19)--2.49
ahyd(7,20)--3.66

```

```

thr
ahyd(8,8)--3.55
ahyd(8,9)--2.85
ahyd(8,10)--2.50
ahyd(8,11)--2.48
ahyd(8,12)--2.30
ahyd(8,13)--2.53
ahyd(8,14)--2.47
ahyd(8,15)--2.42
ahyd(8,16)--2.25
ahyd(8,17)--3.33
ahyd(8,18)--2.75
ahyd(8,19)--2.01
ahyd(8,20)--2.80
+++++
ala
ahyd(9,9)--2.51
ahyd(9,10)--2.15
ahyd(9,11)--2.15
ahyd(9,12)--1.89
ahyd(9,13)--1.70
ahyd(9,14)--1.44
ahyd(9,15)--1.51
ahyd(9,16)--1.57
ahyd(9,17)--2.09
ahyd(9,18)--1.50
ahyd(9,19)--1.10
ahyd(9,20)--1.81
+++++
ahyd(10,10)--2.17
ahyd(10,11)--2.03
ahyd(10,12)--1.70
ahyd(10,13)--1.54
ahyd(10,14)--1.56
ahyd(10,15)--1.22
ahyd(10,16)--1.62
ahyd(10,17)--1.94
ahyd(10,18)--1.68
ahyd(10,19)--0.84
ahyd(10,20)--1.72
+++++
tyr
ahyd(11,11)--1.72
ahyd(11,12)--1.59
ahyd(11,13)--1.59
ahyd(11,14)--1.51
ahyd(11,15)--1.45
ahyd(11,16)--1.66
ahyd(11,17)--2.31
ahyd(11,18)--1.97
ahyd(11,19)--1.02
ahyd(11,20)--1.66
+++++
serine
ahyd(12,12)--1.48
ahyd(12,13)--1.37
ahyd(12,14)--1.31
ahyd(12,15)--1.48
ahyd(12,16)--1.46
ahyd(12,17)--1.94
ahyd(12,18)--1.22
ahyd(12,19)--0.83
ahyd(12,20)--1.35
+++++
glutamine
ahyd(13,13)--0.89
ahyd(13,14)--1.36
ahyd(13,15)--1.33
ahyd(13,16)--1.26
ahyd(13,17)--1.85
ahyd(13,18)--1.85
ahyd(13,19)--1.02
ahyd(13,20)--1.73
+++++
asn
ahyd(14,14)--1.59
ahyd(14,15)--1.43
ahyd(14,16)--1.33
ahyd(14,17)--2.01
ahyd(14,18)--1.41
ahyd(14,19)--0.91
ahyd(14,20)--1.43
+++++
glu
ahyd(15,15)--1.18
ahyd(15,16)--1.23
ahyd(15,17)--2.27
ahyd(15,18)--2.07
ahyd(15,19)--1.60
ahyd(15,20)--1.40
+++++
asp
ahyd(16,16)--0.96
ahyd(16,17)--2.14
ahyd(16,18)--1.98
ahyd(16,19)--1.32
ahyd(16,20)--1.19
+++++
his
ahyd(17,17)--2.78
ahyd(17,18)--2.12
ahyd(17,19)--1.09
ahyd(17,20)--2.17
+++++
arg
ahyd(18,18)--1.39
ahyd(18,19)--0.06
ahyd(18,20)--1.85
+++++
lys
ahyd(19,19)--0.13
ahyd(19,20)--0.67
+++++
pro
ahyd(20,20)--1.18

```


111

APPENDIX E

SAMPLE OUTPUT

The native contact pairs are:

2	18
25	53
57	163

Snapshot (interim report) every 5000 Monte Carlo timesteps.

TEMPERATURE OF THE SYSTEM = 0.340

Square of distance
between adjacent
 α -carbons.

Radius of gyration
squared.

Number of contacts
between sidechains.

1term=	R2=	AS2=	ENERGY=	native	any contacts
1	225	50.23	-302.2651	0	30
2	203	48.55	-294.1492	0	30
3	257	49.63	-298.5013	0	30
4	227	49.07	-301.3834	0	30
5	275	50.14	-306.7366	0	30
6	299	50.46	-304.1194	0	30
7	221	49.85	-303.1781	0	30
8	331	48.67	-294.3552	0	28
9	329	47.93	-294.4433	0	28
10	257	49.45	-291.8564	0	27
11	297	49.12	-299.2383	0	29
12	299	49.15	-299.5342	0	29
13	297	48.81	-298.7695	0	29
14	261	48.46	-294.4760	0	29
15	297	50.30	-300.5060	0	30
16	201	48.37	-292.5648	0	28
17	269	48.30	-293.5644	0	28
18	269	49.49	-298.5347	0	29
19	275	50.13	-305.4173	0	30
20	237	50.13	-285.0356	0	27
21	237	46.07	-288.0940	0	27
22	363	49.26	-298.0356	0	30
23	227	49.21	-293.2128	0	29
24	241	50.60	-297.5958	0	30
.					
.					
.					

APPENDIX ESAMPLE OUTPUT (CONT.)FINAL CONFORMATION

	VECTOR1			VECTOR2			SIDE 1/2/3					HANDENES		
2	0	2	1	1	0	2	-1	-1	1	-1	0	1	-1	14 21
3	1	0	2	-2	0	1	1	1	1	1	0	1	-1	10 25
4	-2	0	1	1	0	2	-1	-1	-1	-1	0	-1	-1	10 11
5	1	0	2	2	-1	0	-1	-1	1	-1	0	1	-1	14 27
6	2	-1	0	2	0	-1	-1	-1	-1	-1	0	-1	-1	18 37
7	2	0	-1	2	0	1	-1	1	-1	-1	0	-1	-1	16 37
8	2	0	1	2	1	0	1	-1	-1	1	0	-1	-1	18 25
9	2	1	0	0	-1	2	-1	1	-1	-1	0	-1	-1	8 9
10	0	-1	2	-2	0	1	1	1	1	1	0	1	-1	14 17
11	-2	0	1	0	-2	-1	0	0	0	0	0	0	1	8 17
12	0	-2	-1	-2	1	0	1	-1	1	1	-1	0	-1	6 21
13	-2	1	0	-2	-1	0	1	1	-1	1	1	0	-1	16 37
14	-2	-1	0	-2	0	-1	-1	1	-1	-1	0	-1	-1	18 35
15	-2	0	-1	-1	0	-2	-1	1	1	-1	0	-1	-1	18 29
16	-1	0	-2	-2	0	1	1	-1	-1	1	0	-1	-1	10 21
17	-2	0	1	-1	2	0	1	1	1	1	0	1	-1	14 21
18	-1	2	0	1	2	0	-1	-1	1	-1	0	-1	-1	16 21
19	1	2	0	-1	0	-2	1	-1	1	1	-1	0	-1	8 17
20	-1	0	-2	0	2	1	-1	-1	-1	-1	0	-1	-1	6 9
21	0	2	1	-1	0	2	-1	1	-1	-1	0	-1	-1	14 27
22	-1	0	2	0	-1	2	-1	-1	-1	-1	0	-1	-1	18 27
23	0	-1	2	2	0	1	1	-1	-1	1	0	-1	-1	14 17
24	2	0	1	0	-2	-1	-1	1	1	-1	0	-1	-1	8 17
25	0	-2	-1	1	0	2	1	-1	-1	1	0	-1	-1	6 11
26	1	0	2	0	1	2	1	1	-1	1	0	-1	-1	18 21
27	0	1	2	1	-2	0	-1	1	1	-1	0	-1	-1	6 13
28	1	-2	0	-1	-2	0	1	1	1	1	0	1	-1	16 21
29	-1	-2	0	1	0	-2	-1	1	1	-1	0	-1	-1	8 9
30	1	0	-2	2	1	0	-1	1	-1	-1	0	-1	-1	14 17
31	2	1	0	1	0	2	-1	1	1	-1	0	-1	-1	14 9
32	1	0	2	-1	-2	0	-1	1	1	-1	0	-1	-1	8 25
33	-1	-2	0	0	-1	2	1	-1	-1	1	0	-1	-1	14 25
34	0	-1	2	1	0	2	1	-1	-1	1	0	-1	-1	18 17
35	1	0	2	-1	2	0	1	-1	-1	1	0	-1	-1	8 25
36	-1	2	0	0	2	1	0	0	0	0	0	0	1	18 27
37	0	2	1	0	1	-2	1	1	1	1	0	1	-1	10 29
38	0	1	-2	0	2	-1	-1	-1	-1	-1	0	-1	-1	18 17
39	0	2	-1	2	-1	0	-1	1	1	-1	0	-1	-1	6 19
40	2	-1	0	1	0	-2	-1	-1	-1	-1	0	-1	-1	14 25

•
•
•

APPENDIX ESAMPLE OUTPUT (CONT.)

```

•
•
•
375 249 46.81 -292.8082 0 28
376 269 45.55 -287.4545 0 30
377 205 45.26 -290.7192 0 28
378 299 49.93 -295.7486 0 27
379 251 48.87 -292.7481 0 28
380 285 48.30 -295.7492 0 29
381 305 49.53 -295.7792 0 27
382 275 47.54 -297.3956 0 27
383 305 47.66 -296.4246 0 30
384 285 48.34 -296.7784 0 26
385 275 49.99 -305.2485 0 30
386 117 48.92 -297.6013 0 30
387 241 49.43 -299.3969 0 30
388 299 49.99 -303.4559 0 30
389 257 49.15 -298.2790 0 30
390 275 49.46 -303.6329 0 30
391 145 48.75 -300.4864 0 30
392 373 48.91 -287.5453 0 29
393 275 50.86 -301.0170 0 28
394 275 50.16 -304.6649 0 30
395 275 50.25 -302.6943 0 30
396 293 50.86 -296.6948 0 28
397 297 49.58 -298.8719 0 29
398 299 49.58 -300.4898 0 28
399 341 50.76 -296.8724 0 31
400 269 49.22 -295.0204 0 28

```

```

<E>= -295.6850 <E2>= 8.74568216D+04 CV= 2.71777422D+01
mean-square-end to end vector= 2.56595001D+02
<S2>= 4.85322037D+01
native contacts= 0.00000000D+00
number of contacts= 2.84550000D+01

```

```

fkink=      fend =      fwave=      frot=

```

```

0.029328 0.133321 0.000000 0.001293

```

```

6 10797 140136 11818 10619 10528
8 27659 102491 31519 101909 31348
10 42315 42630 42626 42620 42721
12 19949 45247 38505 40334 47439
14 344543 344363 343647 345273 344759
16 407038 70689 64827 63643 70601
18 211817 211240 211463 211478 211935

```

```

lenf 7*lenf lenf-2 -nbgl ngbl .78 546 70 6

```

APPENDIX E (CONT.)SAMPLE OUTPUT (CONT.)

L-GLY, occupancy and side groups 72 546 70

***** contact map *****

```

      2and 4are inert      0.0000
**  3 and 7 are attractive -12.5588
**  3 and 69 are attractive -3.8824
**  5 and 15 are attractive -11.2059
**  5 and 17 are attractive -11.0588
**  5 and 19 are attractive -9.3235
**  5 and 25 are attractive -11.2059
**  7 and 69 are attractive -8.7353
**  9 and 73 are attractive -3.0000
** 10 and 72 are attractive -9.9412
      11and 13are inert    0.0000
** 11 and 71 are attractive -3.0000
      15and 17are inert    0.0000
** 17 and 25 are attractive -3.0000
** 19 and 25 are attractive -9.3235
** 28 and 32 are attractive -9.3235
** 28 and 38 are attractive -9.3235
** 32 and 38 are attractive -11.2059
** 32 and 40 are attractive -3.1176
** 45 and 53 are attractive -9.9412

** 46 and 58 are attractive -11.0588
** 47 and 61 are attractive -7.4706
** 47 and 63 are attractive -11.7059
** 52 and 70 are attractive -9.9412
** 52 and 74 are attractive -9.9412
** 55 and 75 are attractive -3.0000
      61and 63are inert    0.0000
      70 and 74 residues are repulsive      0.8529

```

What is Claimed is:

5 1. Method of determining by a machine a
three-dimensional structure of a protein or portion
thereof including sidechains, the method comprising
the steps of:

 specifying a sequence of amino acid residues
whose native tertiary structure is to be determined;
10 specifying local conformation preferences
for respective residues of the sequence, and
representing tertiary interactions between all pairs
of sidechains;

 specifying a temperature;
15 automatically generating a representation of
an unfolded chain of the residues in three
dimensions;

 simulating in the machine folding of the
chain and interactions between all pairs of
20 sidechains, in accordance with said conformation
preferences and said temperature, and producing a
representation of a corresponding native tertiary
structure; and

 displaying the representation of the
25 tertiary structure.

 2. The method of claim 1 where the step of
displaying includes the step of presenting the
tertiary structure as a three-dimensional
30 representation.

 3. The method of claim 1 where the step of
simulating includes the steps of stopping the
simulating operation at an intermediate stage,
35 specifying another temperature, and resuming the

simulating operation.

4. Method of determining a three-dimensional conformation of a globular protein utilizing Monte Carlo dynamics technique with asymmetric Metropolis sampling criterion, the method comprising the steps of:

specifying a sequence of amino acid residues of the protein;

generating a three-dimensional representation of an unfolded conformation consisting of an α -carbon backbone and sidechains in response to the specified sequence;

producing from the unfolded conformation, using said technique, successive likely conformations at a predetermined temperature according to the total energy of each conformation;

selecting from the successive likely conformations the lowest total-free-energy tertiary conformation which satisfies said criterion; and determining the coordinates of the selected tertiary conformation for display.

5. The method of claim 4 where the step of producing includes the step of determining local conformational energetic preferences of the α -carbons.

6. The method of claim 5 where the step of producing includes the step of identifying spatially close pairs of sidechains in each conformation.

7. The method of claim 6 where the step of producing includes the step of simulating tertiary interactions between said spatially close pairs.

8. The method of claim 7 where the step of producing includes the step of determining the sum of the effective interaction contact energy between respective close pairs based on predetermined
5 frequency of contact between said pairs.

9. The method according to claim 8 where the step of determining the effective interaction contact energy includes the step of scaling said
10 energy to a selected lowest level by referencing average interaction contact energies of non-polar residues to a hydrophobicity scale.

10. A computer-based model for
15 representing, in a three-dimensional cartesian coordinate system, a conformation of a protein or portion thereof, including the protein's α -carbon backbone and sidechains of finite surface area, as the protein folds from an unfolded sequence of amino
20 acid residues to a folded tertiary structure, the model comprising:

a cubic arrangement of lattice sites disposed for framing the conformation;

25 the cubic arrangement being represented by unit vectors $(\pm 1, 0, 0)$, $(0, \pm 1, 0)$, $(0, 0, \pm 1)$, where the distance between adjacent lattice sites is unity; and where

30 each α -carbon occupies a lattice site located at a distance of $\sqrt{5}$ units from its adjacent α -carbon along a $(\pm 2, \pm 1, 0)$ vector or cyclic permutation thereof.

11. The model of claim 10 where said cubic arrangement is a 24-nearest neighbor lattice.

12. The model of claim 11 where each α -carbon is represented as occupying a central cubic lattice site plus six adjacent cubic lattice sites defining a surface of interaction of finite size, and each sidechain is represented as being embedded in the lattice and occupying a selected number of lattice sites located relative to said central site, the number of sites occupied by the sidechain being proportional to the number of sites defining the surface of interaction.

13. A computer-based system for determining a three-dimensional structure of a protein or portion thereof including sidechains, the system comprising:

input means for specifying a sequence of amino acid residues whose native tertiary structure is to be determined, and for specifying a temperature and local conformation preferences for respective residues of the sequence;

first memory means for storing the specified sequence, temperature, and conformation preferences;

second memory means having a stored program with routines for performing Monte Carlo dynamics simulation with asymmetric Metropolis sampling criterion and for representing tertiary interactions between all pairs of the sidechains;

processing means coupled to the input, and first and second memory means, and responsive to the specified sequence, temperature, and conformation preferences for, under control of the stored program, generating a first set of coordinates representing a conformation of an unfolded chain of the residues in three dimensions, determining a total free interaction energy from tertiary interactions between all pairs of the sidechains, simulating folding of

the chain at the specified temperature and in accordance with said conformation preferences and total interaction energy, and producing a second set of coordinates representing a native tertiary structure; and

display means coupled to the processing means for displaying the second set of coordinates depicting the native tertiary structure in three dimensions.

14. An apparatus for determining a three-dimensional structure of a selected protein including a plurality of α -carbons comprising:

means for storing a representation of a selected sequence of amino acid residues of the protein and an initial starting temperature value;

means for generating a representation of a cubic arrangement of lattice sites, including means for positioning adjacent sites a unit distance from one another and means for positioning a plurality of α -carbons on selected lattice sites, each α -carbon located a distance on the order of $\sqrt{5}$ from an adjacent α -carbon;

means for combining said generated representation of said cubic arrangement with said representation of said selected stored sequence;

means for producing, in response to said temperature and in accordance with said cubic arrangement, a representation of one or more folded, three-dimensional protein structures; and

means for comparing said produced representation of three-dimensional protein structure to a predetermined criterion and for selecting one of said produced representation for display only in response to a predetermined comparison result.

15. An apparatus as in claim 14 including
means for interrupting said producing, for storing a
new temperature value and re-initiating said
5 producing.

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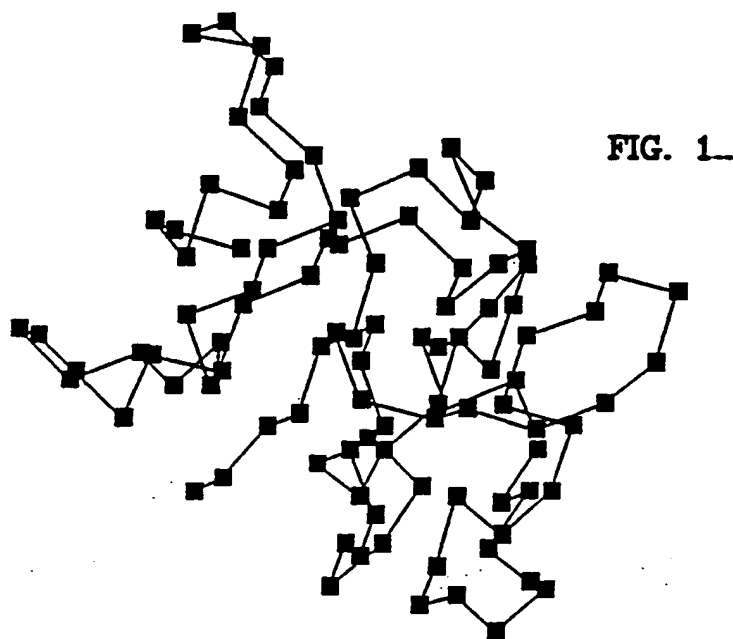
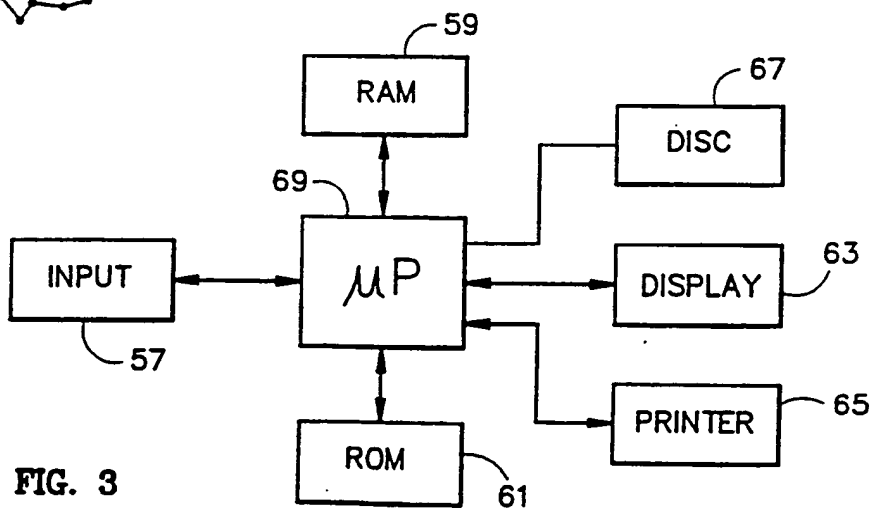
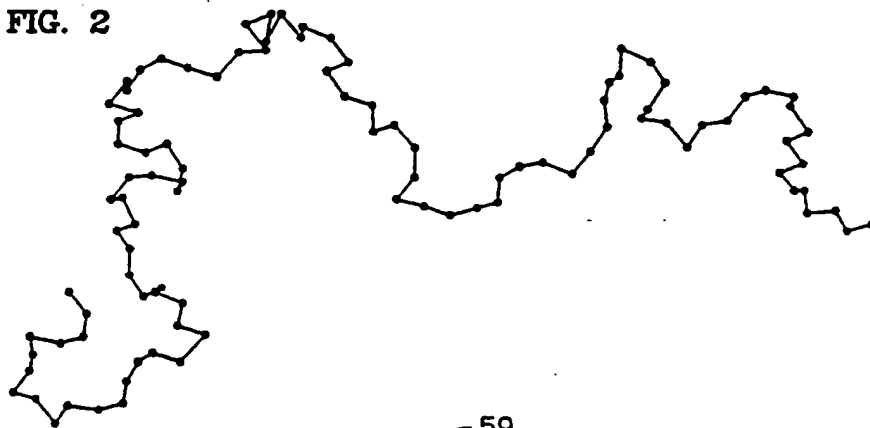


FIG. 2



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FIG. 4

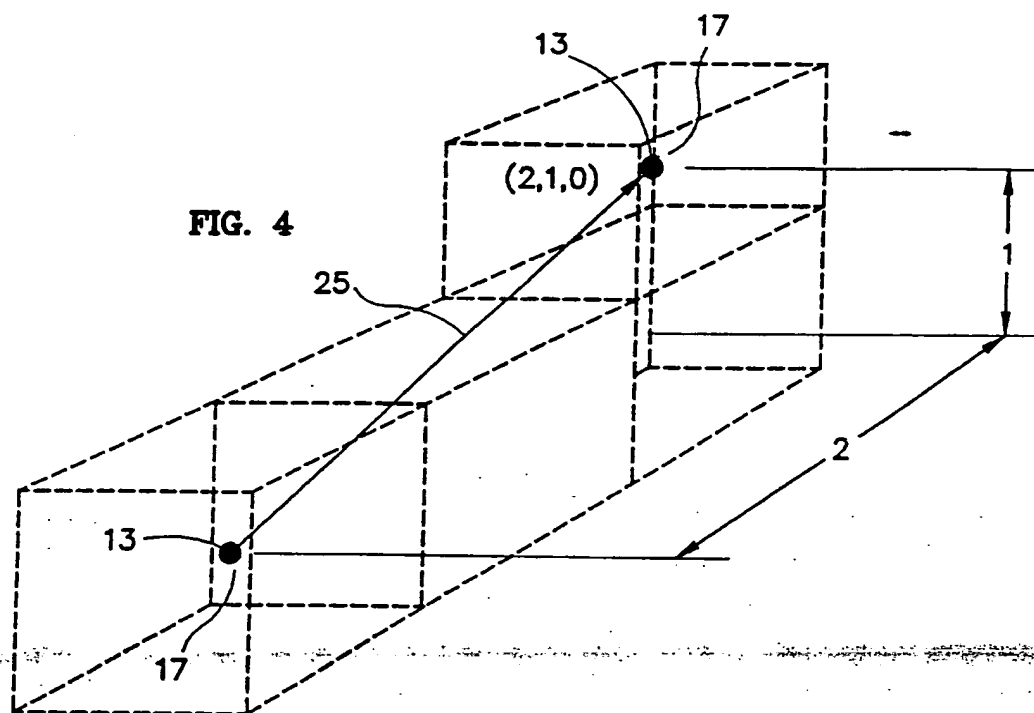
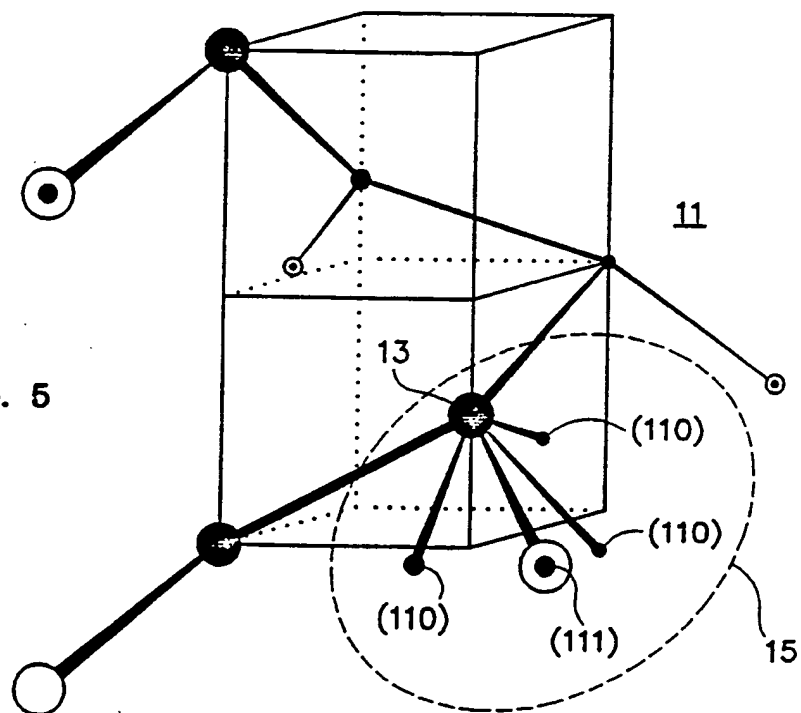
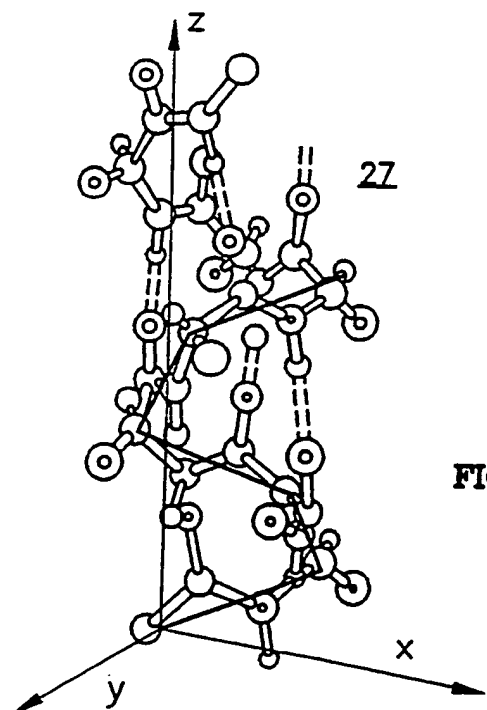
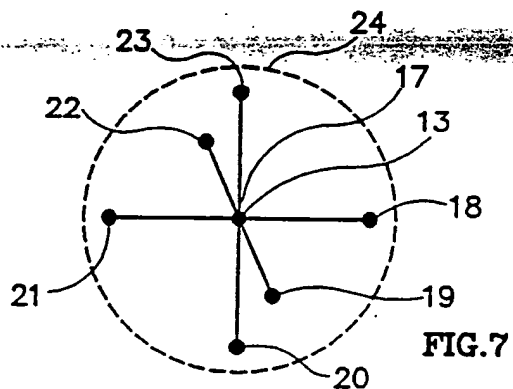
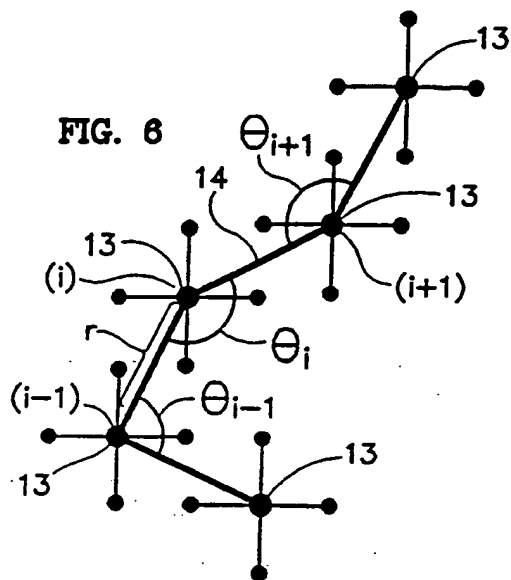


FIG. 5



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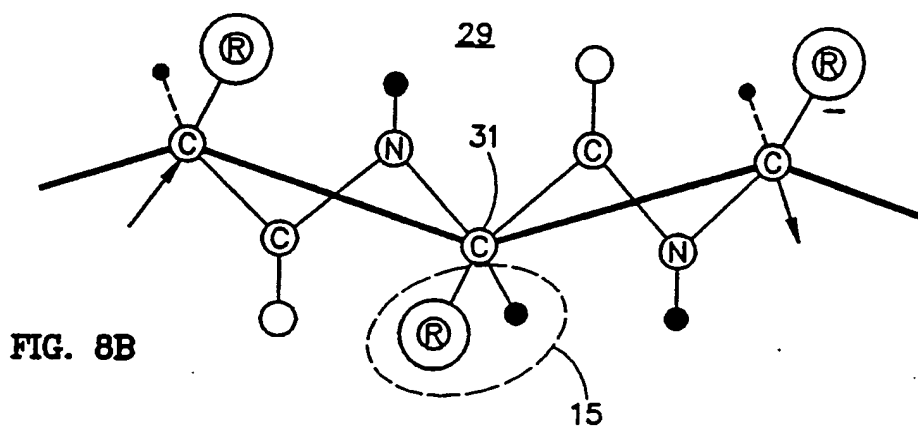


FIG. 8B

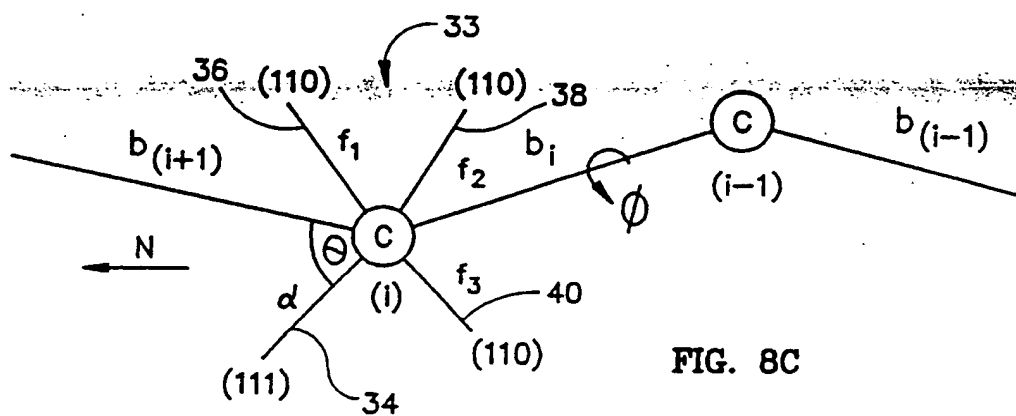


FIG. 8C

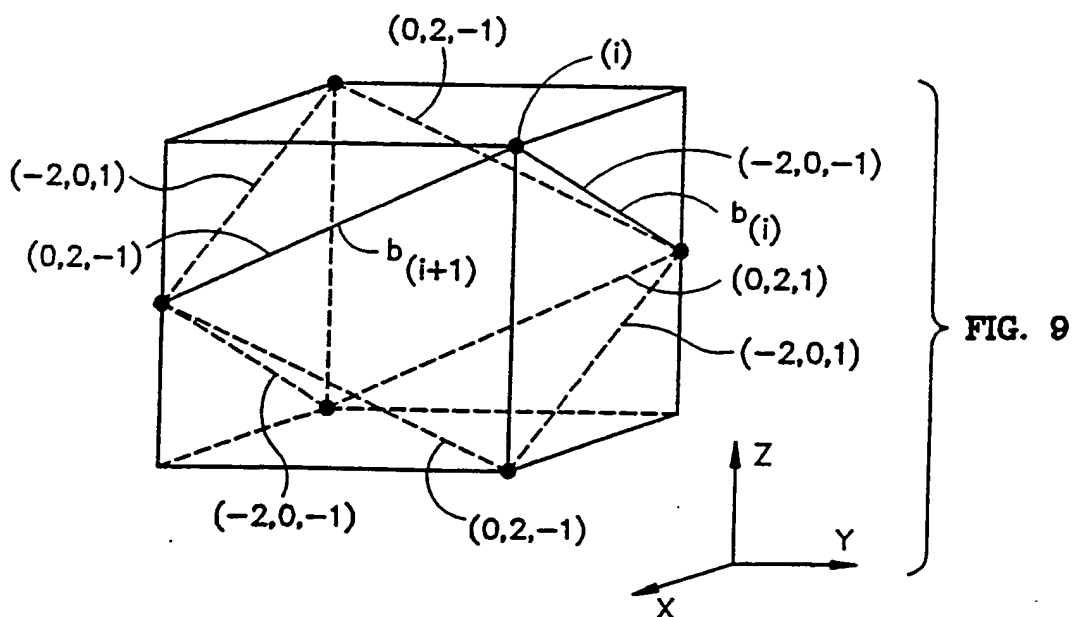
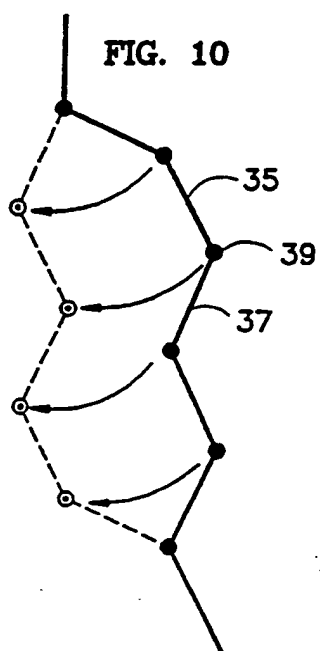


FIG. 9

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(SIDE VIEW)
FIG. 12A

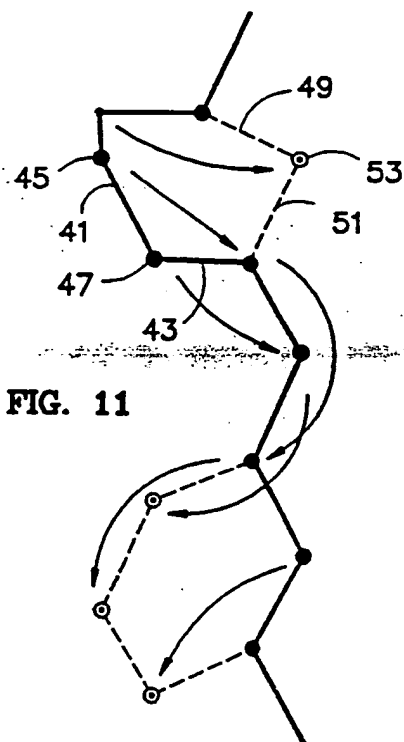
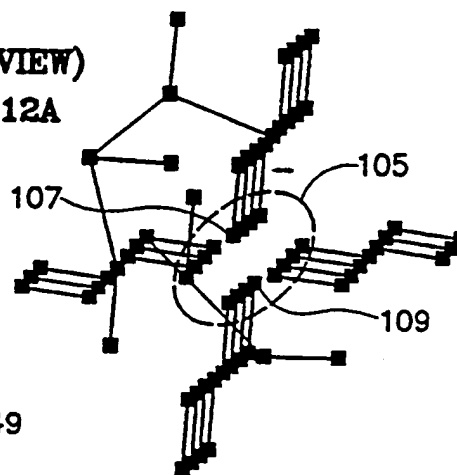


FIG. 11

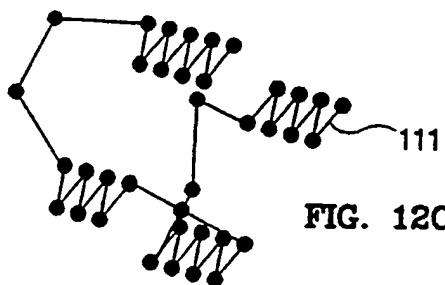
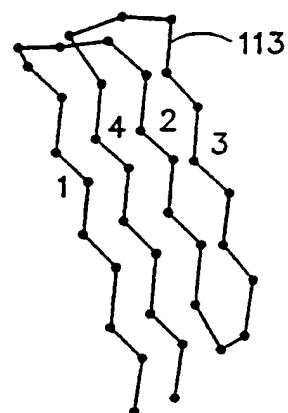
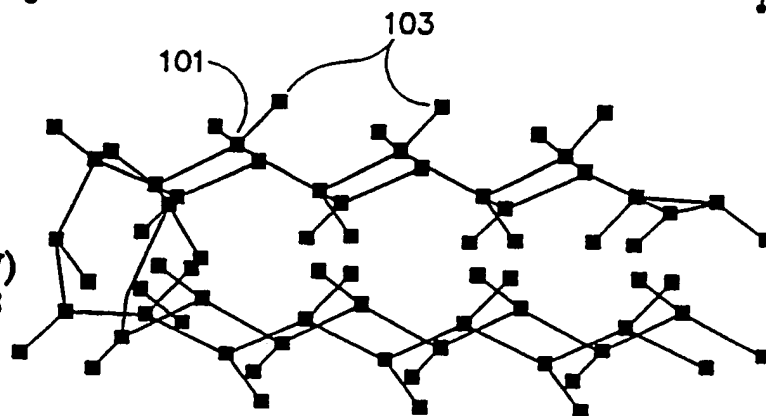


FIG. 12C

FIG. 12D



(TOP VIEW)
FIG. 12B



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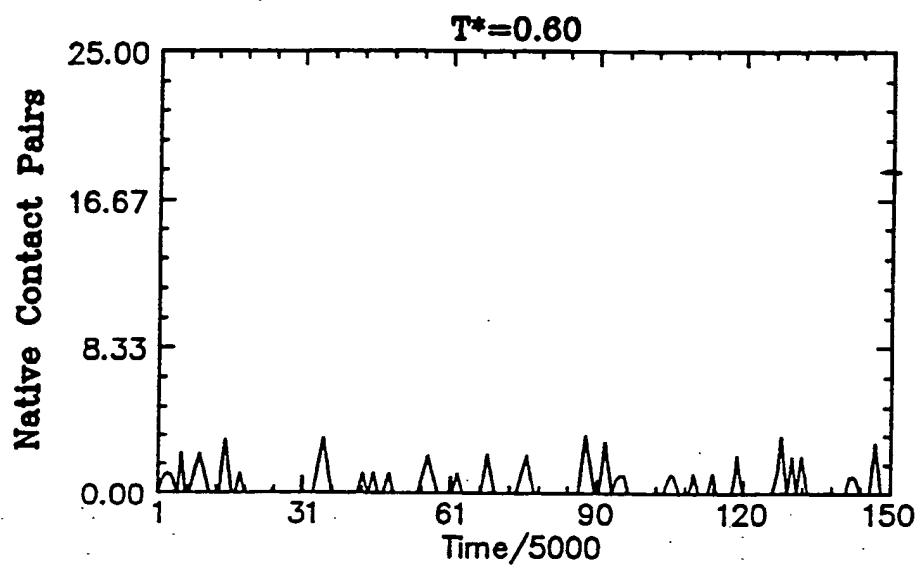


FIG. 13A

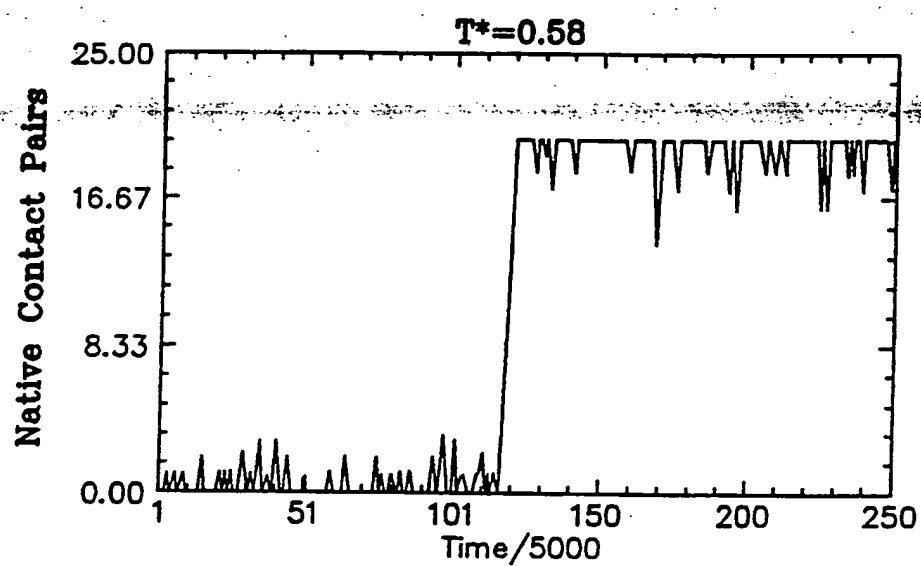


FIG. 13B

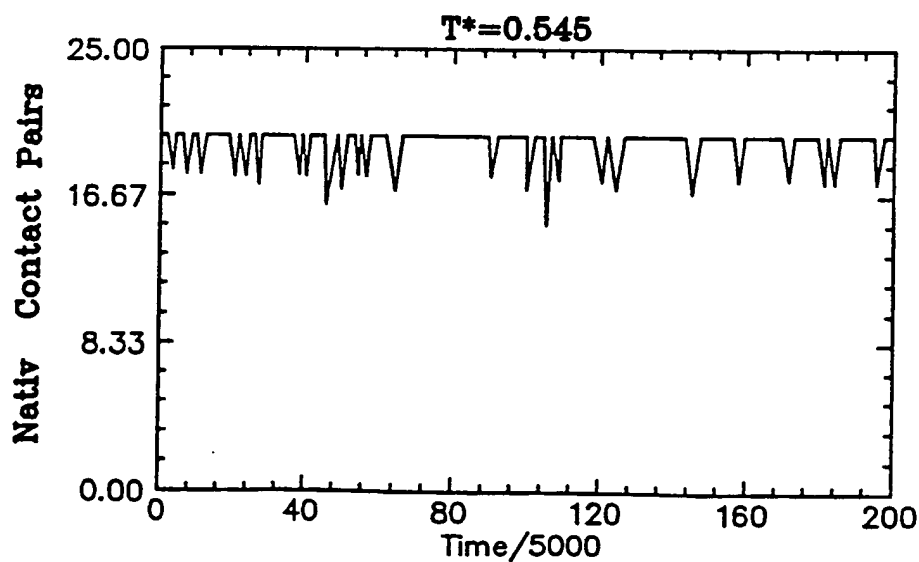


FIG. 13C

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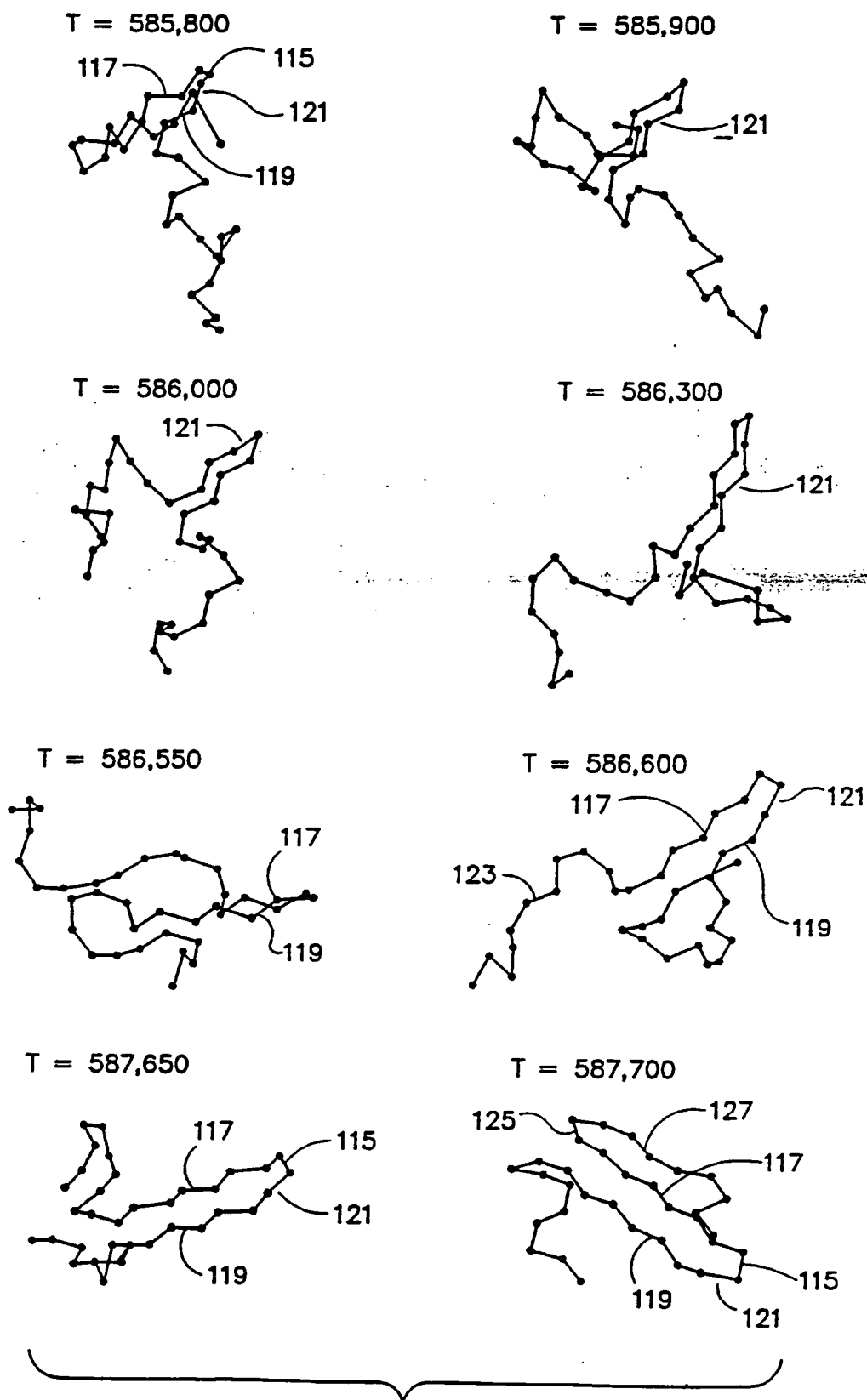


FIG. 14A

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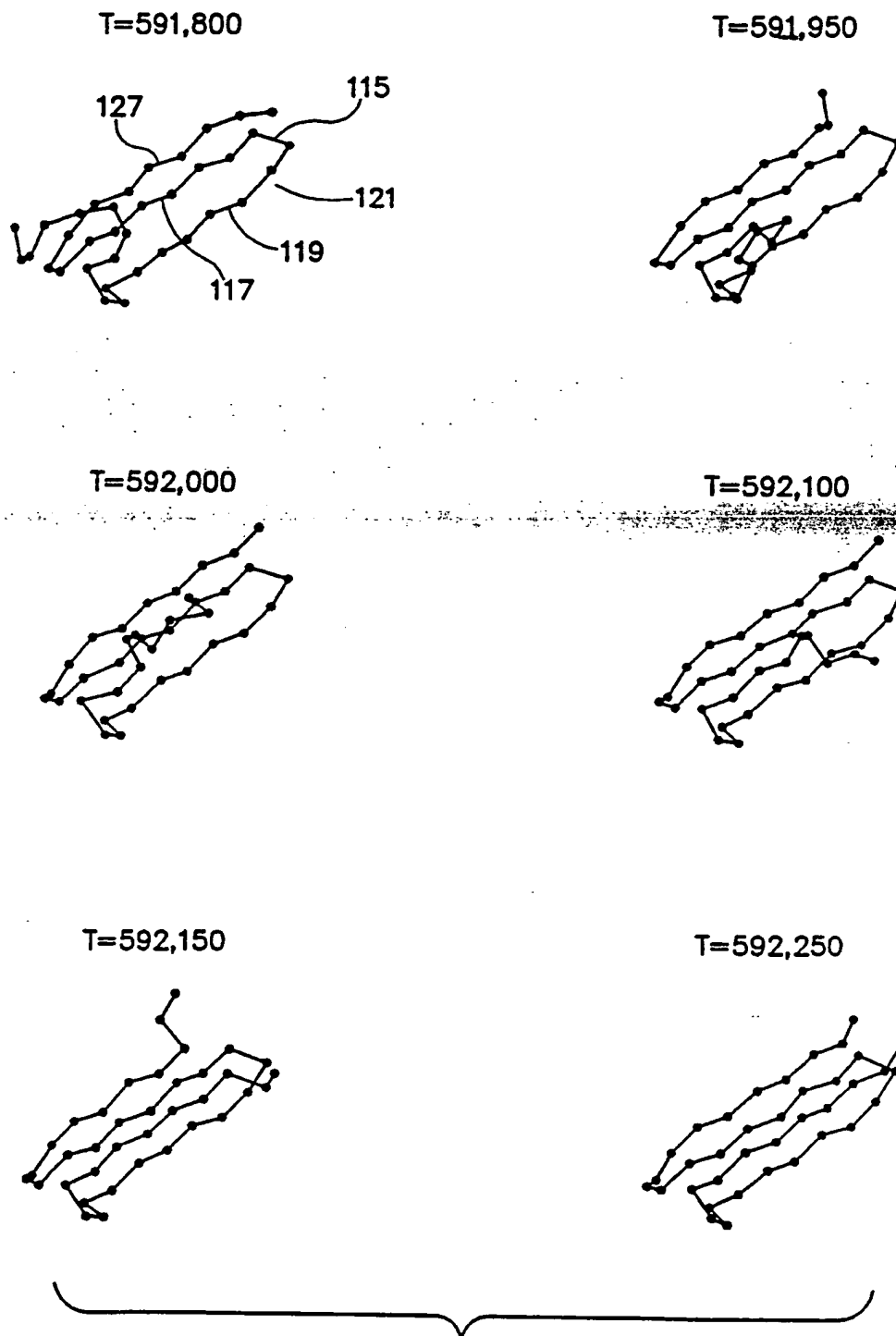


FIG. 14B

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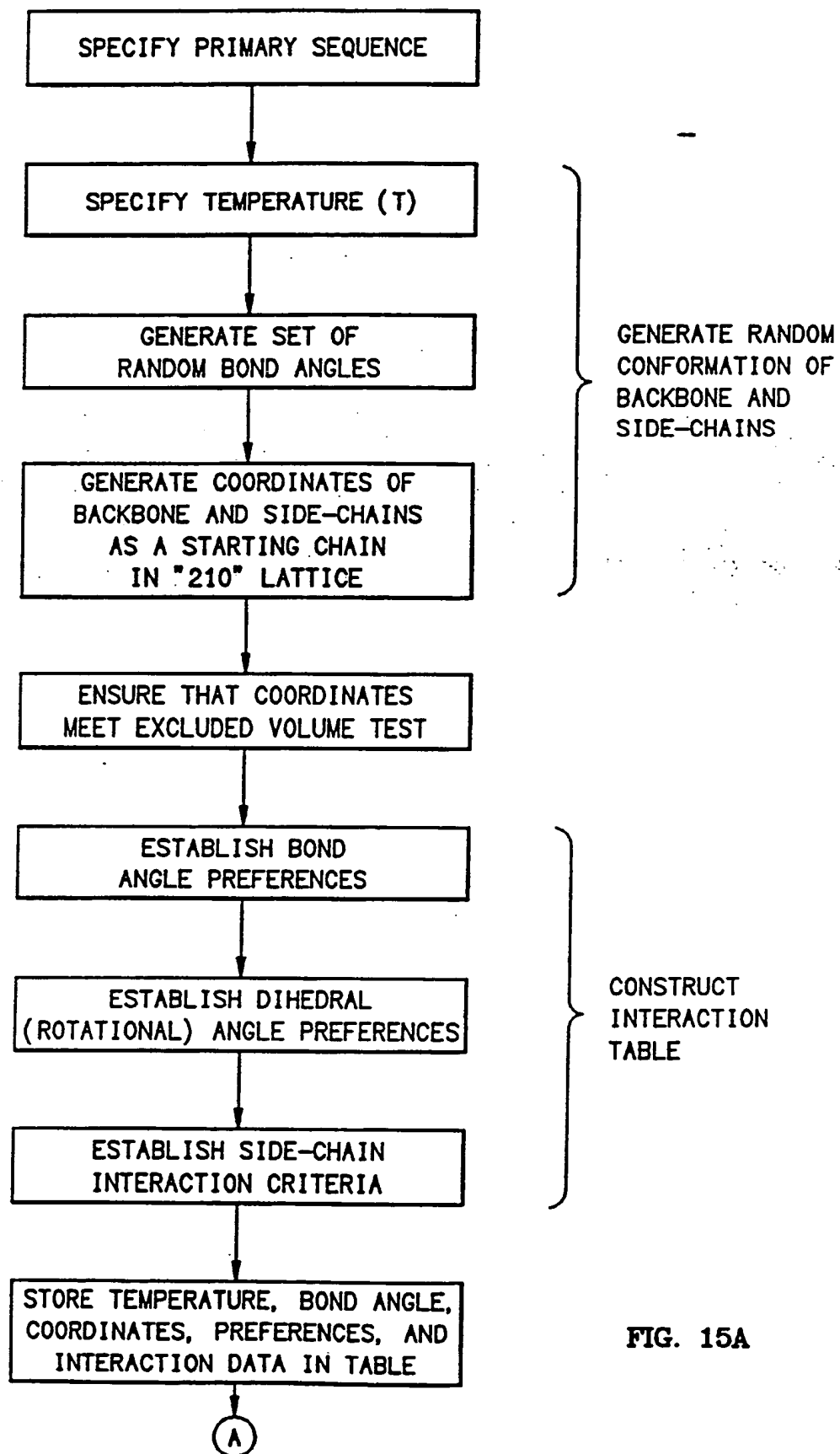
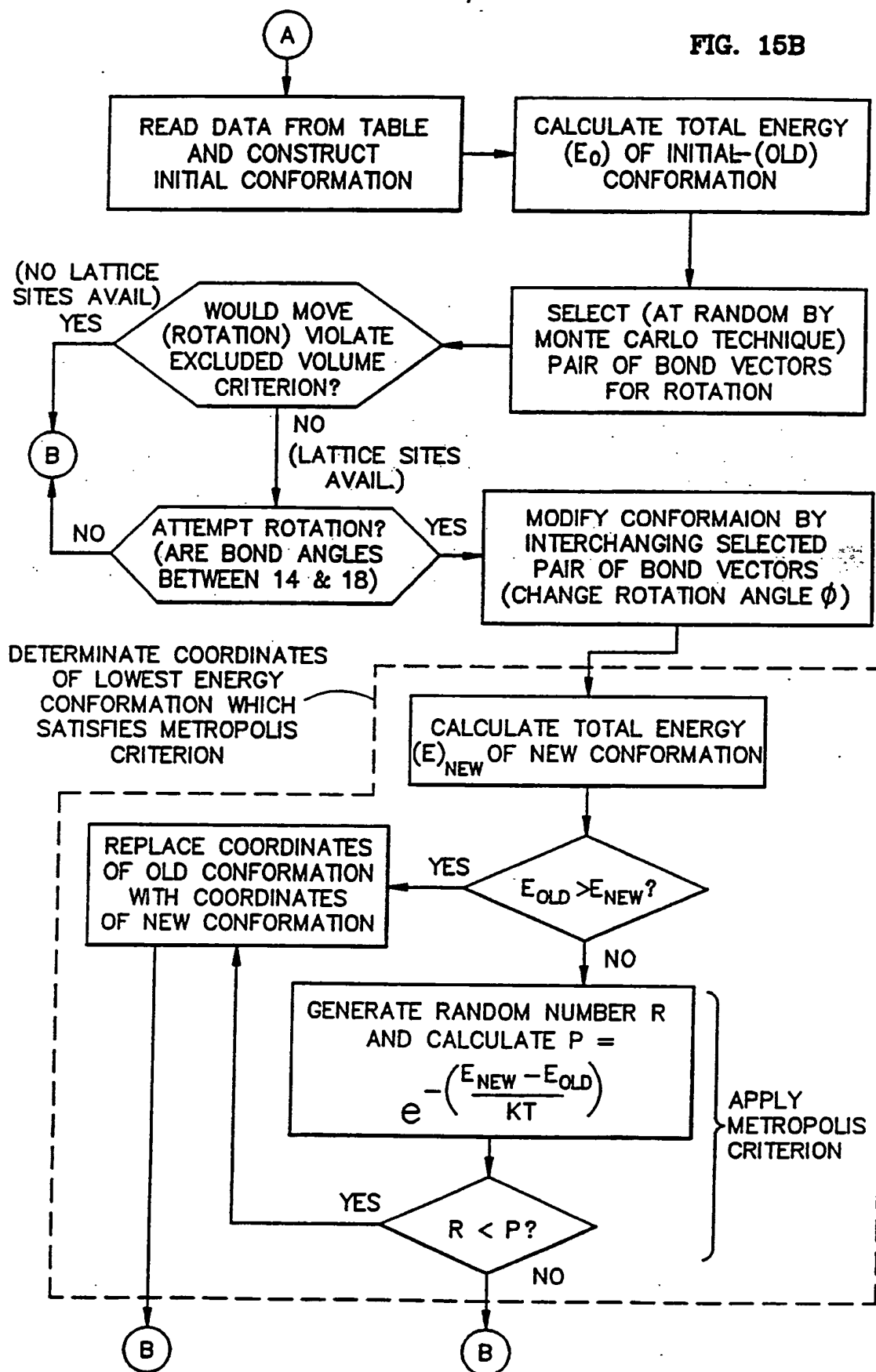


FIG. 15A

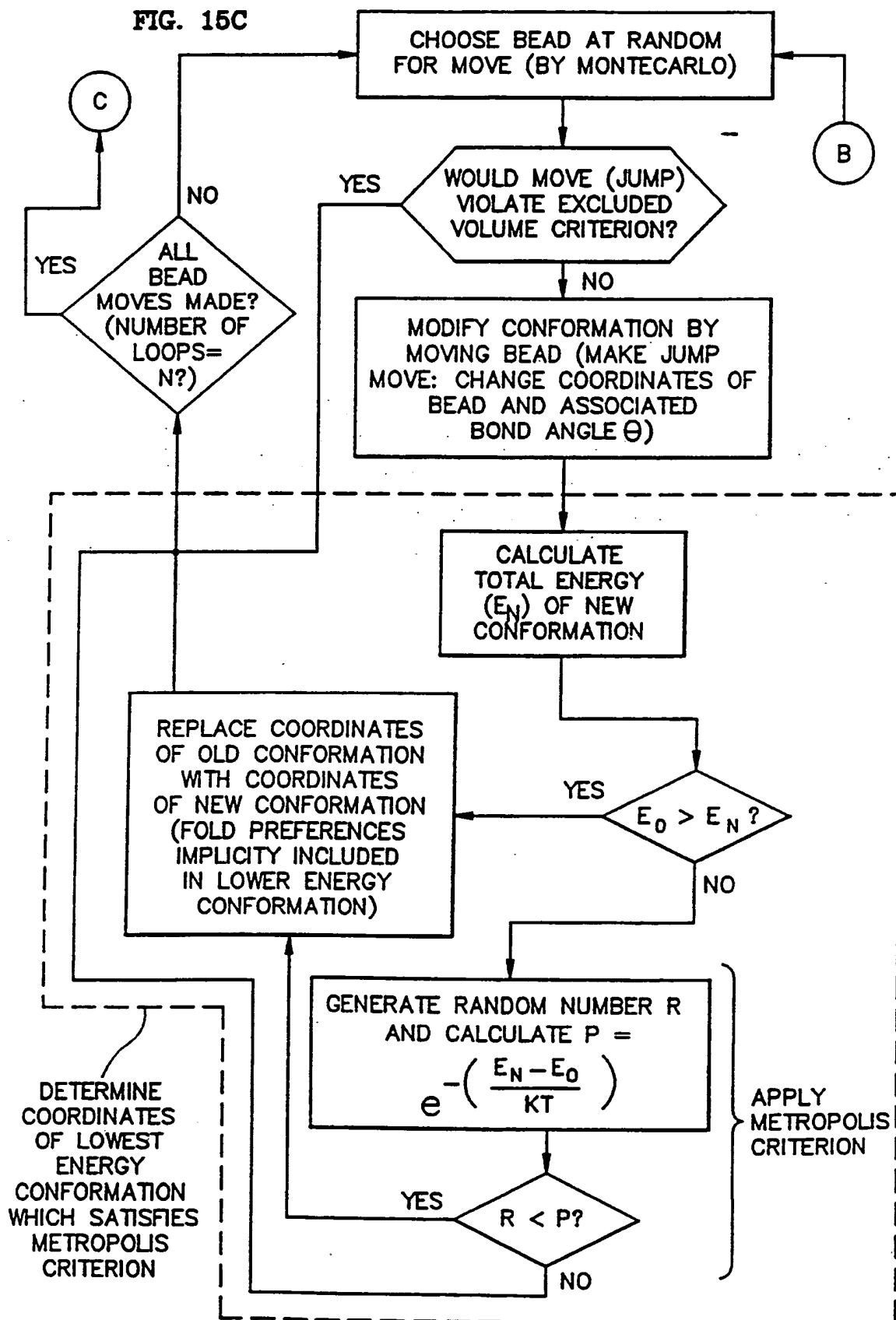
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FIG. 15B



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FIG. 15C



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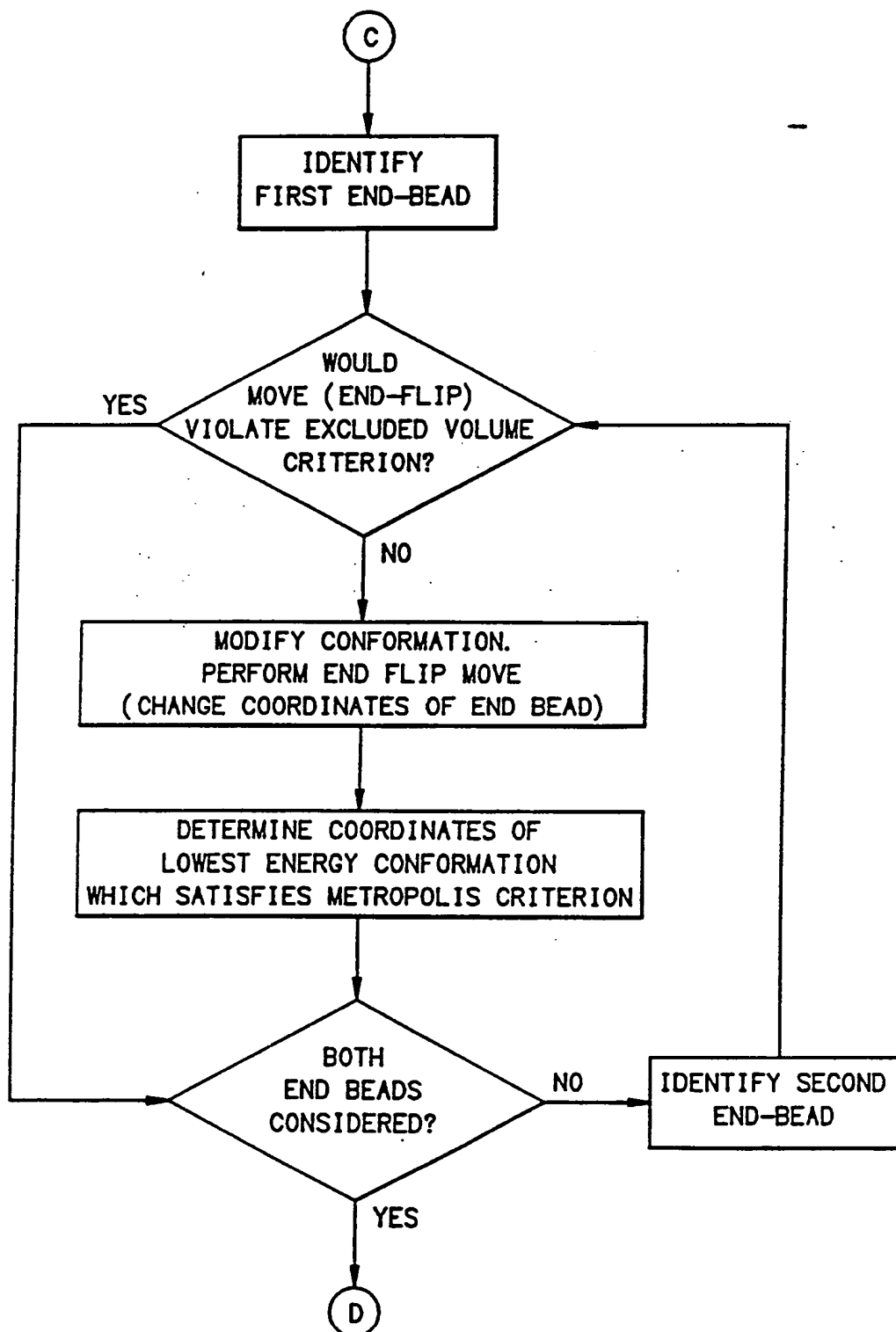
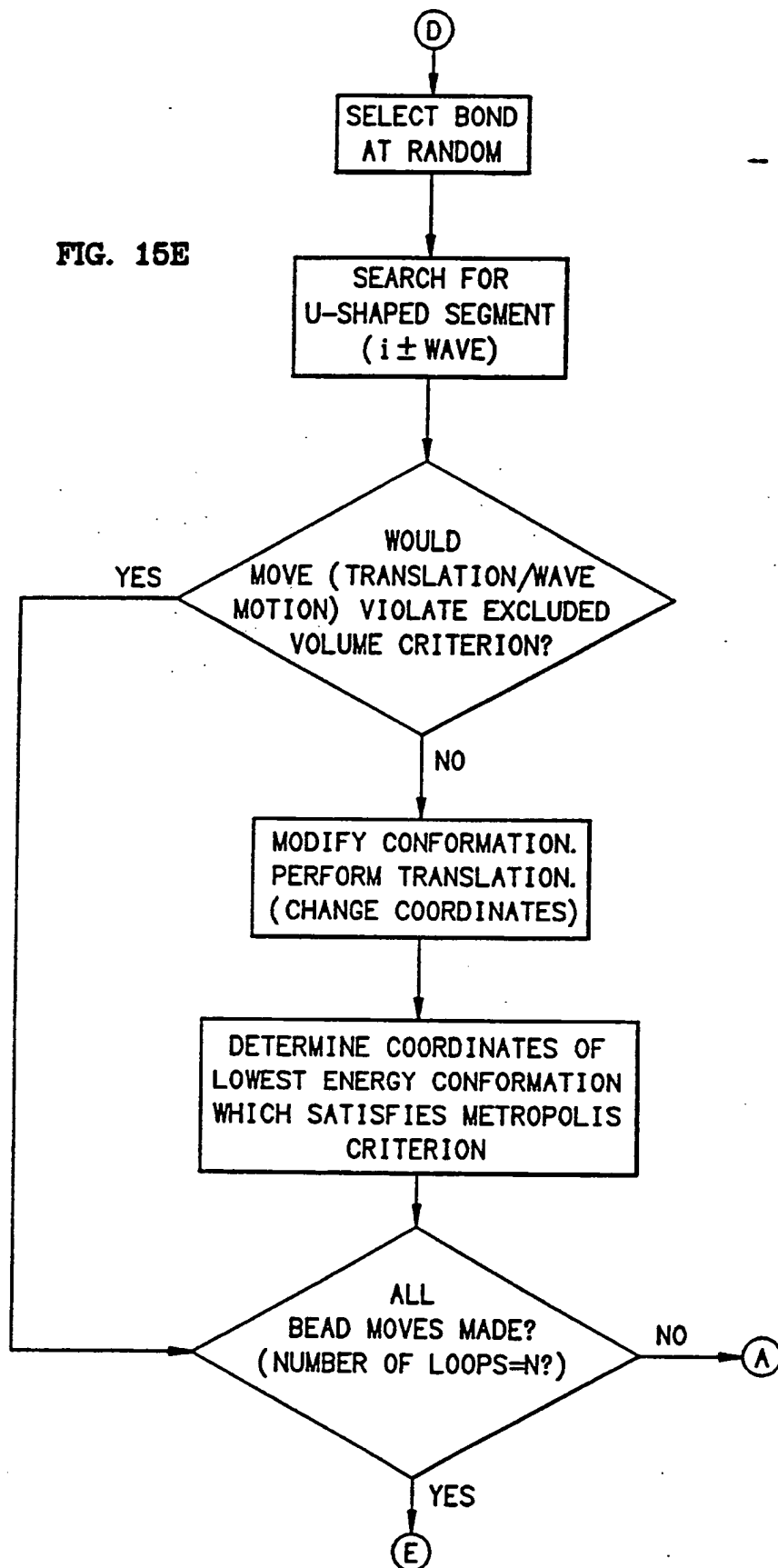


FIG. 15D

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FIG. 15E



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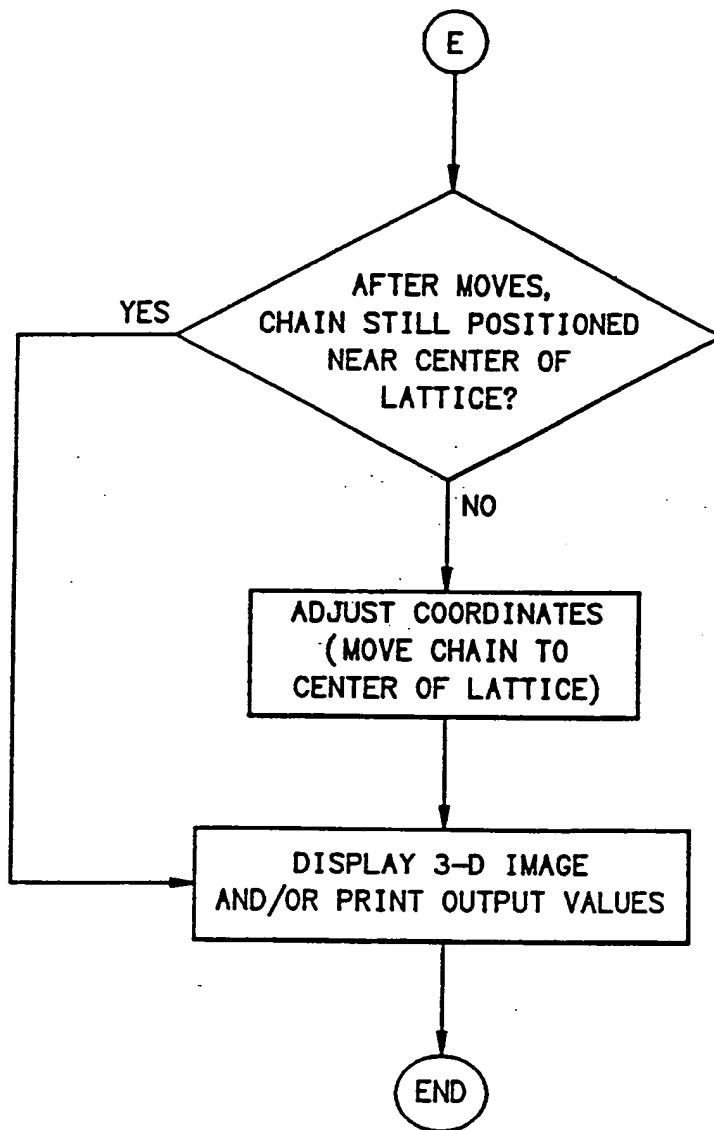


FIG. 15F

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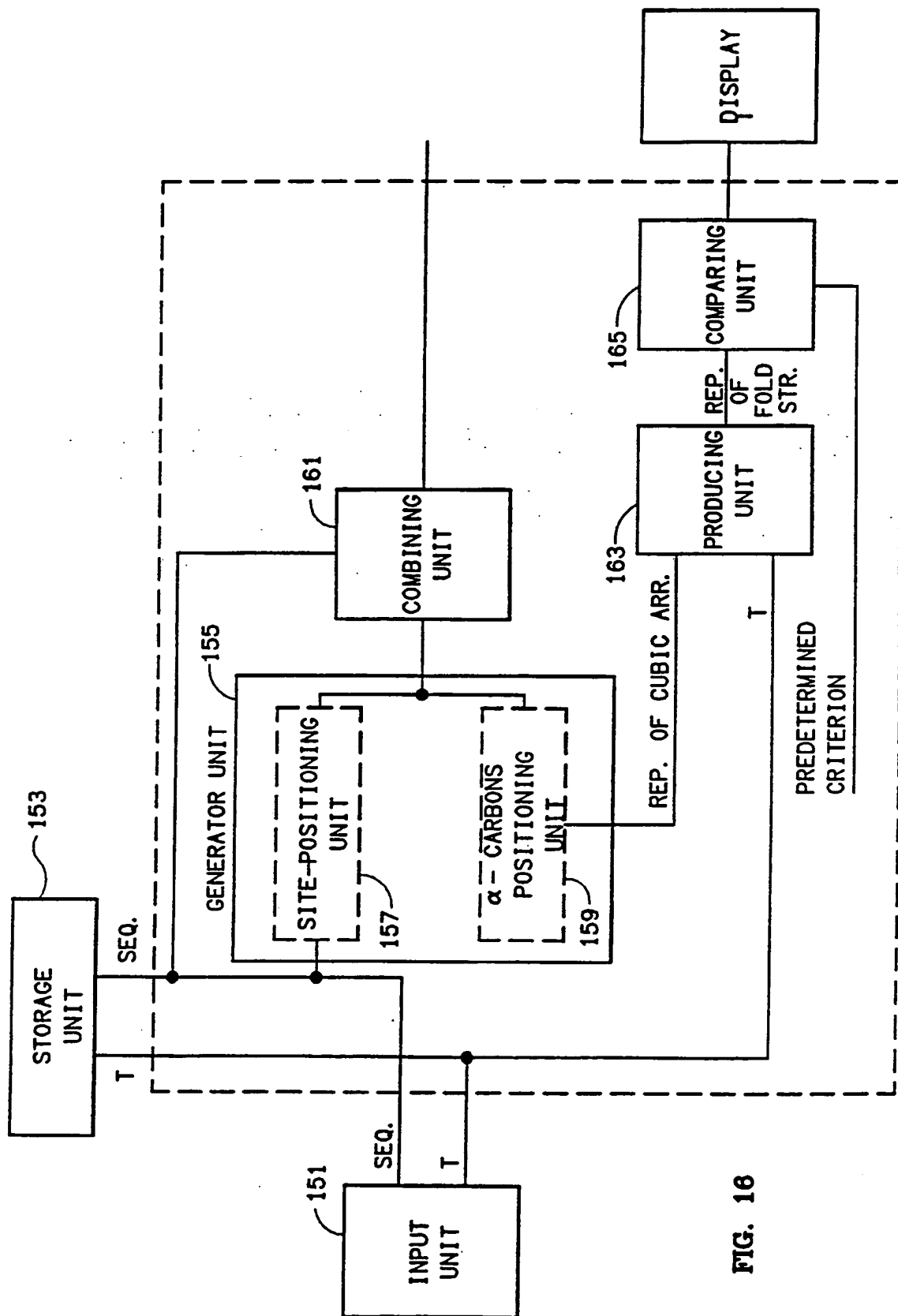
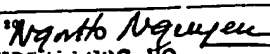


FIG. 16

INTERNATIONAL SEARCH REPORT

International Application No PCT/US91/02786

I. CLASSIFICATION & SUBJECT MATTER (if several classification symbols apply, indicate all) ¹		
According to International Patent Classification (IPC) or to both National Classification and IPC		
IPC(5): G06F 15/46 USCT: 364/496		
II. FIELDS SEARCHED		
Minimum Documentation Searched ²		
Classification System	Classification Symbols	
US CL 364/496, 497, 498, 578, 579, 200; 436/86, 89		
Documentation Searched other than Minimum Documentation to the extent that such Documents are included in the Fields Searched ³		
III. DOCUMENTS CONSIDERED TO BE RELEVANT ^{1,4}		
Category ⁵	Citation of Document, ^{1,6} with indication, where appropriate, of the relevant passages ^{1,7}	Relevant to Claim No. ^{1,8}
A	US, A, 4,704,692 (LADNER) 03 NOVEMBER 1987	
A	US, A, 4,853,871 (PANTOLIANO) 01 AUGUST 1989	
A	US, A, 4,881,175 (LADNER) 14 NOVEMBER 1989	
A	US, A, 4,908,773 (PANTOLIANO ET AL) 13 MARCH 1990	
A,P	US, A, 4,939,666 (HARDMAN) 03 JULY 1990	
A,P	US, A, 4,985,827 (HAMANAKA ET AL) 15 JANUARY 1991	
<div style="display: flex; justify-content: space-between;"> <div style="width: 45%;"> <p>[*] Special categories of cited documents: ^{1,9}</p> <p>"A" document defining the general state of the art which is not considered to be of particular relevance</p> <p>"E" earlier document but published on or after the international filing date</p> <p>"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)</p> <p>"O" document referring to an oral disclosure, use, exhibition or other means</p> <p>"P" document published prior to the international filing date but later than the priority date claimed</p> </div> <div style="width: 45%;"> <p>"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention</p> <p>"X" document of particular relevance: the claimed invention cannot be considered novel or cannot be considered to involve an inventive step</p> <p>"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art.</p> <p>"&" document member of the same patent family</p> </div> </div>		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search ¹		Date of Mailing of this International Search Report ¹
16 JULY 1991		16 AUG 1991
International Searching Authority ¹		Signature of Authorized Officer ^{1,10}
ISA/US		 for KEVIN J. TESKA NGUYEN INTERNATIONAL DIVISION

FURTHER INFORMATION CONTINUED FROM THE SECOND SHEET

V. ☒ OBSERVATIONS WHERE CERTAIN CLAIMS WERE FOUND UNSEARCHABLE¹

This international search report has not been established in respect of certain claims under Article 17(2) (a) for the following reasons:

1. ☒ Claim numbers 1-15, because they relate to subject matter not required to be searched by this Authority, namely:
- 1) Claims 1-9 & 13-15 relate to "scientific & mathematical theories" (See PCT Rule 39.1(i)).
 - 2) Claims 10-12 relate to "computer programs" (See PCT Rule 39.1(vi)).

2. ☐ Claim numbers _____, because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out¹, specifically:

3. ☐ Claim numbers _____, because they are dependent claims not drafted in accordance with the second and third sentences of PCT Rule 6.4(a).

VI. ☐ OBSERVATIONS WHERE UNITY OF INVENTION IS LACKING²

This International Searching Authority found multiple inventions in this international application as follows:

1. ☐ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims of the international application.
2. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims of the international application for which fees were paid, specifically claims: _____
3. ☐ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claim numbers: _____
4. ☐ As all searchable claims could be searched without effort justifying an additional fee, the International Searching Authority invites payment of any additional fee.

Remark on Protest

- ☐ The additional search fees were accompanied by applicant's protest.
- ☐ No protest accompanied the payment of additional search fees.

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